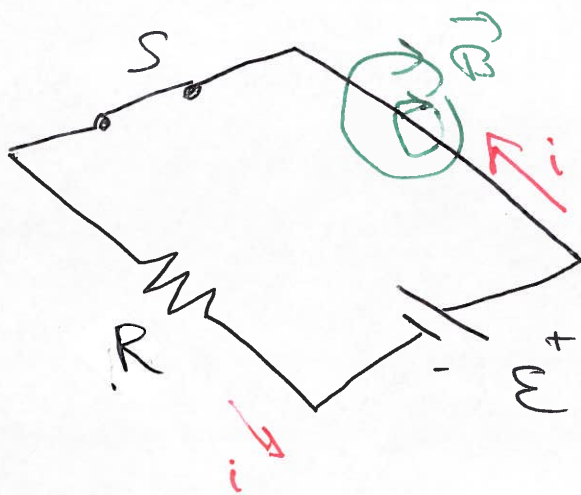


Self induction and inductance



When the switch is closed  $\Rightarrow i = \underline{\underline{E/R}}$

$\Rightarrow$  not immediately

$i \uparrow \Rightarrow B \uparrow \Rightarrow$  change in  $\Phi_B$  over the loop of the circuit

$\Rightarrow$  induced emf in the circuit

$\Rightarrow$  induced current would create  $\vec{B}_{ind}$  opposing to the change in  $\vec{B}$

induced emf is opposed to the original  
emf of the battery

⇒ consequence: gradual increase of  $i$

// This is the same phenomenon as the back  
emf in a motor.

