

In a source-free region (no current): $\vec{\nabla} \times \vec{H} = 0 \Rightarrow \oint_C \vec{H} \cdot d\vec{l} = 0$

→ For conservative field \vec{E} : $\vec{E} = -\vec{\nabla}V$

$$\hookrightarrow V_{ab} = -\int_b^a \vec{E} \cdot d\vec{l}$$

↓
if C does not enclose any current.

when $\vec{\nabla} \times \vec{H} = 0 \Rightarrow \vec{H} = -\vec{\nabla}f$ [A] $f =$ m-scalar Potential or magnetostatic Potential.

$$f_{ab} = f_a - f_b = -\int_b^a \vec{H} \cdot d\vec{l}$$

magnetomotive force (mmf): To describe the difference in m-Potential between two points.

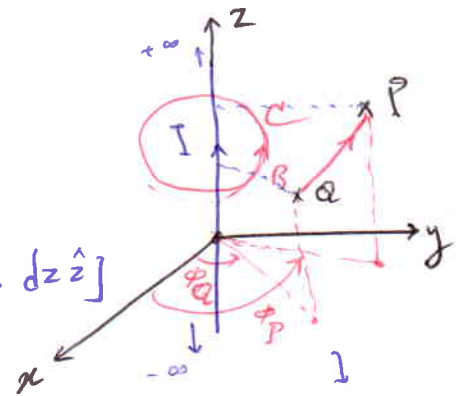
$$\vec{\nabla} \cdot \vec{B} = 0 \Rightarrow \vec{\nabla} \cdot \mu \vec{H} = 0 \Rightarrow \vec{\nabla} \cdot \vec{H} = 0 \quad (\text{linear, isotropic \& homogeneous})$$

$$\Rightarrow \vec{\nabla} \cdot (-\vec{\nabla}f) = 0 \Rightarrow \nabla^2 f = 0 \quad \text{Laplace's eqn for m-scalar Potential in a current-free region.}$$

EX: A wire, I in z -direction. Find m-potential difference between two points in space:

$$\oint_C \vec{H} \cdot d\vec{l} = I_{enc.} \Rightarrow H(2\pi r) = I \Rightarrow \vec{H} = \frac{I}{2\pi r} \hat{\phi}$$

$$f_{PQ} = -\int_{\phi_Q}^{\phi_P} \vec{H} \cdot d\vec{l} \quad ; \quad \vec{H} \cdot d\vec{l} = H_{\phi} \hat{\phi} \cdot [ds \hat{r} + r d\phi \hat{\phi} + dz \hat{z}] = \frac{I}{2\pi} d\phi$$



$P(r_P, \phi_P, z)$, $Q(r_Q, \phi_Q, z_Q)$:

$$f_{PQ} = -\int_{\phi_Q}^{\phi_P} \frac{I}{2\pi} d\phi = -\frac{I}{2\pi} [\phi_P - \phi_Q] = \frac{I}{2\pi} (\phi_Q - \phi_P)$$

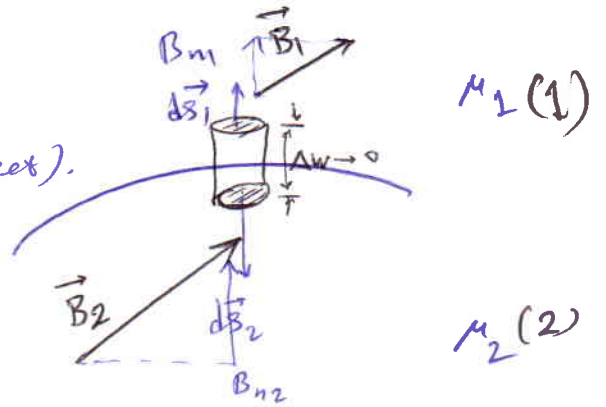
$\phi_P > \phi_Q$
↓
Pot. drop (mmf drop).

