

Asgn 2.

Question 1

Equation of motion gives:

$$(a) \quad \frac{\partial \tau_{yx}}{\partial y} = 0 \rightarrow \tau_{yx} = C_1$$

$$\rightarrow -\mu \frac{dv_x}{dy} = C_1 \rightarrow \frac{dv_x}{dy} = -\frac{C_1}{\mu}$$

$$\rightarrow v_x = -\frac{C_1}{\mu} y + C_2$$

$$BC1) \text{ At } y=0 \quad v_x = 0.333 \text{ m/s} \quad \therefore C_2 = 0.333 \text{ (m/s)}$$

$$BC2) \text{ At } y=0.02 \quad v_x = -0.666 \text{ m/s} \quad (\mu = 0.25 \text{ Pa}\cdot\text{s})$$

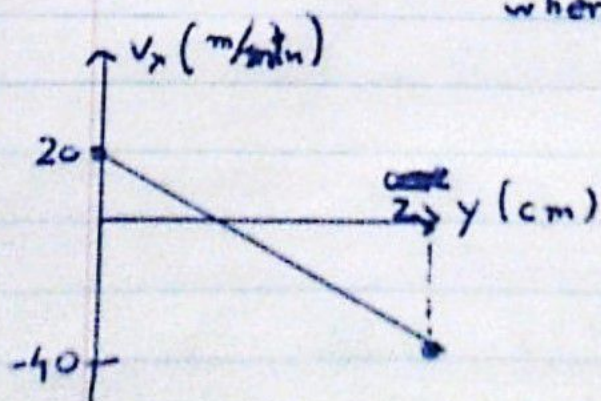
$$-0.666 = -\frac{C_1(0.02)}{0.25} + 0.333 \rightarrow C_1 = 12.5 \text{ Pa}$$

$$\tau_{yx} = 12.5 \text{ Pa}$$

$$(b) \text{ From (a): } v_x = -\frac{12.5}{0.25} y + 0.333$$

$$\rightarrow v_x = -50y + 0.333$$

where v_x in m/s, y in m



$$v_x = 0 \text{ at:}$$

$$-50y + 0.333 = 0$$

$$\rightarrow y = 0.00666 \text{ m} \\ = 0.666 \text{ cm}$$

Question 2.

(a) Navier - Stokes eqn simplifies to:

$$0 = -\frac{dP}{dz} + \mu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_z}{\partial r} \right) \right]$$

$$\rightarrow \frac{\partial}{\partial r} \left(r \frac{\partial v_z}{\partial r} \right) = \frac{1}{\mu} \frac{dP}{dz} r$$

$$\text{Take } \frac{1}{\mu} \frac{dP}{dz} = \alpha$$

$$\text{Then: } \frac{\partial}{\partial r} \left(r \frac{\partial v_z}{\partial r} \right) = \alpha r$$

$$\rightarrow r \frac{\partial v_z}{\partial r} = \frac{\alpha r^2}{2} + C_1$$

$$\rightarrow \frac{\partial v_z}{\partial r} = \frac{\alpha}{2} r + \frac{C_1}{r}$$

$$\rightarrow v_z = \frac{\alpha r^2}{4} + C_1 \ln r + C_2$$

B.C.1) At $r = R_1$, $v_z = 0$:

$$0 = \frac{\alpha R_1^2}{4} + C_1 \ln R_1 + C_2 \quad (1)$$

B.C.2) At $r = R_2$, $v_z = 0$:

$$0 = \frac{\alpha R_2^2}{4} + C_1 \ln R_2 + C_2 \quad (2)$$

$$(1) - (2) : 0 = \frac{\alpha}{4} (R_1^2 - R_2^2) + C_1 \ln \left(\frac{R_1}{R_2} \right)$$

$$\rightarrow C_1 = \frac{\frac{\alpha}{4} (R_1^2 - R_2^2)}{\ln \left(\frac{R_2}{R_1} \right)}$$

$$(1) \rightarrow C_2 = -\frac{\alpha}{4} R_1^2 - C_1 \ln R_1$$

$$\rightarrow C_2 = -\frac{\alpha}{4} R_1^2 - \frac{\alpha (R_1^2 - R_2^2)}{\ln(R_2/R_1)} \ln R_1$$

