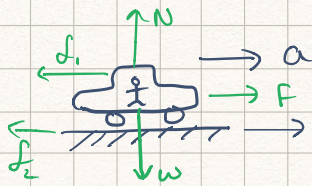


Momentum Equation  $\Rightarrow \vec{B} = \vec{m}$

$$\vec{m} = m\vec{v}$$



$$\begin{aligned} \Sigma \vec{F}_{\text{ext}} &= m\vec{a} = m\left(\frac{d\vec{v}}{dt}\right) = \frac{dm\vec{v}}{dt} = \frac{d\vec{m}}{dt} \\ (\Sigma F_{\text{ext}} = ma)_x \\ \Sigma \vec{F}_{\text{ext}} &= \frac{d\vec{m}}{dt} \end{aligned}$$

Continuity Equation  $\Rightarrow$

$$\frac{d\vec{m}_{\text{CVS}}}{dt} = \frac{dm_{\text{CV}}}{dt} + (\dot{m}_{\text{out}} - \dot{m}_{\text{in}})$$

$$\frac{d\vec{m}}{dt} = \Sigma \vec{F}_{\text{ext}} = \frac{d(m\vec{v})_{\text{CV}}}{dt} + \rho Q (V_{\text{out}} - V_{\text{in}})$$

Steady State:

$$Q = \text{Constant}$$

$$VA = \text{Constant}$$

$$\frac{dv}{dt} = 0$$

$$\therefore \frac{d\vec{m}}{dt} = \frac{dm\vec{v}}{dt}$$

$$(m\vec{v}) = m\vec{v}$$

$$\Sigma \vec{F}_{\text{ext}} = \rho Q (V_{\text{out}} - V_{\text{in}})$$

Momentum Eq

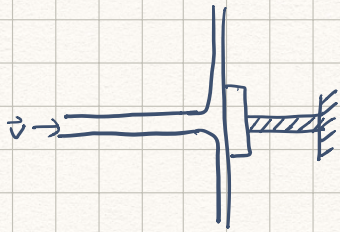
Continuity Eq

Bernoullies Eq

Equilibrium Eq

+ Eulers Equation

# I Vane

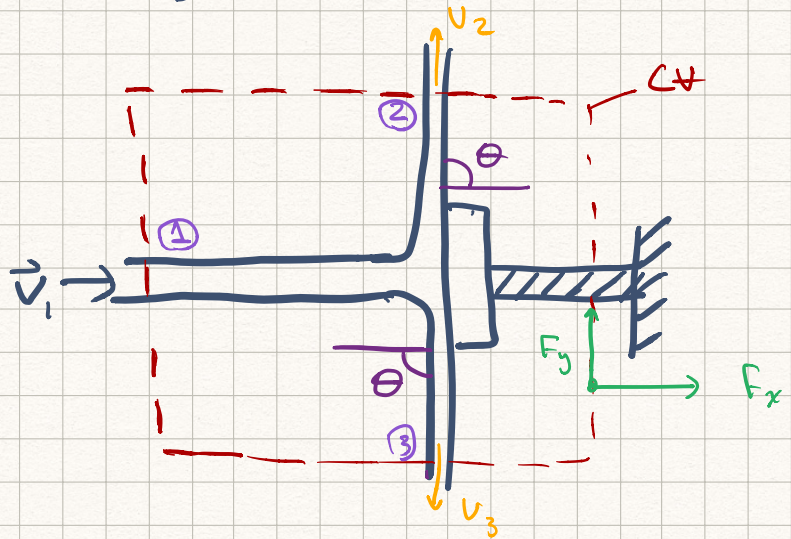


How to solve:

1 - CV

2 - FD

3 -  $\rho Q (V_{out} - V_{in})$



## ① Bernoulli Equation

$$\frac{\cancel{P}}{\cancel{\rho}} + \frac{V_1^2}{2g} + \cancel{z_1} = \frac{\cancel{P}}{\cancel{\rho}} + \frac{V_2^2}{2g} + \cancel{z_2}$$