Interface

Boundary conditions for m-fields: behavior of m-fields at the boundary between two media (regions) with different permeabilities.

\vec{B} : $\oint_S \vec{B} \cdot d\vec{S} = 0$

s: pillbox
 $\Delta w \rightarrow 0$ (no effect).



$$\int_{S_1} \vec{B} \cdot d\vec{S} + \int_{S_2} \vec{B} \cdot d\vec{S} = 0$$

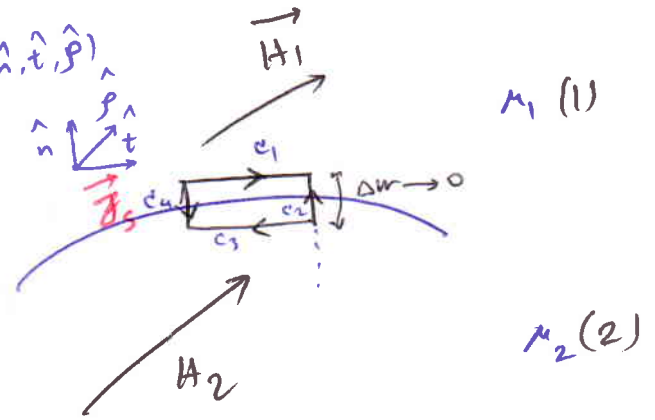
$$\begin{cases} d\vec{S}_1 = dS \hat{n} \\ d\vec{S}_2 = dS (-\hat{n}) \end{cases} \Rightarrow \int_{S_1} \vec{B} \cdot \hat{n} dS + \int_{S_2} \vec{B} \cdot (-\hat{n}) dS = 0$$

$$\int_S (B_{n1} - B_{n2}) dS = 0 \Rightarrow B_{n1} = B_{n2}$$

$$\hat{n} \cdot (\vec{B}_1 - \vec{B}_2) = 0$$

\vec{H} : $\oint_C \vec{H} \cdot d\vec{l} = I$ $\Delta w \rightarrow 0$

mutually perpendicular mit Vec tort.



$$\int_{C_1} \vec{H} \cdot d\vec{l} + \int_{C_3} \vec{H} \cdot d\vec{l} = I$$

$$\int_{C_1} \vec{H}_1 \cdot \hat{t} dl + \int_{C_3} \vec{H}_2 \cdot (-\hat{t}) dl = I$$

$$= \int_S \vec{J}_v \cdot \hat{p} dl \Delta w$$

$$\lim_{\Delta w \rightarrow 0} \vec{J}_v \Delta w = \vec{J}_s$$

$\Delta w \rightarrow 0$ shrink.

$$\Rightarrow \int_{C_1} (\vec{H}_1 - \vec{H}_2) \cdot \hat{t} dl = \int_{C_1} \vec{J}_s \cdot \hat{p} dl$$

$$\hat{t} = \hat{p} \times \hat{n}$$

$$\Rightarrow \int_{C_1} (\vec{H}_1 - \vec{H}_2) \cdot (\hat{p} \times \hat{n}) dl = \int_{C_1} \vec{J}_s \cdot \hat{p} dl$$

using vector identity: $\int_{C_1} \hat{n} \times (\vec{H}_1 - \vec{H}_2) \cdot \hat{p} dl = \int_{C_1} \vec{J}_s \cdot \hat{p} dl$

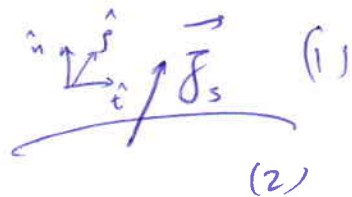
$$\rightarrow \hat{n} \times (\vec{H}_1 - \vec{H}_2) = \vec{J}_s$$

tangential components of \vec{H} -field at boundary are discontinuous.

$$H_{t1} - H_{t2} = J_s$$

$$\text{if } \vec{J}_s = J_s \hat{p}$$

$$\leftarrow H_{t1} > H_{t2} \leftarrow$$



\Rightarrow For two m -media with finite conductivities (σ), $\vec{J}_s = 0$.

