

AM 2811 Midterm Solns

February 27, 2015 7:15 PM

7:15
Q1

(a) Use the isomorphism $ax^2+bx+c \leftrightarrow \begin{pmatrix} a \\ b \\ c \end{pmatrix}$
 Then $1-x-2x^2 \leftrightarrow \begin{pmatrix} -2 \\ -1 \\ 1 \end{pmatrix}$, $5-4x-7x^2 \leftrightarrow \begin{pmatrix} -7 \\ -4 \\ 5 \end{pmatrix}$, $-3+x \leftrightarrow \begin{pmatrix} 0 \\ 1 \\ -3 \end{pmatrix}$

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3 = \vec{0}$$

$$\begin{bmatrix} -2 & -7 & 0 & | & 0 \\ -1 & -4 & 1 & | & 0 \\ 1 & 5 & -3 & | & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 5 & -3 & | & 0 \\ -1 & -4 & 1 & | & 0 \\ -2 & -7 & 0 & | & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 5 & -3 & | & 0 \\ 0 & 1 & -2 & | & 0 \\ 0 & 3 & -6 & | & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 5 & -3 & | & 0 \\ 0 & 1 & -2 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

So $c_3=0$, and a basis is $\left\{ \begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} -7 \\ -4 \\ 5 \end{bmatrix} \right\}$ or equivalently $\{-2x^2-x+1, -7x^2-4x+5\}$

(b) $c_1 \begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} -7 \\ -4 \\ 5 \end{bmatrix} = \begin{bmatrix} a \\ 3 \\ -4 \end{bmatrix}$

$$\begin{bmatrix} -2 & -7 & | & a \\ -1 & -4 & | & 3 \\ 1 & 5 & | & -4 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 5 & | & -4 \\ -1 & -4 & | & 3 \\ -2 & -7 & | & a \end{bmatrix}$$

$$\begin{bmatrix} 1 & 5 & | & -4 \\ 0 & 1 & | & -1 \\ 0 & 3 & | & a-8 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 5 & | & -4 \\ 0 & 1 & | & -1 \\ 0 & 0 & | & a-5 \end{bmatrix}$$

\therefore need $a=5$ for $-4+3x+a^2x^2 \in \text{span } \mathcal{S}$

(c) $\begin{pmatrix} c & d & c \\ d & c & d \end{pmatrix} = c \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} + d \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} = \text{span} \left\{ \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \right\}$

Also $c M_1 + d M_2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$

$\Rightarrow c=0, d=0$

so $\{M_1, M_2\}$ is a basis for the set

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Q2
7:33

(a) $L(\vec{u} + \vec{v}) = L(\vec{u}) + L(\vec{v})$ for $\vec{u}, \vec{v} \in V$

$L(k\vec{v}) = k L(\vec{v})$

$$L(k\vec{v}) = kL(\vec{v}) \quad \checkmark \quad \sim 1/2$$

(b) We show $\ker(L) = \{\vec{v} \in V : L(\vec{v}) = \vec{0}\}$
is a subspace of V . \checkmark

Let $\vec{0} \in V$ be the zero vector of V . \checkmark

Then $L(\vec{0} + \vec{0}) = L(\vec{0}) = 2L(\vec{0})$ so $L(\vec{0}) = \vec{0}$
and $\vec{0} \in \ker(L)$. \checkmark

Let $\vec{u}, \vec{v} \in \ker(L)$. \checkmark

Then $L(\vec{u}) = \vec{0}$, $L(\vec{v}) = \vec{0}$ \checkmark

So $L(\vec{u} + \vec{v}) = L(\vec{u}) + L(\vec{v}) = \vec{0} + \vec{0} = \vec{0}$ \checkmark

