

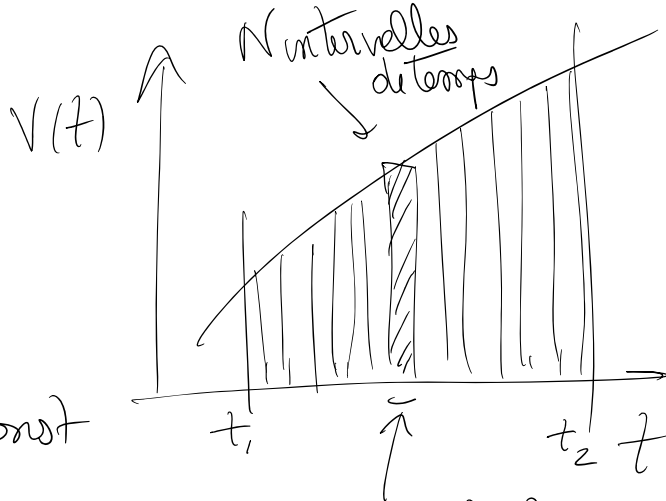
$$v = \frac{\Delta x}{\Delta t}$$

$$\Rightarrow \Delta x = v \Delta t$$

$$x - x_0 = v(t - t_0)$$

Si $v = \text{const}$

Si $v \neq \text{const}$



$$\Delta x = x_2 - x_1 = \sum_{n=1}^N \Delta x_n = \sum_{n=1}^N v(t_n) \Delta t_n = \lim_{\Delta t_n \rightarrow 0} \sum_{n=1}^N v(t_n) \Delta t_n$$

→ somme

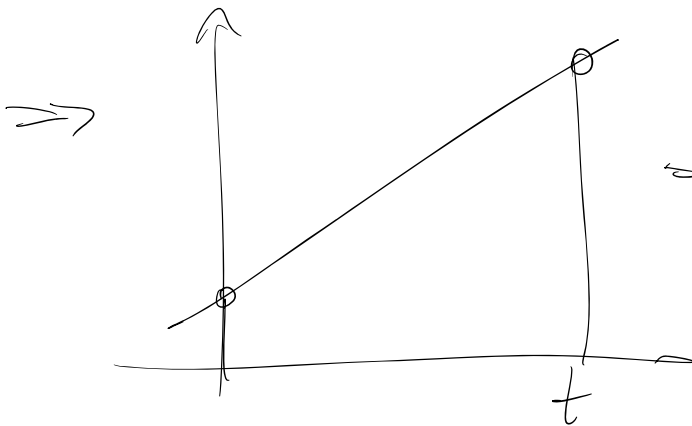
= aire sous la courbe $v(t)$ entre t_1 et t_2
 $= \int_{t_1}^{t_2} v(t) dt$

Si $a = \text{const}$

$$\Delta v = a \Delta t$$

$$v - v_0 = a(t - t_0)$$

→ $\text{si } t_0 = 0$
 $v = v_0 + at$ (1)



$$\Rightarrow x(t) = x_0 + v_0 t + \frac{1}{2} a t^2$$

(2)

(1) $\Rightarrow t = \frac{v - v_0}{a}$

(3) → (2) $x = x_0 + v_0 \left(\frac{v - v_0}{a} \right) + \frac{1}{2} a \left(\frac{v - v_0}{a} \right)^2$

$$\Delta x = x - x_0 = \left(\frac{v - v_0}{a}\right) \left[v_0 + \frac{1}{2} a \left(\frac{v - v_0}{a}\right) \right]$$

$$= \frac{1}{2a} (v - v_0)(v + v_0) = \frac{1}{2a} (v^2 - v_0^2)$$

$$\Rightarrow \boxed{v^2 - v_0^2 = 2a \Delta x}$$

$$\begin{aligned} v &= v_0 + at \\ x &= x_0 + v_0 t + \frac{1}{2} at^2 \\ v^2 - v_0^2 &= 2a(x - x_0) \end{aligned}$$

Ex 1 Accélération d'une voiture

$$v_0 = 0$$

en 6s $a = \text{const}$

$$0 \text{ km/h} \rightarrow 100 \text{ km/h}$$

J'ai besoin de v en m/s

$$v = 100 \text{ km/h} = \frac{100 \times 10^3 \text{ m}}{3600 \text{ s}}$$

$$= \frac{100}{3.6} = 27.8 \text{ m/s}$$

précision 1%

$$\Rightarrow a = \frac{27.8 - 0}{6} = 4.63 \text{ m/s}^2$$

(2) Déplacement

$$x - x_0 = \frac{1}{2} at^2 = \frac{1}{2} \times 4.63 \times 6^2$$

$$= 83.34 \text{ m}$$

$$\underline{x - x_0 = \frac{v^2}{2a} = \frac{27.8^2}{2 \times 4.63} = 83.46 \text{ m}}$$