Thus:

$$V_z = \frac{\alpha}{4} r^2 + C_1 \ln r + C_2$$

$$V_z = \frac{\alpha}{4} r^2 + \frac{\alpha (R_1^2 - R_2^2)}{\ln(R_2/R_1)} \ln r$$

$$- \frac{\alpha}{4} R_1^2 - \frac{\alpha (R_1^2 - R_2^2)}{\ln(R_2/R_1)} \ln R_1$$

$$V_z = \frac{\alpha}{4} \left[r^2 - R_1^2 + \frac{R_1^2 - R_2^2}{\ln(R_2/R_1)} \ln(r/R_1) \right]$$

$$\left(\alpha = \frac{1}{r} \frac{dP}{dz} \right)$$

$$(b) \tau_{rz} = -\mu \frac{\partial V_z}{\partial r}$$

$$\tau_{rz} = -\mu \left[\frac{\alpha}{4} (2r) + \frac{\alpha (R_1^2 - R_2^2)}{\ln(R_2/R_1)} \frac{1}{r} \right]$$

$$\tau_{rz} = -\mu \frac{\alpha}{2} \left[r + \frac{(R_1^2 - R_2^2)}{2 \ln(R_2/R_1)} \left(\frac{1}{r} \right) \right]$$

$$\tau_{rz} = - \underbrace{\frac{\partial P}{\partial z}}_{\text{constant}} \frac{1}{2} \left[r + \frac{(R_1^2 - R_2^2)}{2 \ln(R_2/R_1)} \left(\frac{1}{r} \right) \right]$$

$$(c) \quad V_z = V_{\max} \quad \text{where} \quad \frac{\partial V_z}{\partial r} = 0$$

$$\rightarrow r + \frac{(R_1^2 - R_2^2)}{2 \ln(R_2/R_1)} \cdot \frac{1}{r} = 0$$

$$\rightarrow r^2 = \frac{R_2^2 - R_1^2}{2 \ln(R_2/R_1)}$$

$$\rightarrow r = \sqrt{\frac{(R_2^2 - R_1^2)}{2 \ln(R_2/R_1)}} \quad (\text{ans to (e)})$$

and therefore :

$$V_{\max} = \frac{a}{4} \left[\frac{(R_2^2 - R_1^2)}{2 \ln(R_2/R_1)} - R_1^2 + \frac{(R_1^2 - R_2^2)}{\ln(R_2/R_1)} \ln \left(\frac{\sqrt{\frac{R_2^2 - R_1^2}{2 \ln(R_2/R_1)}}}{R_1} \right) \right]$$

$V_z = 0$ (minimum) at ~~to~~ $r = R_1$ and $r = R_2$

$$(d) \quad Q = 2\pi \int_{R_1}^{R_2} v_z r \, dr$$

$$= 2\pi \int_{R_1}^{R_2} \frac{\alpha}{4} \left[r^2 - R_1^2 + \frac{(R_1^2 - R_2^2)}{\ln(R_2/R_1)} \ln(r/R_1) \right] r \, dr$$

$$= \frac{\pi\alpha}{2} \int_{R_1}^{R_2} \left(r^3 - R_1^2 r + \frac{R_1^2 - R_2^2}{\ln(R_2/R_1)} r \ln(r/R_1) \right) dr$$

~~$$= \frac{\pi\alpha}{2} \left[\frac{r^4}{4} - \frac{R_1^2 r^2}{2} + \frac{(R_1^2 - R_2^2)}{\ln(R_2/R_1)} \right]$$~~