If there is any current flow in either medium, it will be in \vec{J}_s .

\Rightarrow If one of the media is Perfect conductor, m -field inside the Perfect conductor $\Rightarrow \vec{J}_s$ exists on the surface of Perfect conductor.

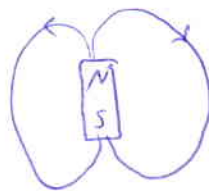
Energy in m -field: $w_e = \frac{1}{2} \vec{D} \cdot \vec{E} \Rightarrow W_e = \frac{1}{2} \int_V \vec{D} \cdot \vec{E} dV$

$$w_m = \frac{1}{2} \vec{B} \cdot \vec{H} \Rightarrow W_m = \frac{1}{2} \int_V \vec{B} \cdot \vec{H} dV$$

$$= \frac{1}{2} \mu H^2 = \frac{B^2}{2\mu} \rightarrow W_m = \int_V w_m dV$$

Magnetic circuits:

\rightarrow magnetic flux lines form a closed path and m -flux entering a boundary is the same as the



m -flux leaving a boundary \rightarrow Like current in a closed conducting circuit.

→ The m-flux cannot be completely confined to follow a given path in a magnetic material ^{as good a} ~~take~~ currents, but if the permeability of the magnetic material is very high compared to that of surrounding (such as free space) most of the flux will be confined to highly permeable material.

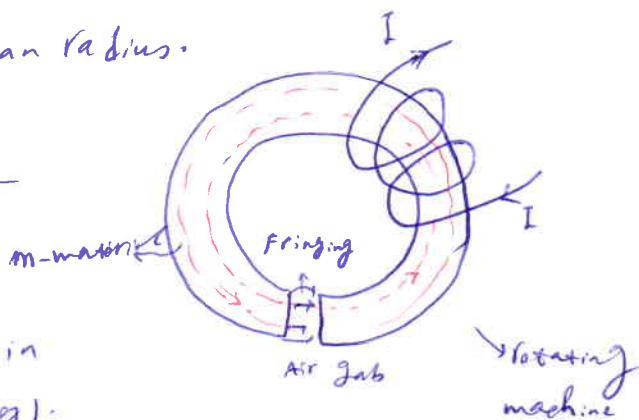
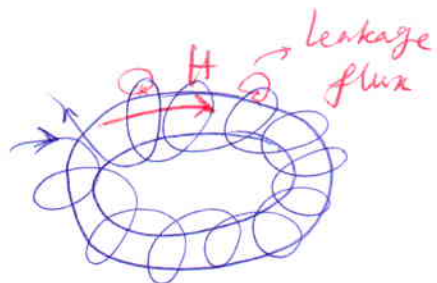
magnetic shielding: m-flux will be concentrated within a magnetic material.

→ channeling of the flux \equiv current through a conductor.

↳ **magnetic circuit**

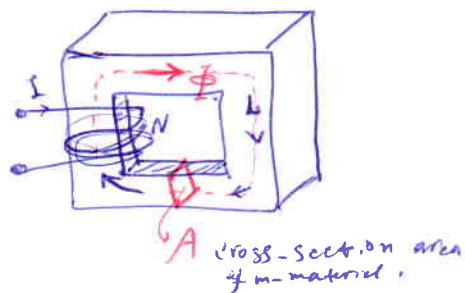
→ we assume that the m-flux density is uniform within the m-material, and its magnitude is equal to the m-flux density at the mean radius.