1%
arr

$$x - x_0 = \frac{v}{2a} = \frac{27,8}{2 \times 4,63} = 83,46 \text{ m} \quad \bar{a} \approx 16 \text{ pres}$$

chute libre

$$v_y = v_{y_0} - gt$$

$$y = y_0 + v_{y_0}t - \frac{1}{2}gt^2$$

$$v_y^2 - v_{y_0}^2 = -2g(y - y_0)$$

y
(verticale)

$$a_y = -g$$

$$g = 9,80 \text{ m/s}^2$$

x
(horizontale)

$$v_{y_0} = 0$$

$$v_y^2 - 0 = -2g(0 - h)$$

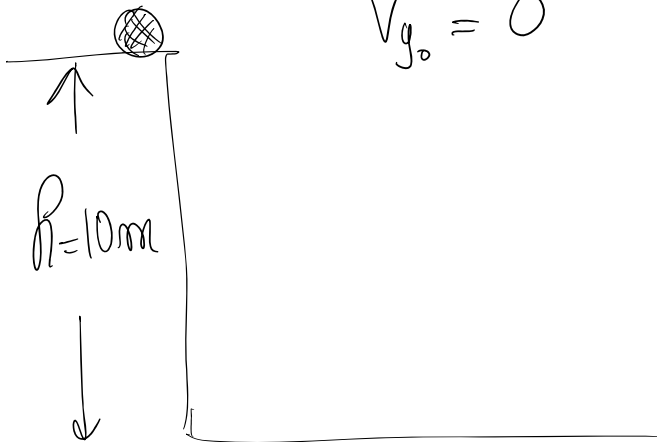
$$v_y^2 = 2gh$$

$$= 2 \times 9,8 \times 10$$

$$= 196 \text{ m}^2/\text{s}^2$$

$$v_y = \pm \sqrt{196} \text{ m/s}$$

$$= -14 \text{ m/s}$$



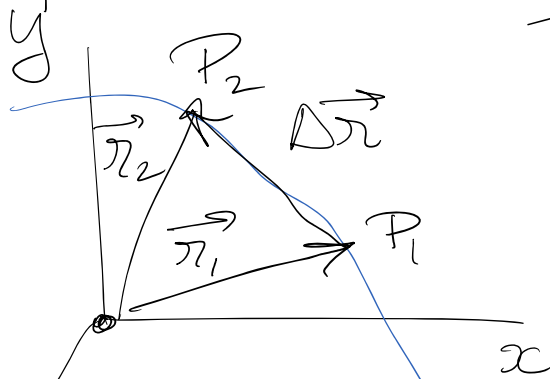
Chap. 4 Mouvement en 2 dimensions

① Mouvement dans l'espace (3 dimensions)

à t_1 : \vec{r}_1 au point P_1
à t_2 : \vec{r}_2 " P_2

déplacement

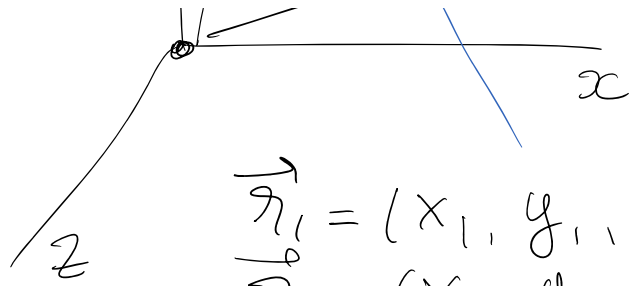
$$\vec{r}_1 + \Delta\vec{r} = \vec{r}_2$$



$$\vec{r}_1 + \Delta\vec{r} = \vec{r}_2$$

$$\Delta\vec{r} = \vec{r}_2 - \vec{r}_1$$

$$\Delta t = t_2 - t_1$$



$$\vec{r}_1 = (x_1, y_1, z_1)$$

$$\vec{r}_2 = (x_2, y_2, z_2)$$

$$\Delta\vec{r} = \vec{r}_2 - \vec{r}_1$$

$$= (x_2\hat{i} + y_2\hat{j} + z_2\hat{k}) - (x_1\hat{i} + y_1\hat{j} + z_1\hat{k})$$



$$= (x_2 - x_1)\hat{i} + (y_2 - y_1)\hat{j} + (z_2 - z_1)\hat{k}$$

$$= \Delta x\hat{i} + \Delta y\hat{j} + \Delta z\hat{k}$$

Vitesse moyenne

$$\vec{v}_{\text{moy}} = \frac{\Delta\vec{r}}{\Delta t} = \frac{\Delta x}{\Delta t}\hat{i} + \frac{\Delta y}{\Delta t}\hat{j} + \frac{\Delta z}{\Delta t}\hat{k}$$