So $\vec{u} + \vec{v} \in \ker(L)$. \checkmark

Also $L(c\vec{u}) = cL(\vec{u}) = c\vec{0} = \vec{0}$ \checkmark

so $c\vec{u} \in \ker(L)$ and \checkmark

$\ker(L)$ is a subspace of V . \checkmark

(c) Here $L(u) = u_{xx} + u_{yy}$

We only need to show L is a linear operator
then use the result of (b). \checkmark

$$\begin{aligned} L(u+v) &= (u+v)_{xx} + (u+v)_{yy} \quad \checkmark \\ &= u_{xx} + v_{xx} + u_{yy} + v_{yy} \quad \checkmark \\ &= L(u) + L(v) \end{aligned}$$

$$\begin{aligned} L(ku) &= (ku)_{xx} + (ku)_{yy} \quad \checkmark \\ &= k u_{xx} + k u_{yy} \quad \checkmark \\ &= k L(u) \end{aligned} \quad \checkmark \quad 3/3$$

So L is a linear operator and by (b)
 $\ker(L)$ is a vector space.

(d) This has form $L(u) = 1$ \checkmark

So if $u=0$, then $L(0) = 1 \neq 0$

So 0 not a vector of $L(u) = 0$

and this is not a vector space. \checkmark

7:42

Q3 $7:51$

$$(a) \mathcal{Q} = \left\{ \begin{pmatrix} a & b \\ b & a \end{pmatrix} : b = 2a \right\} = \left\{ \begin{pmatrix} a & 2a \\ 2a & a \end{pmatrix} : a \in \mathbb{R} \right\}$$

3/3

$$(a) Q = \left\{ \begin{pmatrix} a & b \\ b & a \end{pmatrix} : b = 2a \right\} = \left\{ \begin{pmatrix} a & 2a \\ 2a & a \end{pmatrix} : a \in \mathbb{R} \right\} \quad 3/3$$

$$= \text{span} \left\{ \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \right\}$$

i.e. this is a VS with basis $\begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}$.

Alternatively show it's a subspace of $M_{2 \times 2}$.

Note $\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \in Q$ (set $a=0$).

Also show closure under + and scalar mult.

(b) $F = \{ f: \mathbb{R} \rightarrow \mathbb{R}, \text{ with } f(x+3) = f(x) \}$
is a subset of the VS $\mathcal{F}(\mathbb{R}, \mathbb{R})$.

The zero $f^0: z(x) = 0$ is in F since

$$z(x+3) = 0 = z(x)$$

Also if $f, g \in F$ then

$$(cf + dg)(x+3) = cf(x+3) + dg(x+3)$$

$$= cf(x) + dg(x)$$

$$= (cf + dg)(x)$$

so $cf + dg \in F$ for all $c, d \in \mathbb{R}$.

So F is a subspace.

$$(c) G = \left\{ \vec{v} \in \mathbb{R}^2 : \vec{v} = \begin{pmatrix} x \\ 0 \end{pmatrix} \text{ or } \vec{v} = \begin{pmatrix} 0 \\ y \end{pmatrix} \right\}$$

$$x, y \in \mathbb{R}$$

Note $\begin{pmatrix} 1 \\ 0 \end{pmatrix} \in G, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \in G$, but

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \notin G.$$

So G is not a subspace of \mathbb{R}^2 .

7:59

Q4 8:03

(a) $\text{rng}(B) = \text{col space}(B)$ OR Use REF(B^T)

$$\begin{matrix} \text{pivots} \\ \begin{pmatrix} 1 & -3 & -7 & 9 \\ 0 & 1 & 5 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix} \end{matrix} \left\{ \begin{array}{l} \text{rows give basis} \\ \text{for row space}(B^T) \\ \rightarrow (1, 0, 1) \\ (0, 1, 1) \\ \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\} \end{array} \right.$$

So $\text{rng}(B) = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}$

cokernel $B = \ker B^T$

$$= \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} : \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \right\}$$

4x3

$$\begin{aligned} x + z &= 0 \\ y + z &= 0 \end{aligned}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -z \\ -z \\ z \end{pmatrix} = z \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix} = \text{span} \left\{ \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix} \right\}$$

(b) $\dim \ker B + \text{rank } B = \# \text{ cols } B$

$$= 4$$

(c) First reduce C to REF.