Highly permeable material is in series with a low permeable material. →



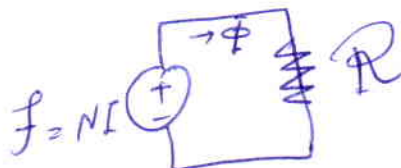
flux are equal: spread of m-flux in air gap. (fringing).
 Ampere-turn [A.t]

$$f = NI = \oint_C \vec{H} \cdot d\vec{l} \quad \begin{matrix} \text{H is uniform} \\ \underline{\underline{HL}} \\ \downarrow \\ \text{length of magnetic path.} \end{matrix}$$



$$B = \mu H = \frac{\mu NI}{L} \quad ; \quad \mu = \text{Permeability of the m-material.}$$

$$\Phi = \int_S \vec{B} \cdot d\vec{S} = BA = \frac{\mu NI A}{L} = \frac{NI}{L/\mu A} = \frac{f}{L/\mu A}$$



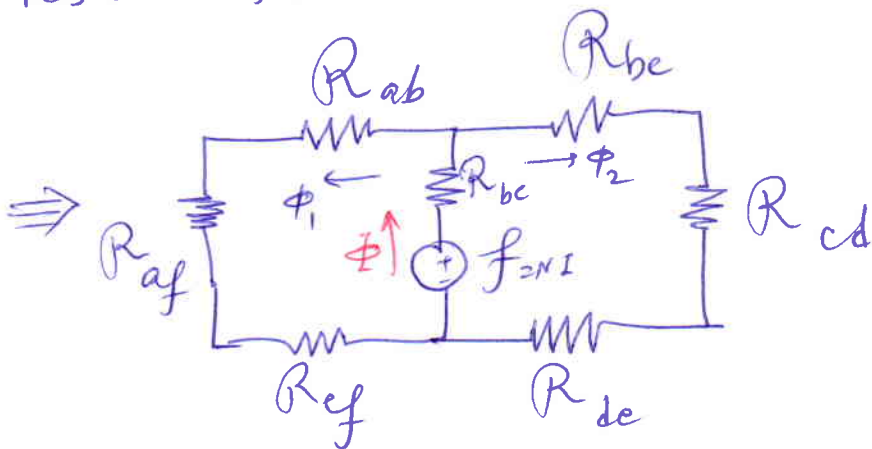
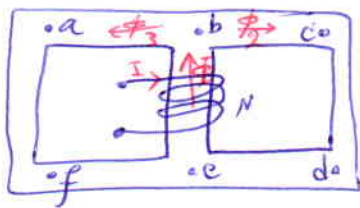
$\equiv R$ "reluctance" of m-circuit.
 [A.t]

$\Rightarrow R = \frac{L}{\mu A} \Rightarrow \Phi R = NI$ ohm's law for the m-circuit.

$R = \frac{L}{\mu A} \Rightarrow \mu \equiv \sigma \Rightarrow \mu \uparrow \Rightarrow R \downarrow$

For the same ^{applied} magnetomotive force (mmf), the flux in highly permeable material will be higher than that in a low permeable material.

In a circuit containing many m-materials, each part can be represented by its reluctance. \Rightarrow resistances.



H_i = m-field intensity in the i^{th} section of a m-circuit

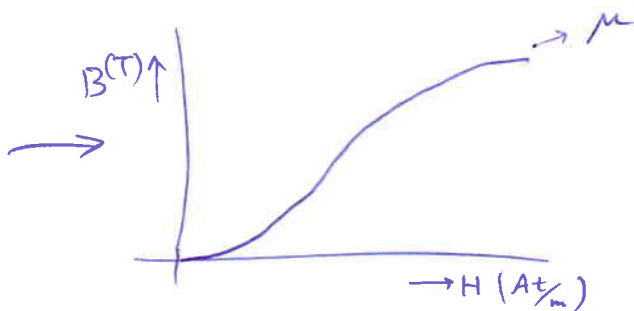
L_i = mean length of i^{th} section.