Vitesse instantanée

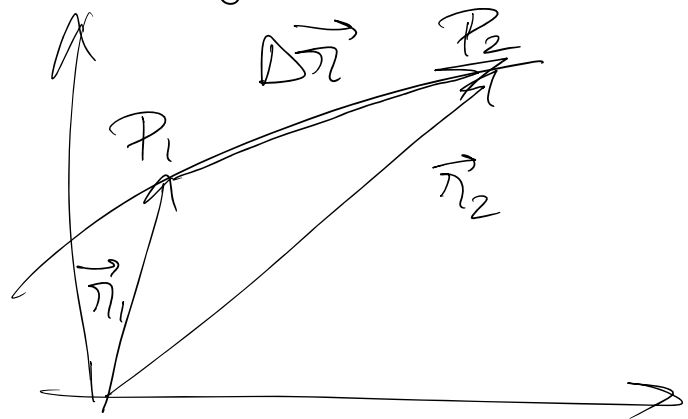
$$= \bar{v}_x\hat{i} + \bar{v}_y\hat{j} + \bar{v}_z\hat{k}$$

$$\vec{v} = \lim_{\Delta t \rightarrow 0} \frac{\Delta\vec{r}}{\Delta t}$$

$$= \frac{dx}{dt}\hat{i} + \frac{dy}{dt}\hat{j} + \frac{dz}{dt}\hat{k}$$

$$= v_x\hat{i} + v_y\hat{j} + v_z\hat{k}$$

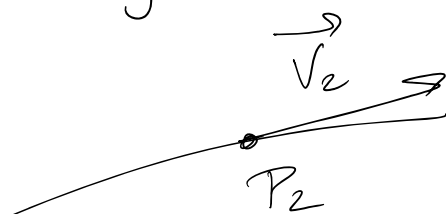
$P_2 \rightarrow P_1$:



\vec{v} est tangente à la trajectoire

Accélération

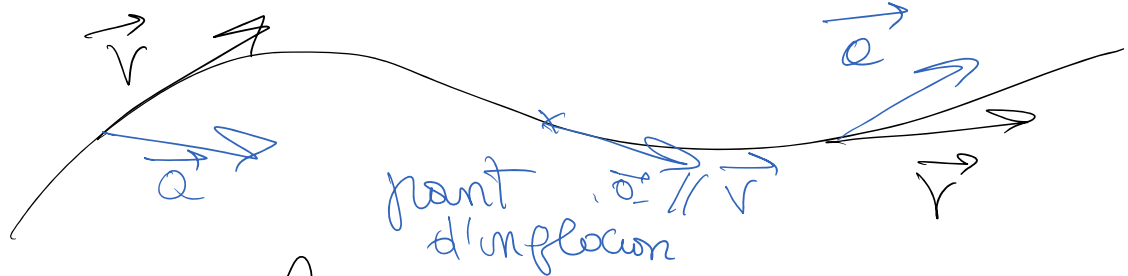
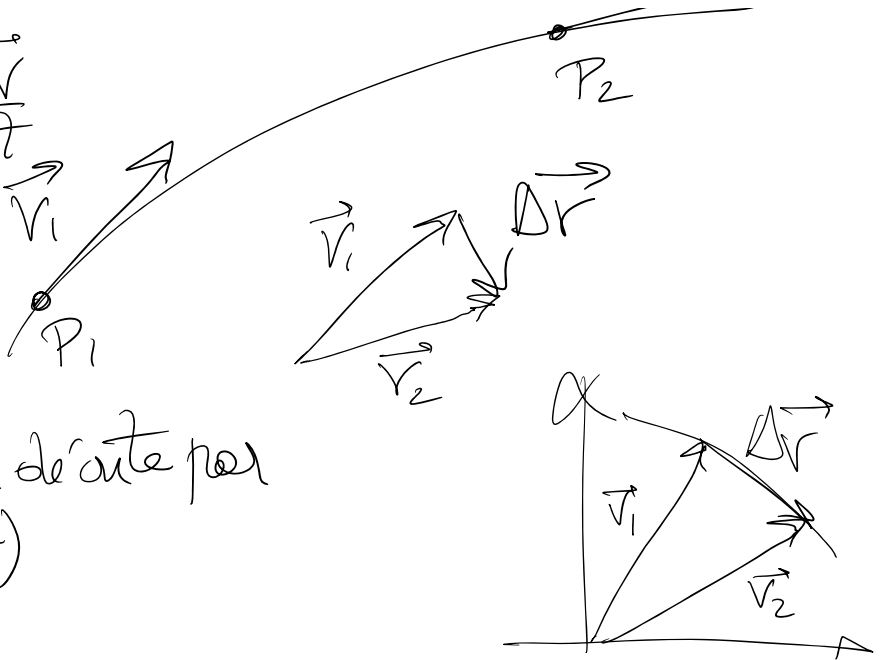
$$\rightarrow \vec{v}_0 - \vec{v}_1 \quad \Delta\vec{v}$$



