



GNG 1105/ 1505
Final Exam

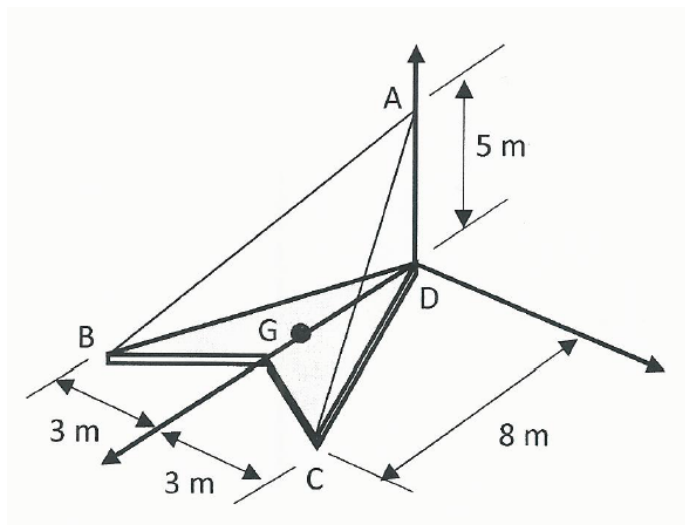
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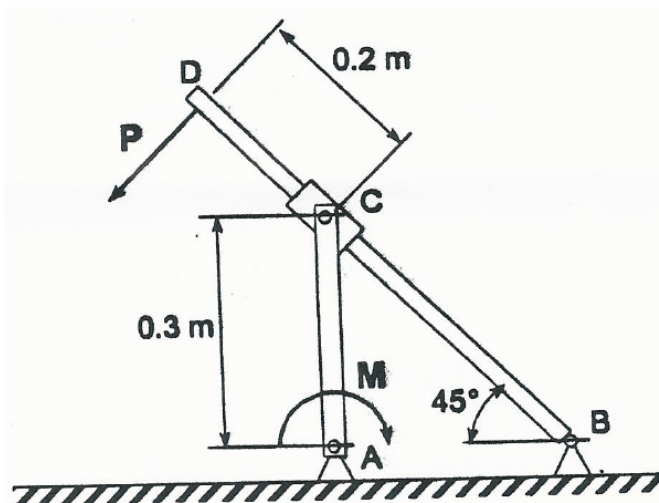
Time: 3 hours

Closed book examination. Only non-programmable calculators are allowed. All other electronic devices are not allowed. All questions are of equal value.

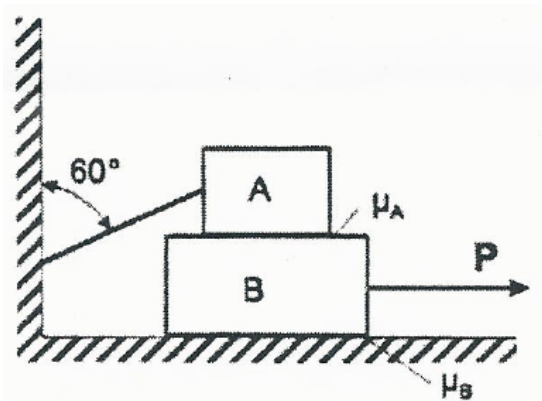
1. A horizontal plate with a mass of 800 kg is held in place by a ball and socket joint at D and two cables (AB and AC) as shown. The distance between the centre of mass of the plate (G) and the joint at D is 4m.
 - a. Draw the free body diagram for the plate.
 - b. Write, in vector form, the tension in cables AB, AC and the weight of the plate.
 - c. Calculate the tension forces in each cable and the components of the reaction at point D.



2. The mechanism shown has pin joints at A and B and is driven by a couple $M=100$ Nm at A. Joint C is a frictionless slider which is attached to member AC by a frictionless pin. (a) Calculate the force P required to maintain the system in equilibrium. P acts at right angles to BD, and AC is vertical. (b) Determine the reactions at A and B.

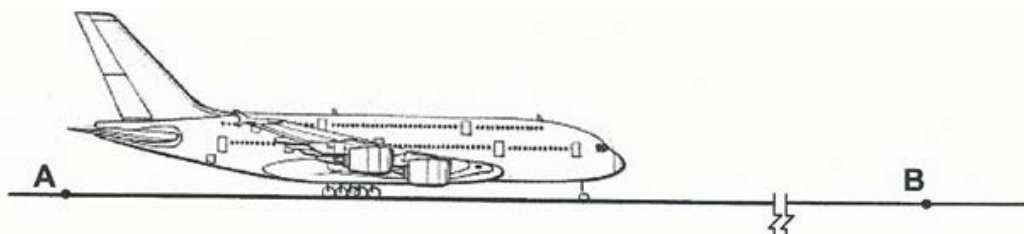


3. Block A in the sketch has a mass of 20 kg and is attached to the wall by means of a cord at an angle of 60° with the vertical, while block B has a mass of 40 kg. The coefficient of static friction between A and B is 0.2, while the coefficient of static friction between B and the floor is 0.3. Determine the minimum force P required to cause Block B to slide (i.e. Motion impending).

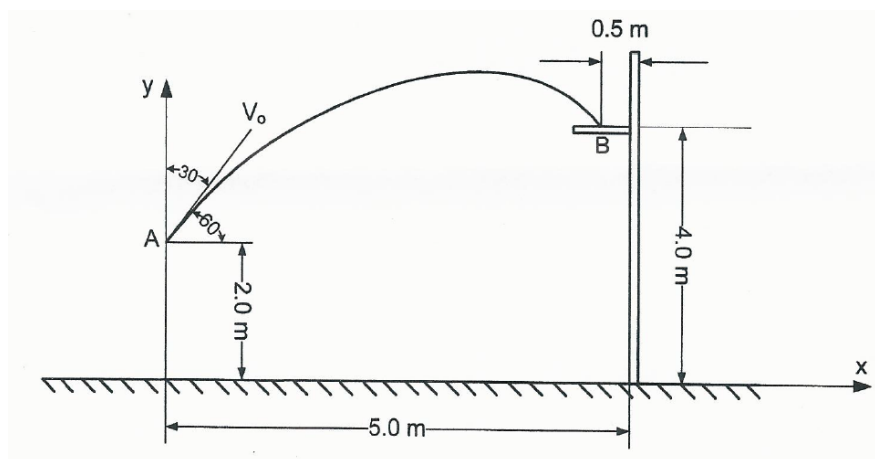


4. Parts (a) and (b) are independent.

(a) An airplane begins to take-off on the runway at point A with zero velocity and a constant acceleration a . Knowing that it will take off 30s later at point B and that the distance AB is 900m, determine (a) the acceleration a , (b) the take-off velocity V_B .



(b) A basketball player threw the ball at point A with an initial velocity, V_o , which makes 60° with the horizontal. It falls through a hoop at B. Determine the initial velocity, V_o , of the ball ($g=9.81\text{m/s}^2$).



Useful Equations:

$$\begin{aligned}
 x &= x_o + vt & x &= x_o + v_o t + \frac{1}{2}at^2 & \sum \vec{F} &= m\vec{a} \\
 v &= v_o + at & v^2 &= v_o^2 + 2a(x - x_o) & & \\
 \sum F_x &= ma_x & , & \sum F_y &= ma_y & , \sum F_z = ma_z
 \end{aligned}$$