Total mmf drop in the m-circuit = mmf applied

$\sum_{i=1}^n H_i L_i = NI$ Kirchhoff's voltage law for an e-circuit (analogous)

* for linear m-materials (constant permeability) we can use analogous circuit.

nonlinear m-materials: magnetization characteristic (B-H curve)
 μ is dep. to m-flux density
 Ferromagnetic materials (iron).



two types of Problems: $\left\{ \begin{array}{l} \text{(a) m-f flux density is given} \rightarrow \text{Find applied mmf} \\ \text{(b) applied mmf is given} \rightarrow \text{Calculate m-f flux density} \rightarrow \text{flux} \\ \text{in m-circuit.} \end{array} \right.$

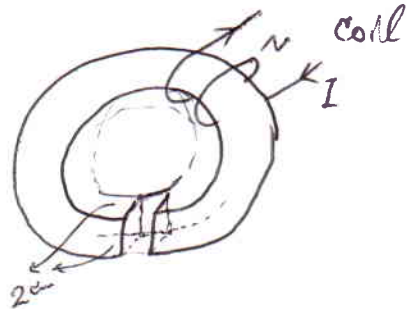
solving problems: $\left\{ \begin{array}{l} \text{Linear m-material} \rightarrow \text{equivalent circuit approach} \\ \text{Non linear} \left\{ \begin{array}{l} \text{(a) Calculate flux density in each m-section} \rightarrow H \text{ from} \\ \text{B-H curve} \rightarrow \text{mmf drops across each m-section} \rightarrow \text{Summation} \\ \text{applied.} \\ \text{(b)} \rightarrow \text{using iterative technique;} \end{array} \right. \end{array} \right.$

educated guess for mmf drop in one of the m-regions \rightarrow obtain the total mmf requirements \rightarrow compare the results with the given mmf \rightarrow another educated guess if we are off.

\rightarrow continue till the error between calculated mmf & the applied mmf is within permissible limits.

($\pm 2\%$).

EX! An electromagnet of square cross section, with 1500 turns, radii inner 10 cm & outer 12 cm. length of airgap 1 cm. $I = 4 \text{ A}$, $\mu_r = 1200$, Find flux density in the magnetic circuit.



$\mu_r = \text{const}$, Applied mmf is known. \rightarrow reluctance method \rightarrow flux density in the core.

$$r_{\text{mean}} = \bar{r} = \frac{r_{\text{in}} + r_{\text{out}}}{2} = 11 \text{ cm}$$

$$L_m = \text{mean length of m-Path} = 2\pi\bar{r} - l = 2\pi(11) - 1 = 68.12 \text{ cm}$$

neglecting the effect of fringing, cross-section area of m-Path is the same as

$$\text{gap} \rightarrow A_m = A_g = 2 \times 2 = 4 \text{ cm}^2.$$

$$\text{Reluctance of each region: } R_m = \frac{L}{\mu_r \mu_0 A} = \frac{68.12 \times 10^{-2}}{(1200)(4\pi \times 10^{-7})(4 \times 10^{-4})} = 1.29 \times 10^6 \frac{\text{At}}{\text{wb}}$$

$$R_g = \frac{L_g}{\mu_0 A} = \frac{1 \times 10^{-2}}{(4\pi \times 10^{-7})(4 \times 10^{-4})} = 19.894 \times 10^6 \frac{\text{At}}{\text{wb}}$$

$$R = R_m + R_g = 21.023 \times 10^6 \frac{\text{At}}{\text{wb}}$$

$$\text{Flux in the m-circuit } \Phi = \frac{NI}{R} = \frac{(1500)(4)}{21.023 \times 10^6} = 285.402 \times 10^{-6} \text{ wb}$$

$$\text{Flux density: } B_m = B_g = \frac{\Phi}{A} = \frac{285.402 \times 10^{-6}}{4 \times 10^{-4}} = 0.714 \text{ T}$$

Problems: 5.2, 5.7, 5.11, 5.20, 5.25, 5.31, 5.35, 5.39,

7: Time-varying electromagnetic fields

Summary so far: a) static e-fields are created by charges.

b) \sim m-fields are produced by charges in motion or steady currents.

c) \sim e-field is a conservative field ($\vec{\nabla} \times \vec{E} = 0$)

d) \sim m-field is continuous because ($\vec{\nabla} \cdot \vec{B} = 0$).

e) \sim e-field can exist even when there is no static m-field and vice versa.

