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Student No. _____

**DEPARTMENT OF MECHANICAL & INDUSTRIAL ENGINEERING
CONCORDIA UNIVERSITY
MECH 375/1-CC: Mechanical Vibrations**

CLASS TEST

29 July 2013

DURATION: 90 Minutes

8 PAGES

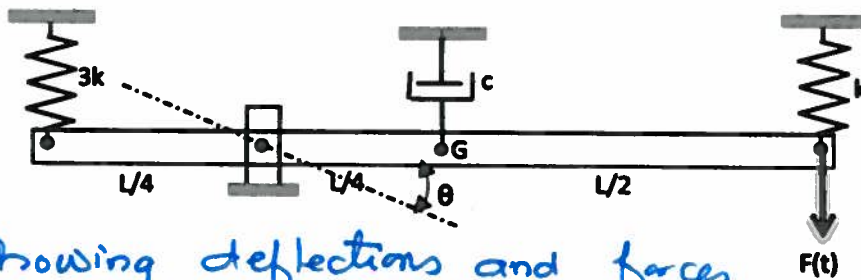
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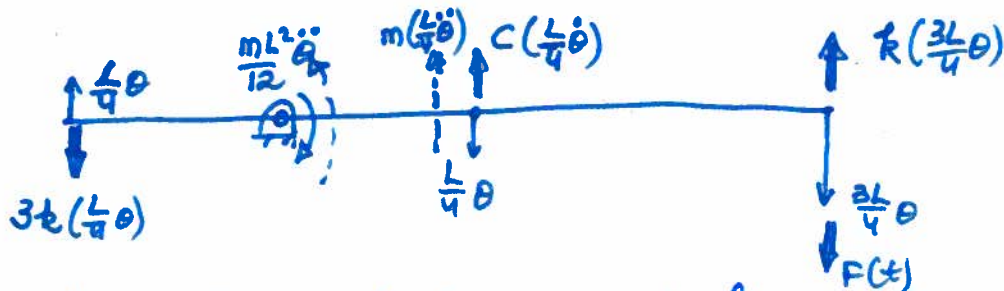
QUESTION # 1 (25)

For the uniform rigid bar of mass m and $I_G = mL^2/12$, compute the following, given that $m=5$ kg; $k=6220$ N/m; $L=0.6$ m; $c=12$ Ns/m; $F(t) = 120 \cos(20\pi t)$ N:

- Equivalent stiffness and inertia with generalized coordinate being bar rotation θ about the pivot.
- Equation of motion of the system
- Critical damping constant
- Natural frequency and damping ratio of the system.



FBD showing deflections and forces



Σ moments = Σ moments due to ext. force

$$3k\left(\frac{L}{4}\theta\right)\left(\frac{L}{4}\right) + k\left(\frac{3L}{4}\theta\right)\left(\frac{3L}{4}\right) + c\left(\frac{L}{4}\dot{\theta}\right)\left(\frac{L}{4}\right) + m\left(\frac{L}{4}\ddot{\theta}\right)\left(\frac{L}{4}\right) + \frac{mL^2}{12}\ddot{\theta} = F(t) \cdot \left(\frac{3L}{4}\right)$$

$$\frac{3}{4}kL^2\theta + c\frac{L^2}{16}\dot{\theta} + \left(\frac{mL^2}{16} + \frac{mL^2}{12}\right)\ddot{\theta} = \frac{3L}{4}F(t)$$

$$\frac{7}{48}mL^2\ddot{\theta} + c\frac{L^2}{16}\dot{\theta} + \frac{3}{4}kL^2\theta = \frac{3L}{4}F(t)$$

$$a) \quad k_{eq} = \frac{3}{4} kL^2 = \frac{3}{4} (6220) (.6)^2 = 1679.4 \text{ Nm/rad}$$

$$m_{eq} = \frac{7}{48} mL^2 = \frac{7}{48} (5) (.6)^2 = 0.2625 \text{ kg m}^2$$

$$b) \quad \text{Eqn. of motion} \quad cL^2/16 = 12 \times \frac{.6^2}{16} = 0.27$$

$$.2625 \ddot{\theta} + 0.27 \dot{\theta} + 1679.4 \theta = 54 \cos(20\pi t)$$

$$c) \quad c_c = 2 \sqrt{k_{eq} m_{eq}} = 42 \text{ Nms/rad}$$

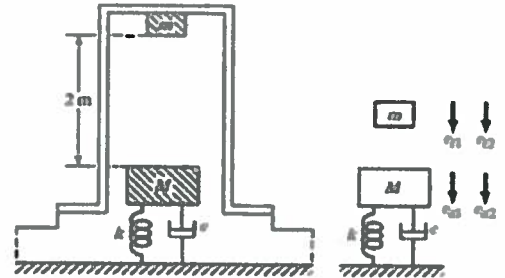
$$d) \quad \omega_n = \sqrt{\frac{k_{eq}}{m_{eq}}} = \sqrt{\frac{1679.4}{.2625}} = 79.99 \text{ rad/s}$$

$$f = \frac{c_{eq}}{c_c} = \frac{0.27}{42} = 0.0064.$$

QUESTION # 2 (25)