$$\vec{a}_{\text{moy}} = \frac{\vec{v}_2 - \vec{v}_1}{\Delta t} = \frac{\Delta \vec{v}}{\Delta t}$$

$$\vec{a} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{v}}{\Delta t}$$

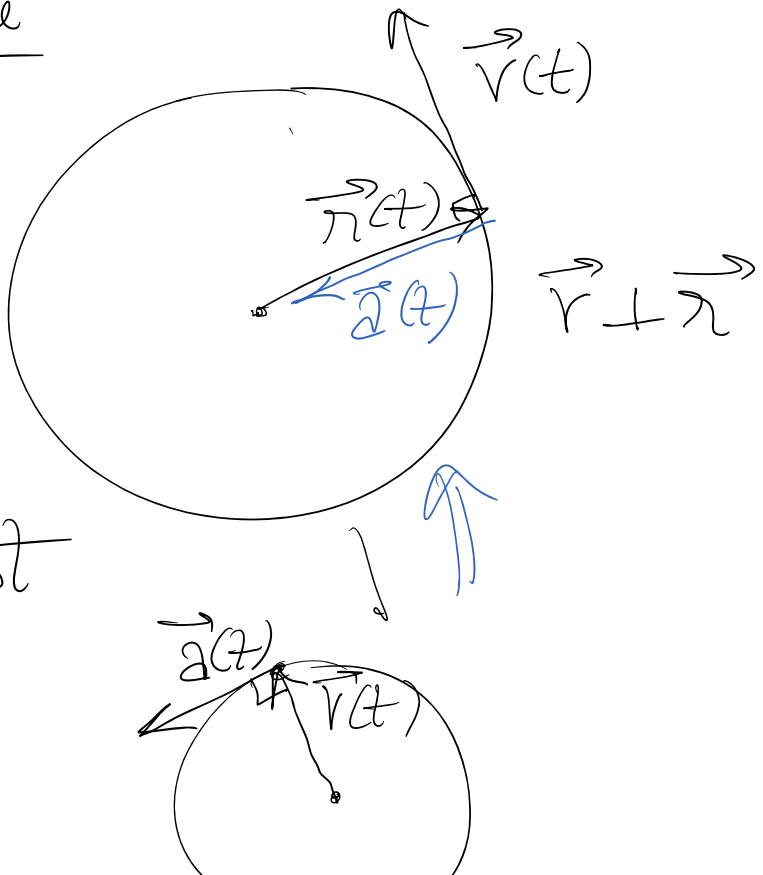
tangent à la courbe décrite par $\vec{v}(t)$



Mouvement circulaire

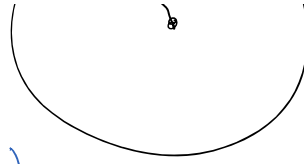
$|\vec{r}(t)| = r$ constant
 \Rightarrow particule décrit un cercle

spécifie : circulaire
uniforme
 $|\vec{v}| = \text{const}$



\vec{a} est tangente au cercle décrit par \vec{v}

- cercle de centru $\vec{r}(t)$



$\Rightarrow \vec{a}(t) \propto -\vec{r}(t)$
o accelerație centripetă

\propto simbol de
de proporționalitate

$$\vec{a}(t) = -a_r \hat{r}$$

\uparrow
radiale

$$\hat{r} = \frac{\vec{r}(t)}{|\vec{r}(t)|}$$

