

$$\vec{F}_{12} = k_e \frac{q_1 q_2}{r^2} \hat{r}_{12} \quad \vec{E} = \frac{\vec{F}_e}{q_o} = k_e \frac{q}{r^2} \hat{r}; \quad \vec{E} = k_e \sum_i \frac{q_i}{r_i^2} \hat{r}_i$$

$$\vec{E} = k_e \lim_{\Delta q_i \rightarrow 0} \sum_i \frac{\Delta q_i}{r_i^2} \hat{r}_i = k_e \int \frac{dq}{r^2} \hat{r}; \quad \vec{a} = \frac{q\vec{E}}{m}$$

$$\Phi_E \equiv \int_{\text{surface}} \vec{E} \cdot d\vec{A}; \quad \Phi_E = \oint \vec{E} \cdot d\vec{A} = \frac{q_{\text{in}}}{\epsilon_0}; \quad E = \frac{\sigma}{2\epsilon_0}; \quad E = \frac{\sigma}{\epsilon_0}$$

$$C = \frac{Q}{V}; \quad C = \frac{\epsilon_0 A}{d}; \quad C = \frac{ab}{k_e(b-a)}; \quad C = \frac{\ell}{2k_e \ln(b/a)}$$

$$C_{\text{eq}} = C_1 + C_2 + C_3 + \dots \quad (\text{parallel combination})$$

$$\frac{1}{C_{\text{eq}}} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3} + \dots \quad (\text{series combination})$$

$$U = \frac{Q^2}{2C} = \frac{1}{2} Q \Delta V = \frac{1}{2} C (\Delta V)^2; \quad \sigma_p = \sigma \left(1 - \frac{1}{\kappa}\right)$$

$$I \equiv \frac{dQ}{dt}; \quad I_{\text{avg}} = \frac{\Delta Q}{\Delta t} = nqv_d A; \quad J \equiv \frac{I}{A} = nqv_d$$

$$J = \sigma E; \quad R \equiv \frac{\Delta V}{I}; \quad R = \rho \frac{\ell}{A}; \quad J = nqv_d = \frac{nq^2 E}{m_e} \tau$$

$$\rho = \rho_0 [1 + \alpha(T - T_0)]; \quad \rho = \frac{1}{\sigma}; \quad \wp = I \Delta V$$

$$\wp = I^2 R = \frac{(\Delta V)^2}{R}; \quad \sum_{\text{junction}} I = 0; \quad \sum_{\text{loop}} \Delta V = 0$$

$$\tau = RC; \quad q(t) = C \mathcal{E} (1 - e^{-t/RC}) = Q(1 - e^{-t/RC}); \quad q(t) = Q e^{-t/RC};$$

$$U = \frac{1}{2} Q \mathcal{E} = \frac{1}{2} C \mathcal{E}^2 \quad \Delta U = -q_0 \int_A^B \vec{E} \cdot d\vec{s}; \quad V = \frac{U}{q_0}; \quad \Delta U = q \Delta V$$

$$dV = k_e \frac{dq}{r}; \quad \Delta V = -E \int_A^B ds = -Ed$$

$$\Delta V = - \int_A^B \vec{E} \cdot d\vec{s} = -\vec{E} \cdot \int_A^B d\vec{s} = -\vec{E} \cdot \vec{s}; \quad \Delta K + \Delta U = 0$$

$$U = k_e \frac{q_1 q_2}{r_{12}}; \quad V = k_e \frac{q}{r}; \quad E_x = -\frac{dV}{dx}; \quad E_r = -\frac{dV}{dr}$$

$$E_x = -\frac{\partial V}{\partial x} \quad E_y = -\frac{\partial V}{\partial y} \quad E_z = -\frac{\partial V}{\partial z}$$

$$\vec{F}_B = q\vec{v} \times \vec{B}; \quad \vec{F} = q\vec{E} + q\vec{v} \times \vec{B}; \quad F_B = |q| v B \sin \theta$$

$$K = \frac{1}{2} mv^2 = \frac{q^2 B^2 R^2}{2m}; \quad d\vec{B} = \frac{\mu_0}{4\pi} \frac{I d\vec{s} \times \hat{r}}{r^2}; \quad B = \frac{\mu_0 I}{2\pi a}$$

$$B = \frac{\mu_0 I}{4\pi a} (\sin \theta_1 - \sin \theta_2); \quad B = \frac{\mu_0 I}{4\pi a} \theta; \quad B_x = \frac{\mu_0 I a^2}{2(a^2 + x^2)^{3/2}}$$

