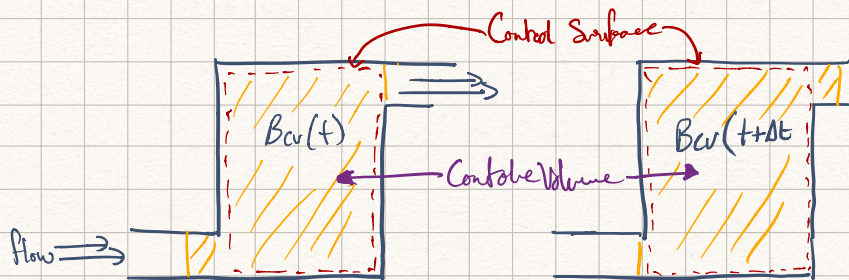


Control volume / Continuity

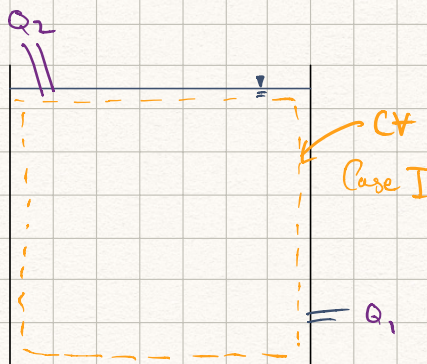
$$\frac{dB_{sys}}{dt} = \frac{dB_{cv}}{dt} + (B_{out} - B_{in})$$

$$\left[\begin{array}{l} \text{Rate of change of} \\ \text{Property B} \\ \text{of system} \end{array} \right] = \left[\begin{array}{l} \text{Rate at change of} \\ \text{Prop B in Control} \\ \text{Volume} \end{array} \right] + \left[\begin{array}{l} \text{net out flow of} \\ \text{Property B through} \\ \text{Control surface} \end{array} \right]$$

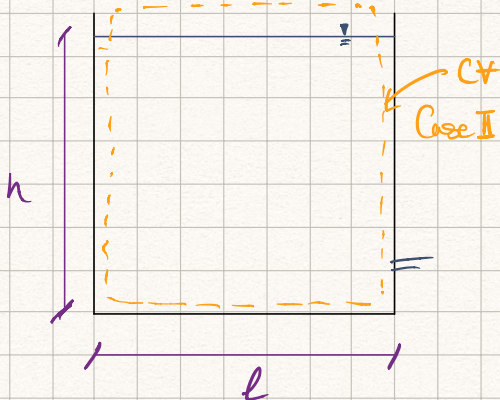


$$0 = \frac{dm_{cv}}{dt} + (\dot{m}_{out} - \dot{m}_{in}) \quad \dot{m} = \rho Q$$

$$\left[\frac{kg}{s} = \frac{kg}{m^3} \times \frac{m^3}{s} \right]$$



- ① CV ↙ chose CV
- ② Term By Term



② (Case I)

$$\frac{dm_{cv}}{dt} = 0$$

$$(\dot{m}_{out})_{cs} = (\rho Q_{out})_{cs} = \rho Q_1$$

$$(\dot{m}_{in})_{cs} = (\rho Q_{in})_{cs} = \rho Q_2$$

$$0 = 0 + (\rho Q_1 - \rho Q_2) \Rightarrow Q_1 = Q_2$$

② (Case II)

$$dM_{\text{ctrl}} \neq 0 \Rightarrow M_{\text{ctrl}} = \rho \forall = \rho(hl) 1$$

$$\frac{d}{dt} (M_{\text{ctrl}} = \rho(hl))$$

$$\frac{dM_{\text{ctrl}}}{dt} = \frac{d}{dt} (\rho hl) = \boxed{\rho l \frac{dh}{dt}}$$

$$(\dot{m}_{\text{out}})_{\text{cs}} = \rho Q_1$$

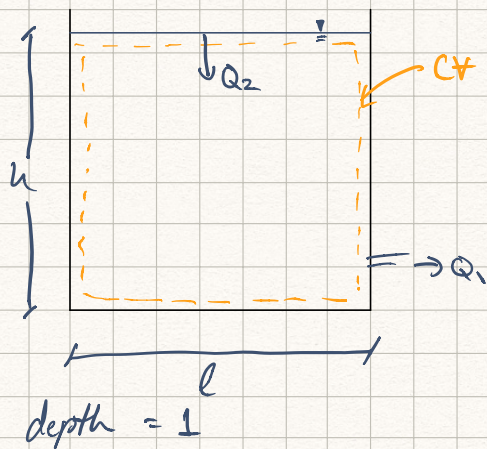
$$(\dot{m}_{\text{in}})_{\text{cs}} = 0$$