⇒  $\mathcal{E}_L$  : self. induced emf

$$// \mathcal{E}_L = -L \frac{di}{dt}$$

proportional to the  
time rate of change of  
 $i$

$L$ : proportionality constant = inductance

↳ geometry of the loop + physical characteristics

from Faraday's law

$$\mathcal{E}_L = -N \frac{d\Phi_B}{dt}$$

↓  
N loops

⇒  $L di = N d\Phi_B$

2

$$\Rightarrow L = \frac{N \Phi_B}{i}, \quad L = - \frac{\epsilon_L}{di/dt}$$

of:  $R = \Delta V / I$

R: measure of opposition to current

L: measure of opposition to a change in current

$$SI = 1 \text{ Henry} = 1 \text{ H} = 1 \text{ V} \cdot \text{s} / \text{A}$$

### Inductance of a solenoid

Uniform solenoid of  $N$  turns and length  $l$

$l \gg$  radius of the cylinder

$\Rightarrow \vec{B}$  uniform inside the solenoid

$$\Rightarrow B = \mu_0 n i = \mu_0 \frac{N}{l} i$$

$$\Phi_B = \int_S \vec{B} \cdot d\vec{S} = B \int_S ds = \mu_0 \frac{N}{l} i S$$

uniform

$$\Rightarrow L = \frac{N \Phi_B}{i} = \mu_0 \frac{N^2}{\ell} S$$

Note that  $N = n\ell$

$$\Rightarrow L = \mu_0 \frac{(n\ell)^2}{\ell} S = \mu_0 n^2 S\ell$$

$\swarrow$   
 Volume of  
 the solenoid  $V$

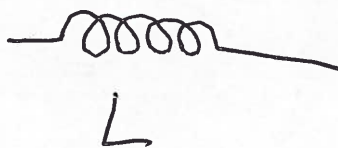
$$\Rightarrow L = \mu_0 n^2 V$$

## RL circuits

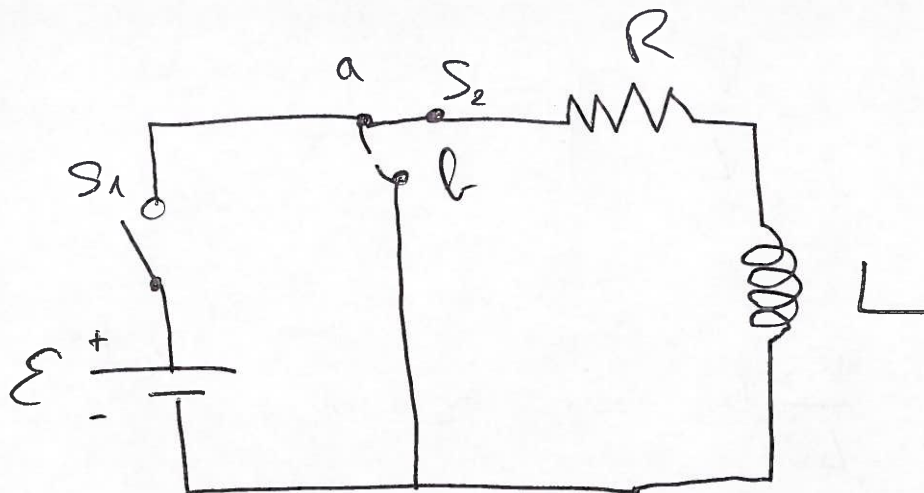
Inductance of the wires  $\Rightarrow$  neglect

Element of circuit with large inductance

$\Rightarrow$  Inductor



$\Rightarrow$  "sluggish" circuits.



$S_1$  open for  $t < 0$ , closed at  $t = 0$

$i \uparrow$  and a back emf is created in the solenoid.

$\Rightarrow$  Kirchhoff's rule

$$\mathcal{E} - iR - L \frac{di}{dt} = 0$$

To solve this  $\Rightarrow$  change of variable

$$x = \mathcal{E}/R - i \quad \Rightarrow \quad dx = -di$$

$$\Rightarrow \quad x + \frac{L}{R} \frac{dx}{dt} = 0$$

$$\int_{x_0}^x \frac{dx}{x} = -\frac{R}{L} \int_0^t dt$$

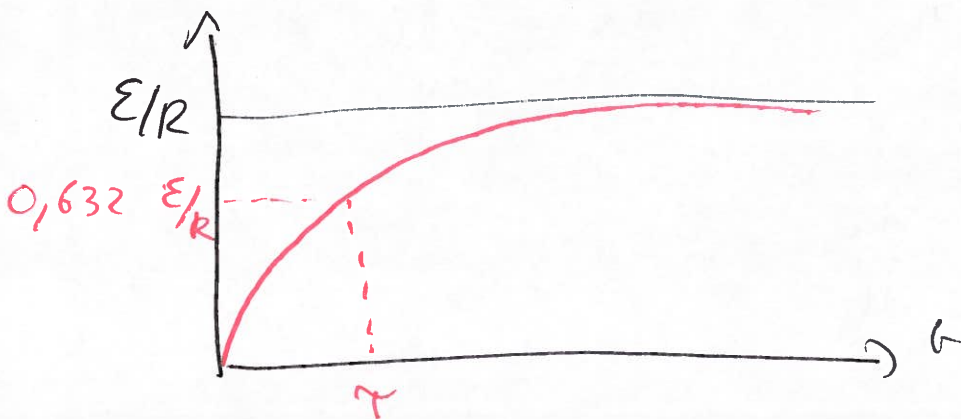
$$\ln \frac{x}{x_0} = -\frac{R}{L} t \Rightarrow x = x_0 e^{-R/L t}$$