- In this chapter: we show that a time-varying m-field \rightarrow produces a time-varying e-field, which is called "induced e-field" or "an emf-producing e-field".

- Induced e-field is not a "conservative" field.

- Induced emf $\equiv \oint_{\text{ind}} \vec{E} \cdot d\vec{l}$. (electro-motive force).

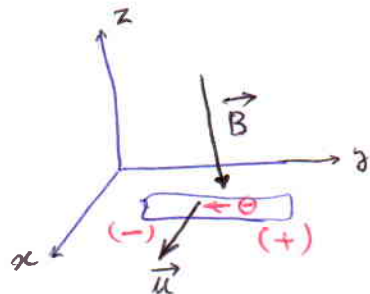
- If there exists a t-varying e-field \leftrightarrow there exist a t-varying m-field, in that region.

- Maxwell's eqn: describes the relations between e-field & m-field.

Motional electromotive force:

A conductor moving with a uniform velocity \vec{u}

$$\text{in } \hat{z} \text{ direction; } \vec{B} = -B\hat{z} \rightarrow \vec{F}_{\text{on each free electron}} = q_e \vec{u} \times \vec{B} = q_e u B \hat{y}$$



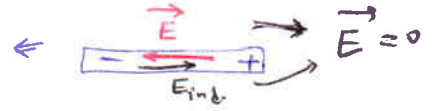
Barnett exp: cut the conductor while it was moving.

The left part had (-) charge, & the right part had (+) charge.

$\Rightarrow \frac{\vec{F}}{q_e} = uB\hat{y} = \vec{u} \times \vec{B} = \vec{E} \rightarrow$ induced electric field (motional e-field).
 induced e-field is a nonconservative field.

Boundary condition:

- induced e-field is tangential to the surface of the conductor. AS the tangential component of e-field just above the surface = 0 \Rightarrow e-field just beneath the surface of conductor = 0

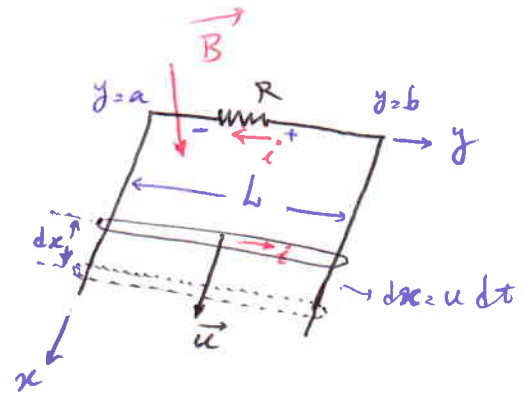


$\Rightarrow \vec{E}$ due to separation of charges = $\vec{E}_{induced} \Rightarrow \vec{E}_{net} = 0$

- sliding conductor: If we make a closed loop, the accumulation of charges will not happen. \rightarrow induced current in the same direction as induced e-field.

The moving conductor acts like an emf source

Induced emf



Lorentz force: m-force on moving conductor: $\vec{F}_m = i\vec{L} \times \vec{B} = -Bil\hat{x}$ (opposes the motion of conductor).

$\vec{F}_{external} = -\vec{F}_m = Bil\hat{x} \equiv i\vec{L} \times \vec{B}$

$dW_{ext} = \vec{F}_{ext} \cdot d\vec{x} = BLi dx = BLi u dt$; $dq = i dt$

$dW_{ext} = BL u dq$

$\Rightarrow e = \frac{dW_{ext}}{dq} = Bl u$ induced emf; motional emf.
 [Volt] = [J/C]. [T $\equiv \frac{wb}{m^2}$] [m] [m/s].
 "flux cutting action" of a conductor in m-field.