{ Note: $\int_{R_1}^{R_2} r \ln(r/R_1) \, dr = \int_{R_1}^{R_2} (r \ln r - r \ln R_1) \, dr$

$$= \left[\frac{1}{2} r^2 \ln r - \frac{1}{4} r^2 - \frac{\ln R_1}{2} r^2 \right]_{R_1}^{R_2}$$

$$= \frac{1}{2} R_2^2 \ln R_2 - \frac{1}{2} R_1^2 \ln R_1 - \frac{1}{4} (R_2^2 - R_1^2)$$

$$= \frac{1}{2} R_2^2 \ln R_2 - \frac{1}{2} R_1^2 \ln R_1 - \frac{(2 \ln R_1 + 1)(R_2^2 - R_1^2)}{4}$$

$$Q = \frac{\pi\alpha}{2} \left[\frac{R_2^4 - R_1^4}{4} + \frac{R_1^2}{2} (R_2^2 - R_1^2) \right.$$

$$\left. + \left(\frac{R_1^2 - R_2^2}{\ln(R_2/R_1)} \right) \left\{ \frac{1}{2} R_2^2 \ln R_2 - \frac{1}{2} R_1^2 \ln R_1 - \frac{(1 + 2 \ln R_1)(R_2^2 - R_1^2)}{4} \right\} \right]$$

(can simplify more)

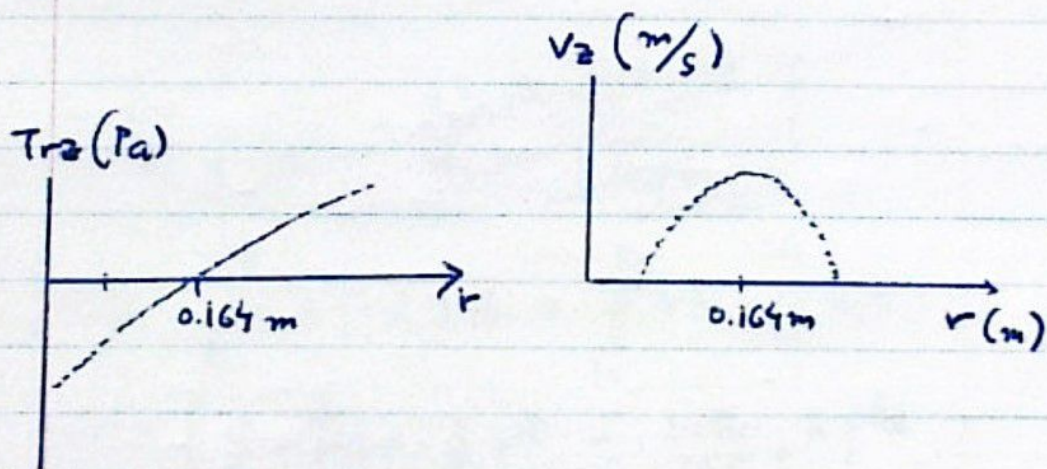
For part (f) use excel with found equations for

$$R_1 = 0.13 \text{ m}$$

$$R_2 = 0.2 \text{ m}$$

$$\mu = 0.001 \text{ Pa}\cdot\text{s}$$

$$\frac{dP}{dz} = -20000 \text{ Pa/m}$$



R1 (cm)	13
R1 (m)	0.13
R2 (cm)	20
R2 (m)	0.2
μ (cP)	1
μ (Pa.s)	0.001
dP/dz (kPa/m)	-20
dP/dz (Pa/m)	-20000
r max (m)	0.1637426
Vmax (m/s)	12312.695
α (1/m/s)	-2.0E+07

r (m)	Vz (m/s)	dVz/dr (1/s)	τ_{rz} (Pa)
0.13	0	762434.5	-762.434
0.1335	2511.808	673363.2	-673.363
0.137	4716.764	587054.6	-587.055
0.1405	6624.172	503302.4	-503.302
0.144	8242.645	421920	-421.92
0.1475	9580.179	342738.9	-342.739
0.151	10644.21	265605.8	-265.606
0.1545	11441.65	190381.8	-190.382
0.158	11978.96	116939.8	-116.94
0.1615	12262.17	45163.98	-45.164
0.165	12296.92	-25051.6	25.05162
0.1685	12088.51	-93804.3	93.80426
0.172	11641.9	-161183	161.1832
0.1755	10961.74	-227271	227.2708
0.179	10052.42	-292143	292.1426
0.1825	8918.076	-355869	355.8686
0.186	7562.601	-418514	418.5135
0.1895	5989.673	-480137	480.1373
0.193	4202.766	-540795	540.7954
0.1965	2205.171	-600540	600.5395
0.2	0	-659418	659.4176