Then $\text{rank } C = \# \text{ pivots in REF } C = r$.

We can solve for r of the pivot variables leaving the remaining variables as parametric.

There are $n - r$ remaining free variables.

$$\text{So } n - r + r = n$$

$$\text{or } \dim \ker C + \text{rank } C = n.$$

8:16.

5:39 Q5

(a) $\|f\| = \sqrt{\langle f, f \rangle} = \sqrt{\int_{-1}^{+1} f(x) f(x) e^x dx}$

3/3.

(b) $|\langle f, g \rangle| \leq \|f\| \|g\|$

$$\left| \int_{-1}^{+1} f(x) g(x) e^x dx \right| \leq \sqrt{\int_{-1}^{+1} f(x)^2 e^x dx} \sqrt{\int_{-1}^{+1} g(x)^2 e^x dx}$$

4/4

(c) $\left| \int_{-1}^{+1} x e^{-x} e^x dx \right| = \left| \int_{-1}^{+1} x dx \right| = \left| \left[\frac{x^2}{2} \right]_{-1}^{+1} \right| = 0$

$$\begin{aligned} \int_{-1}^{+1} x^2 e^x dx &= [x^2 e^x]_{-1}^{+1} - \int_{-1}^{+1} 2x e^x dx \\ &= e - e^{-1} - 2 \left[[x e^x]_{-1}^{+1} - \int_{-1}^{+1} e^x dx \right] \\ &= e - e^{-1} - 2 \{ \cancel{e} + e^{-1} - (\cancel{e} - e^{-1}) \} \\ &= e - 5e^{-1} \end{aligned}$$

+1 Calc. f's

+1 $\int_{-1}^{+1} x e^x dx = 0$

+2 other 2 f's

+2 other 2 f's.

$$= e^{-5e^{-1}}$$

$$\int_{-1}^{+1} e^{-2x} e^x dx = \int_{-1}^{+1} e^{-x} dx = [-e^{-x}]_{-1}^{+1} = e - e^{-1}$$

Cauchy Schwarz is:
 $0 \leq \sqrt{e - 5e^{-1}} \sqrt{e - e^{-1}}$ which is correct

(d) Not necessarily true. ✓
 E.g. consider $\begin{pmatrix} 1 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} -1 \\ 1 \end{pmatrix} = 0$ in the dot product ✓
 But in a weighted inner product
 $\langle \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}, \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \rangle = w_1 u_1 v_1 + w_2 u_2 v_2$
 $\langle \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \end{pmatrix} \rangle = w_1 (-1) + w_2 (1) = 0$ 3/3
 only if $w_2 - w_1 = 0$ ✓

Q6 6:00 pm

(a) $c_1 \sin(x) + c_2 \sin(2x) + c_3 \sin(3x) + \dots = f(x)$
 $\Rightarrow \langle \sin(mx), c_1 \sin(x) + c_2 \sin(2x) + \dots \rangle = \langle \sin(mx), f(x) \rangle$
 $c_m \langle \sin(mx), \sin(mx) \rangle = \langle \sin(mx), f(x) \rangle$
 Since $\langle \sin(mx), \sin(nx) \rangle = 0$ for $m \neq n$ ✓
 $\Rightarrow c_m = \frac{\langle \sin(mx), f(x) \rangle}{\langle \sin(mx), \sin(mx) \rangle}$ ✓ 4/4 (*)

(b) Suppose $c_1 \sin(x) + c_2 \sin(2x) + c_3 \sin(3x) + \dots = 0$
 Then by (*)

$$c_m = \frac{\langle \sin(mx), 0 \rangle}{\langle \sin(mx), \sin(mx) \rangle} = 0$$

So $\sin(x), \sin(2x), \dots$ are linearly independent. 2/2

6:06 pm.