Generally:

$\vec{F}_{ext} = - \int_C i d\vec{l}_c \times \vec{B}$
 Path of integration in elemental length of conductor in \hat{i} direction.

$\Rightarrow dW = \vec{F}_{ext} \cdot d\vec{l} = -i d\vec{l} \cdot \int_C d\vec{l}_c \times \vec{B}$

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$$i = \frac{dq}{dt}, \vec{u} = \frac{d\vec{l}}{dt}$$

$$\Rightarrow e = \frac{dw}{dq} = -\vec{u} \cdot \int_c \vec{dl}_c \times \vec{B}$$

\vec{u} does not vary along the length of conductor.

$$= - \int_c \vec{u} \cdot (d\vec{l}_c \times \vec{B}) = \int_c \vec{u} \cdot (\vec{B} \times d\vec{l}_c)$$

vector identity.

$$\text{emf}_{\text{ind.}} \rightarrow e = \int_c (\vec{u} \times \vec{B}) \cdot d\vec{l}_c$$

$i_{\text{ind.}}$ due to motional emf \Leftarrow
is in the direction of the $E_{\text{ind.}}$

$H_{\text{ind.}} =$ induced E-field intensity

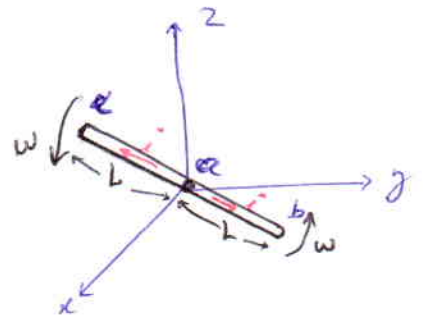
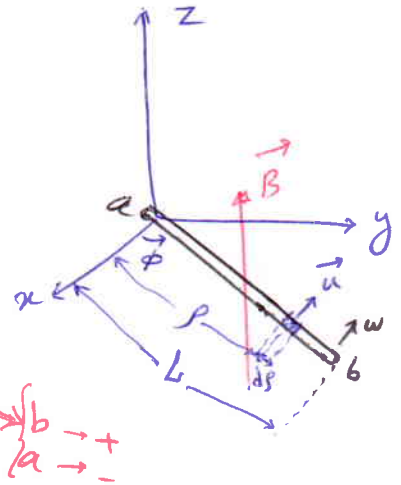
EX: A COPPER STRIP of length L pivoted at one end is rotating freely with an angular velocity ω in a uniform m-field. what is induced emf? between the two ends of the strip? $\vec{B} = B\hat{z}$

$$e_{ba} = \int_c (\vec{u} \times \vec{B}) \cdot d\vec{l}_c$$

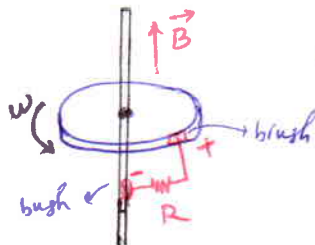
$$\vec{u} = \omega \hat{\phi} \Rightarrow \vec{E} = \vec{u} \times \vec{B} = \omega B (\hat{\phi} \times \hat{z}) = \omega B \hat{r} \rightarrow \text{radial direction.}$$

$$\Rightarrow e_{ba} = \omega B \int_0^L \rho d\rho = \frac{1}{2} \omega B L^2.$$

$$\Rightarrow e_{cb} = e_{ca} + e_{ba} = 0.$$



HOMOPOlar Generator: if we use many rotating rod ($2L$) (each supplying $2I$), we can increase the current through R considerably. A disc acts like a constant (dc) voltage source.



(Faraday's disc).