\* in vane problems  
 $z_1 = z_2$

$$V_1 = V_2$$

∴ The same goes for ① and ③

$$\Rightarrow V_1 = V_3$$

$$\therefore \boxed{V_1 = V_2 = V_3 = V}$$

## ② Continuity Equation :

$$Q_1 = Q_2 + Q_3$$

$$\cancel{V_1} A_1 = \cancel{V_2} A_2 + \cancel{V_3} A_3$$

• from B.E.

$$\boxed{A_1 = A_2 + A_3}$$

$$\Rightarrow A_2 = A_3$$

\* symmetry

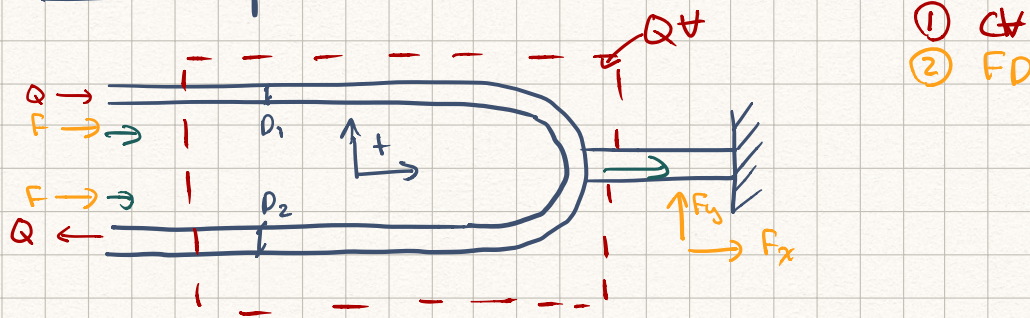
$$= \boxed{A_2 = A_3 = \frac{A_1}{2}}$$

### ③ Momentum Equation

$$F_x = \rho [Q_2 V_2 \cos \theta - Q_3 V_3 - Q_1 V_1]$$

$$F_y = \rho [Q_2 V_2 \sin \theta - Q_3 V_3 \sin \theta - 0]$$

## II Pipe



### Continuity Eq.

$$Q = vA$$

$$Q_1 = v_1 \frac{\pi D_1^2}{4}$$

$$Q_2 = v_2 \frac{\pi D_2^2}{4}$$

$$Q_1 = Q_2$$

### Momentum Eq.

$$\sum \vec{F}_{\text{ext}} = \rho Q (\vec{v}_{\text{out}} - \vec{v}_{\text{in}})$$

$$x \Rightarrow F_x + F_{p1} + F_{p2} = \rho [-Q_2 V_2 - v_1 Q_1]$$

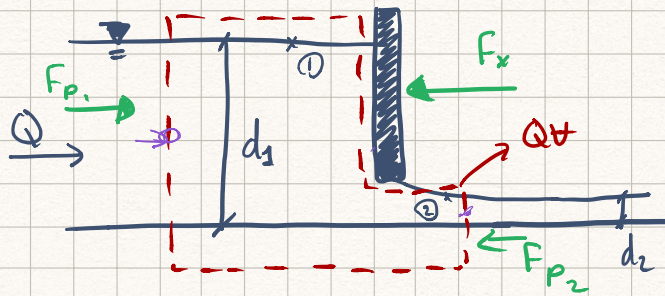
$$y \Rightarrow F_y = 0$$

### Force

$$F_p = PA$$

$$P = \frac{F}{A} \quad F = P \cdot A$$

### III GATES



① - QV  
② - FD

BE.

$$\frac{P_1}{\rho} + \frac{v_1^2}{2g} + z_1 = \frac{P_2}{\rho} + \frac{v_2^2}{2g} + z_2$$

$$d_1 - d_2 = \frac{v_2^2}{2g}$$

C.E.

$$Q_1 = Q_2$$

$$v_1 d_1 = v_2 d_2 \Rightarrow v_1 = \frac{v_2 d_2}{d_1}$$

ME

$$x \Rightarrow F_x + F_{p1} - F_{p2} = \rho Q [v_2 - v_1]$$

$$y \Rightarrow F_y = 0$$

$$F_{p1} = \bar{P}_c A$$

$$F_{p2} = \frac{1}{2} d_1 \gamma A_1$$

$$F_{p2} = \frac{1}{2} d_2 \gamma A_2$$