$$\frac{F_B}{\ell} = \frac{\mu_0 I_1 I_2}{2\pi a}; \quad \oint \vec{B} \cdot d\vec{s} = \mu_0 I; \quad B = \left(\frac{\mu_0 I}{2\pi R^2}\right) r \quad (\text{for } r < R)$$

$$B = \frac{\mu_0 N I}{2\pi r}; \quad B = \mu_0 \frac{N}{\ell} I = \mu_0 n I; \quad \mu = \left(\frac{e}{2m_e}\right) L; \quad \mu_{\text{spin}} = \frac{e\hbar}{2m_e}$$

$$\mu_B = \frac{e\hbar}{2m_e} = 9.27 \times 10^{-24} \text{ J/T};$$

$$\vec{F}_B = I\vec{L} \times \vec{B}; \quad d\vec{F}_B = I d\vec{s} \times \vec{B}; \quad \vec{\tau} = I\vec{A} \times \vec{B};$$

$$\vec{\tau} = \vec{\mu} \times \vec{B};$$

$$\Delta V_H = E_H d = v_d B d; \quad \Delta V_H = \frac{IB}{nqt} = \frac{R_H I B}{t}$$

$$U_E = (\epsilon_0 E^2)/2; \quad C = \kappa C_0; \quad \tau = \rho \times E; \quad U = \rho \cdot E; \quad E = E_0 / \kappa$$

$$\epsilon = -N \frac{d\Phi_B}{dt}; \quad \Delta V = E \ell = B \ell v; \quad \epsilon = -B \ell v \oint \vec{E} \cdot d\vec{s} = -\frac{d\Phi_B}{dt}$$

$$\epsilon_L = -L \frac{dI}{dt}; \quad L = \frac{N\Phi_B}{I}; \quad L = -\frac{\epsilon_L}{dI/dt}; \quad L = \frac{N\Phi_B}{I} = \mu_0 \frac{N^2}{\ell}; \quad L = \mu \ell \ln(b/a)/2\pi$$

$$L = \mu_0 \frac{(n\ell)^2}{\ell} A = \mu_0 n^2 A \ell = \mu_0 n^2 V; \quad I = \frac{\epsilon}{R} (1 - e^{-t/\tau}); \quad \tau = \frac{L}{R}$$

$$I = \frac{\epsilon}{R} e^{-t/\tau} = I_i e^{-t/\tau}; \quad U = \frac{1}{2} LI^2; \quad u_B = \frac{U}{V} = \frac{B^2}{2\mu_0}; \quad M_{12} = \frac{N_2 \Phi_{12}}{I_1}$$

$$\epsilon_1 = -M_{21} \frac{dI_2}{dt} \quad U = U_C + U_L = \frac{Q^2}{2C} + \frac{1}{2} LI^2$$

$$\omega = \frac{1}{\sqrt{LC}}; \quad Q = Q_{\text{max}} e^{(-\frac{Rt}{2L})} \cos(\omega_d t); \quad \omega_d = \left[\frac{1}{LC} - \left(\frac{R}{2L}\right)^2\right]^{1/2}$$

$$i_c = \omega C \Delta V_{\text{max}} \sin\left(\omega t + \frac{\pi}{2}\right); \quad q = C \Delta V_{\text{max}} \sin(\omega t); \quad X_C \equiv 1/\omega C;$$

$$\Delta v_C = I_{\text{max}} X_C \sin\left(\omega t - \frac{\pi}{2}\right) = -\Delta V_C \cos(\omega t); \quad I_{\text{max}} = \frac{\Delta V_{\text{max}}}{X_C}$$

$$\Delta v_R = I_{\text{max}} R \sin(\omega t) = \Delta V_R \sin(\omega t); \quad I_{\text{max}} = \frac{\Delta V_{\text{max}}}{Z}$$

$$\Delta v_L = I_{\text{max}} X_L \sin\left(\omega t + \frac{\pi}{2}\right) = \Delta V_L \cos(\omega t); \quad X_L \equiv \omega L; \quad R = Z \cdot \cos(\theta)$$

$$I_{\text{max}} = \frac{\Delta V_{\text{max}}}{\sqrt{R^2 + (X_L - X_C)^2}}; \quad R_{\text{eq}} = \left(\frac{N_1}{N_2}\right)^2 R_L; \quad \wp_{\text{avg}} = \frac{1}{2} I_{\text{max}} \Delta V_{\text{max}} \cos(\theta)$$

$$\Delta v_2 = \frac{N_2}{N_1} \Delta v_1; \quad I_1 \Delta V_1 = I_2 \Delta V_2; \quad I_d = \epsilon_0 \frac{d\Phi_E}{dt}; \quad c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}; \quad c = \frac{E}{B}$$