The anvil of the forging hammer, shown below, is supported on an elastic support with vertical stiffness of 500,000 N/m and critical damping constant of 20,000 Ns/m. The log decrement of the support was measured as 0.75. During the forging operation, the hammer of mass m is made to drop on the anvil from a height of 2 m. The hammer, however, bounces back immediately after the impact with the anvil mass M and it causes a velocity of the anvil mass M of 2.5 m/s.

- Determine the vibration response of M
- Maximum displacement of M



Egn. of motion

$$M\ddot{x} + c\dot{x} + kx = 0$$

$$\dot{x}(0) = 2.5 \text{ m/s} \quad x(0) = 0$$

Given $\delta = 0.75 \approx 2\pi\zeta \rightarrow \zeta = 0.1194$

Alternatively $\zeta = \frac{2\pi\delta}{\sqrt{1-\delta^2}}$; $\zeta = \frac{\delta}{\sqrt{\delta^2 + 4\pi^2}} = 0.1185$

Let $\zeta = 0.119$

$$C_c = 20,000 \text{ Ns/m (Given)}$$

$$C = C_c \times \zeta = 20,000 \times 0.119 = 2,380 \text{ Ns/m}$$

Also $C_c = 2\sqrt{kM}$; $M = \frac{C_c^2}{4k} = \frac{20000^2}{4 \times 500,000}$

$$\therefore \omega_n = \sqrt{\frac{k}{M}} = \sqrt{\frac{500,000}{200}} = \underline{50 \text{ rad/s}} \quad M = \underline{200 \text{ kg}}$$

$$\omega_d = \omega_n \sqrt{1 - \zeta^2} = 50 \sqrt{1 - 0.119^2} = 49.645 \text{ rad/s}$$

a) Free Vibration Response

$$x(t) = e^{-\zeta \omega_n t} [A \cos \omega_d t + B \sin \omega_d t]$$

$$x(0) = 0 \quad \text{yields} \quad A = 0$$

$$\dot{x}(0) = 2.5 \text{ m/s} \quad \text{yields} \quad B = \frac{2.5}{\omega_d} = 0.05036$$

$$\zeta \omega_n = 0.119 \times 50 = 5.95$$

$$\therefore x(t) = 0.05036 e^{-5.95 t} \sin 49.645 t, \text{ m}$$

b) Maximum displacement response occurs when

$$49.645 t = \pi/2; \quad t = 0.0316$$

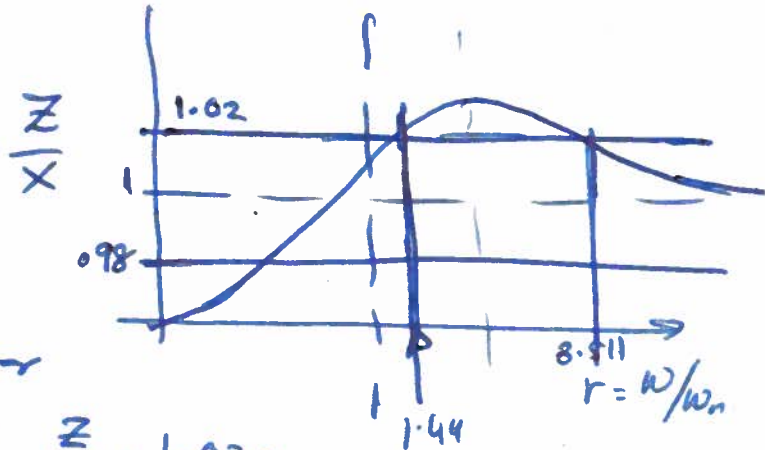
$$X_{\max} = 0.05036 e^{-5.95 \times 0.0316} = \underline{\underline{0.0417 \text{ m}}}$$

QUESTION # 3 (15)

The undamped natural frequency of a vibrometer is 10 Hz and its frequency of damped oscillations is reported as 8 Hz. Determine the lowest frequency so that it can measure the displacement of a structure with less than 2 percent error.

Given $f_n = 10 \text{ Hz}; f_d = 8 = f_n \sqrt{1 - \zeta^2}$

$\therefore \zeta = 0.6$



It appears that the error would be corresponding to $\frac{Z}{X} = 1.02$.