$$0 = \frac{dM_{\text{ctrl}}}{dt} + (\dot{m}_{\text{out}} - \dot{m}_{\text{in}})$$

$$0 = \rho l \left(\frac{dh}{dt} \right) + (\rho Q_1 - 0)$$

$$\frac{dh}{dt} = \frac{-Q_1}{l}$$

(Case 3)



$$\frac{d}{dt} (M_{\text{ctrl}}) = 0$$

$$(\dot{m}_{\text{out}})_{\text{cs}} = \rho Q_1$$

$$(\dot{m}_{\text{in}})_{\text{cs}} = \rho Q_2$$

$$0 = 0 + (Q_1 - Q_2) \rho$$

$$Q_1 = Q_2$$

$$Q_2 = \frac{\Delta \forall}{\Delta t} = vA$$

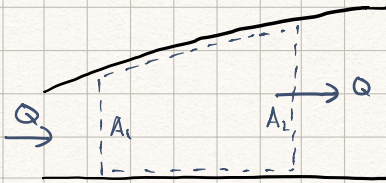
$$\left\{ \begin{array}{l} Q_2 = vA_2 = v(ld) = vl \\ Q_2 = lv \\ v = \frac{dh}{dt} \end{array} \right\} \frac{dh}{dt}(l) = Q_2$$

$$\frac{Q_1}{l} = \frac{dh}{dt}$$

Common Mistakes

$$\frac{dm_{tot}}{dt}$$

$$(m_{in})_{cs}$$



$$\frac{d(m_{tot})}{dt} = 0$$

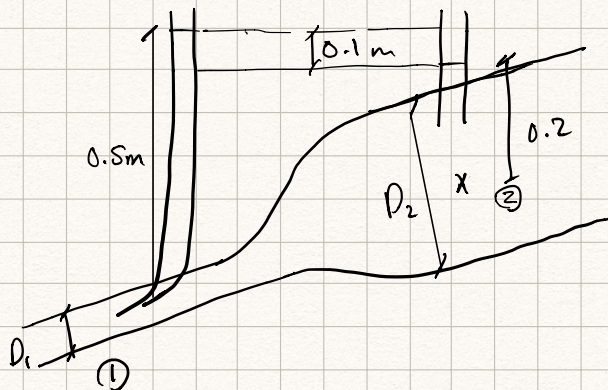
$$(m_{out})_{cs} = \rho Q_1$$

$$(m_{in})_{cs} = \rho Q_2$$

$$Q_1 = Q_2$$

$$v_1 A_1 = v_2 A_2$$

Example



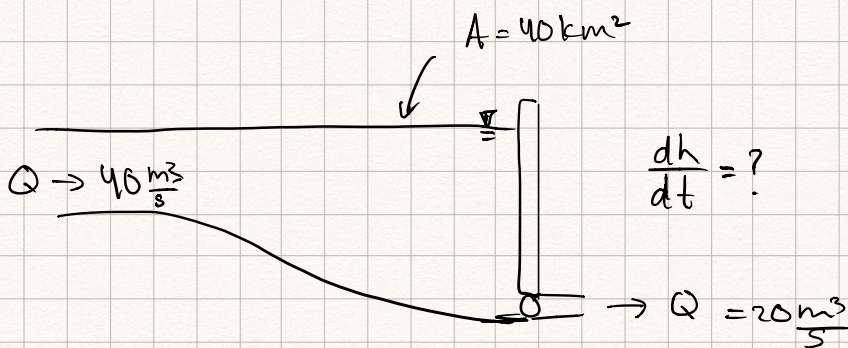
$$\text{loss} = 0$$

$$D_1 = \frac{1}{2} D_2$$

$$Q_1 = Q_2$$

$$4A_1 = v_2 A_2$$

$$v_1 = 4v_2$$



$$\frac{dh}{dt} = ?$$

$$0 = \frac{d(m_{tot})}{dt} + (m_{out} - m_{in})$$

$$\frac{dm_{tot}}{dt} \neq 0$$

$$\dot{m}_{out} = 20 \rho$$

$$\dot{m}_{in} = 40 \rho$$

$$\frac{d(m_{tot} = \rho h A)}{dt}$$

$$\begin{aligned} \frac{dm_{tot}}{dt} &= \frac{d}{dt} (\rho h A) \\ &= \left(\frac{dh}{dt} \right) \rho A \end{aligned}$$