$$\frac{\partial^2 E}{\partial x^2} = \mu_0 \epsilon_0 \frac{\partial^2 E}{\partial t^2}; \quad \frac{\partial B}{\partial x} = -\mu_0 \epsilon_0 \frac{\partial E}{\partial t}; \quad \frac{\partial E}{\partial x} = -\frac{\partial B}{\partial t}; \quad \vec{S} \equiv \frac{1}{\mu_0} \vec{E} \times \vec{B}$$

$$E = E_{\text{max}} \cos(kx - \omega t); \quad B = B_{\text{max}} \cos(kx - \omega t); \quad k = 2\pi/\lambda; \quad \omega = 2\pi f$$

$$\lambda = c T = \frac{c}{f}; \quad u_B = u_E = \frac{1}{2} \epsilon_0 E^2 = \frac{B^2}{2\mu_0}; \quad I = S_{\text{avg}} = \frac{E_{\text{max}} B_{\text{max}}}{2\mu_0} = \frac{E_{\text{max}}^2}{2\mu_0 c} = \frac{c B_{\text{max}}^2}{2\mu_0}$$

$$P = \frac{F}{A} = \frac{1}{A} \frac{dp}{dt} = \frac{1}{c} \left(\frac{dTEB}{dt}\right) = (1+f) \frac{S}{c}; \quad f \text{ is the fraction of the reflected light}$$

$$m_\alpha = 6.644657 \times 10^{-27} \text{ kg} = 4.00151 \text{ u} = 3727.409 \frac{\text{MeV}}{c^2}$$

$$e = 1.6 \times 10^{-19} \text{ C}; \quad N = 6.02 \times 10^{23} \text{ particles/mole}$$

$$c = 3.00 \times 10^8 \frac{\text{m}}{\text{s}}; \quad k_e = 8.9876 \times 10^9 \text{ N m}^2/\text{C}^2; \quad k_e = 1/(4\pi\epsilon_0)$$

$$\epsilon_0 = 8.8542 \times 10^{-12} \frac{\text{C}^2}{\text{N.m}^2}; \quad \mu_0 = 4\pi \times 10^{-7} \frac{\text{T.m}}{\text{A}}; \quad 1T = 10^4 \text{ G}$$

$$1 \text{ u} = 931.502 \text{ MeV}/c^2$$

$$1 \text{ eV} = 1.602 \times 10^{-19} \text{ J}$$

$$m_p = 1.672 \times 10^{-27} \text{ kg}$$

$$= 1.0073 \text{ u} = 938.280 \text{ MeV}/c^2$$

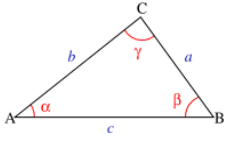
$$m_n = 1.674 \times 10^{-27} \text{ kg}$$

$$= 1.0087 \text{ u} = 939.57 \text{ MeV}/c^2$$

$$m_e = 9.11 \times 10^{-31} \text{ kg}$$

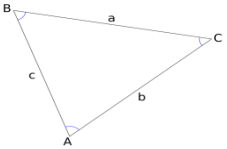
$$= 5.486 \times 10^{-4} \text{ u} = 0.511 \text{ MeV}/c^2$$

Law of cosines



$$c^2 = a^2 + b^2 - 2ab \cos(\gamma)$$

Law of sines



$$\frac{\sin A}{a} = \frac{\sin B}{b} = \frac{\sin C}{c}$$

Quadratics:

$$ax^2 + bx + c = 0$$

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

Trigonometric Identities:

$$\cos^2 \theta + \sin^2 \theta = 1$$

$$\sin(a \pm b) = \sin a \cos b \pm \cos a \sin b$$

$$\cos(a \pm b) = \cos a \cos b \mp \sin a \sin b$$

$$\tan(a \pm b) = \frac{\tan a \pm \tan b}{1 \mp \tan a \tan b}$$

$$V = \frac{4}{3}\pi r^3 ; A = 4\pi r^2 ; A = \pi r^2 ;$$

$$(x - y)(x + y) = x^2 - y^2$$

$$v_f = v_i + a \Delta t$$

$$x_f = x_i + v_i \Delta t + \frac{1}{2} a \Delta t^2$$

$$v_f^2 = v_i^2 + 2 a \Delta x$$

$$x_f = x_i + \frac{1}{2}(v_f + v_i) \Delta t$$

$$\omega_f = \omega_i + \alpha \Delta t$$

$$\theta_f = \theta_i + \omega_i \Delta t + \frac{1}{2} \alpha \Delta t^2$$

$$\omega_f^2 = \omega_i^2 + 2 \alpha \Delta \theta$$

$$\theta_f = \theta_i + \frac{1}{2}(\omega_f + \omega_i) \Delta t$$