Since $\zeta = 0.6$ is quite high, it is also possible that peak value may not approach 1.02 (Caution)

Let $\left(\frac{Z}{X}\right)_{\text{peak}} = 1.02 = \frac{r^2}{\sqrt{(1-r^2)^2 + (2\zeta r)^2}}$

$$\frac{1.04}{1.02^2} = 1 + r^4 - 2r^2 + 4\zeta^2 r^2$$

$$0.96117 r^4 = r^4 + 1 - 0.56 r^2$$

$$0.03883 r^4 - 0.56 r^2 + 1 = 0$$

or $r^4 - 14.42 r^2 + 25.75 = 0$

$$\therefore r^2 = 7.21 \pm \sqrt{7.21^2 - 25.75} = 7.21 \pm 5.12$$

$$r^2 = 2.09, 12.33 \text{ or } r = 1.445, 3.511^5$$

from the $\frac{z}{s}$ plot

$$\text{Select } \zeta_{\text{root}} \quad \zeta = 3.511 = \frac{b}{b_n}$$

$$f \geq 3.511 \times f_n$$

$f \geq 35.11 \text{ Hz}$ will ensure error within 2%.

QUESTION # 4 (35)

An air compressor ($M=100\text{kg}$) is supported on an elastic support with spring constant $k\text{ N/m}$ and damping constant $c\text{ Ns/m}$. The compressor has an unbalanced mass of 4 kg at a radial distance of 0.01 m from the axis of rotation. The damping ratio of the elastic support is measured as 0.12 .

- It is desired that the magnitude of force transmitted to the foundation must not exceed 150 N , when operating at a speed of 1200 rpm . Determine the spring rate of the support to limit the magnitude of force transmitted to this target value.
- The steady-state vibration response of the compressor mass.

Given $M = 100\text{ kg}$; $m_e = 4 \times 0.01 = 0.04\text{ kgm}$; $\zeta = 0.12$

$$\omega = \frac{2\pi N}{60} = \frac{2\pi \times 1200}{60} = 40\pi\text{ rad/s}$$

Input force magnitude, $F_0 = m_e \omega^2 = 0.04 \times (40\pi)^2$
 $F_0 = 631.65\text{ N}$

Q) $\therefore \frac{F_T}{F_0} \leq \frac{150}{631.65} = 0.2374 = \frac{1}{\sqrt{(1-\zeta^2)^2 + (2\zeta\zeta)^2}}$

$$1 + \zeta^4 - 2\zeta^2 + (0.24\zeta)^2 = \frac{1}{(0.2374)^2} [1 + (0.24\zeta)^2]$$

$$\zeta^4 - 1.9424\zeta^2 + 1 = 17.74 + 1.022\zeta^2$$

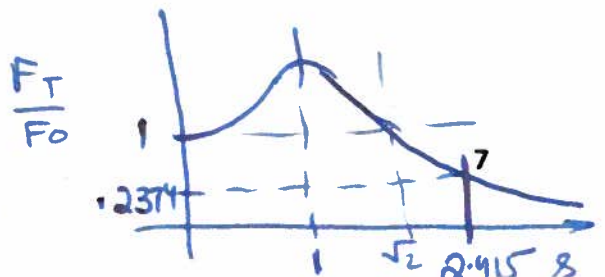
$$\zeta^4 - 2.9644\zeta^2 - 16.74 = 0$$

$$\zeta^2 = 1.4822 \pm \sqrt{1.4822^2 + 16.74} = 1.4822 \pm 4.35$$

only feasible root is $\zeta^2 = 5.83$ or $\zeta = 2.415$

$$\zeta = 2.415 = \frac{\omega}{\omega_n}; \omega_n = \frac{\omega}{2.415}$$

$$\omega_n = \frac{40\pi}{2.415} = 52.03\text{ rad/s}$$



$$\omega_n = \sqrt{\frac{k}{m}}; \quad k = M\omega_n^2 = 100(52.03)^2$$

$$k = \underline{270,786 \text{ N/m}}$$

b) Steady state response

$$x(t) = X \sin(\omega t + \varphi)$$

$$\frac{M X}{m e} = \frac{r^2}{\sqrt{(1-r^2)^2 + (2\zeta r)^2}}; \quad \zeta = 0.12; \quad r = 2.415$$

$$\frac{M X}{m e} = \frac{2.415^2}{\sqrt{(1-2.415^2)^2 + (0.24 \times 2.415)^2}} = 1.198$$

$$X = \frac{m e}{M} (1.198) = \frac{0.04}{100} (1.198) = \underline{4.8 \times 10^{-4} \text{ m}}$$

$$\varphi = \tan^{-1}\left(\frac{2\zeta r}{1-r^2}\right) = \tan^{-1}\left(\frac{0.58}{-4.83}\right) = -0.12 \text{ rad}$$

$$\varphi = \pi - 0.12 = 3.022 \text{ rad}$$



$$\underline{x(t) = 4.8 \times 10^{-4} \cos(40\pi t - 3.022) \text{ m}}$$