$$\text{at } t=0, i=0 \Rightarrow x = \mathcal{E}/R$$

$$\Rightarrow \frac{\mathcal{E}}{R} - i = \frac{\mathcal{E}}{R} e^{-R/L t}$$

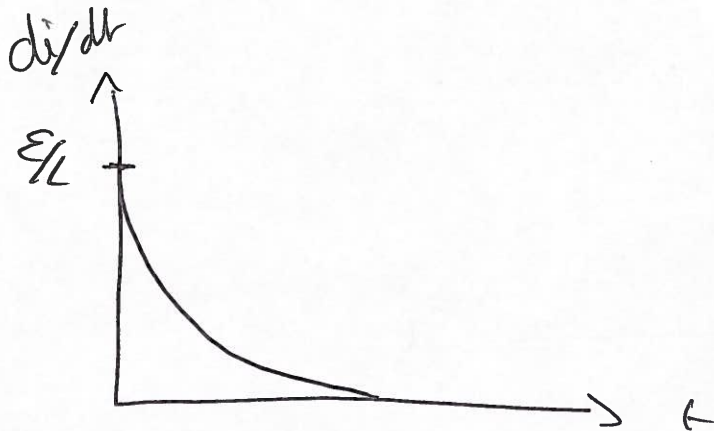
$$\Rightarrow \parallel i(t) = \frac{\mathcal{E}}{R} (1 - e^{-Rt/L})$$
$$= \frac{\mathcal{E}}{R} (1 - e^{-t/\tau})$$

time constant  $\tau = L/R$

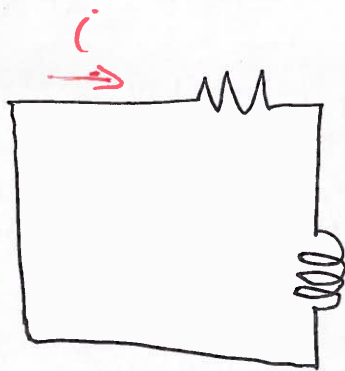


We have  $\frac{di}{dt} = \frac{\mathcal{E}}{L} e^{-t/\tau}$

4



\*  $i = \mathcal{E}/R$  (equilibrium),  $S_2$  switch from a to b  
 $\Rightarrow$  the battery is eliminated



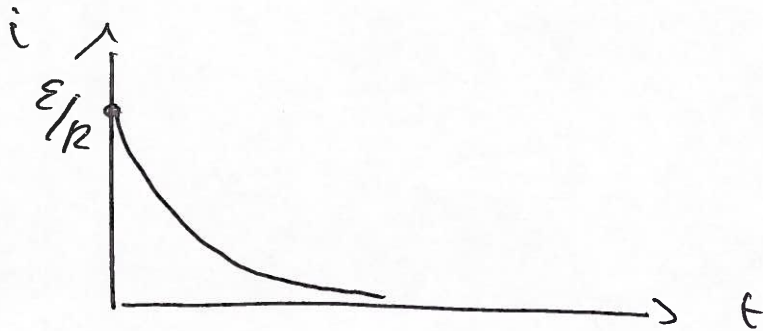
at  $t=0$ ,  $i = \mathcal{E}/R$   
 $I_0$

$$\Rightarrow iR + L \frac{di}{dt} = 0$$

$$\Rightarrow \frac{di}{i} = - \frac{R}{L} dt$$

$$i = I_0 e^{-R/L t}$$

$$i(t) = \frac{\mathcal{E}}{R} e^{-t/\tau}$$



Note if  $L$  really small  $\Rightarrow$  no inductance effect

$\Rightarrow \tau$  small

if no inductor  $\Rightarrow$   $i$  would increase  $\uparrow$  or decrease  $\downarrow$  immediately to  $\mathcal{E}/R$  or to 0

$\Rightarrow$  the presence of  $L$  slows down the process

## Energy in a magnetic field

$$\mathcal{E} = Ri + L \frac{di}{dt}$$

( $S_1$  on a,  $S_2$  just closed)

$\times i$   
 $\downarrow$   
 $i\mathcal{E} =$   
 rate of energy supplied by the battery

$$= Ri^2 + L i \frac{di}{dt}$$

$\swarrow$  rate of energy (power) delivered to the resistor

$U_B \Rightarrow$  energy stored in the inductor at any time 5

Rate of energy  $\Rightarrow \frac{dU_B}{dt}$

$$\Rightarrow \frac{dU_B}{dt} = L i \frac{di}{dt}$$

$$\Rightarrow dU_B = L i di$$

$$\Rightarrow U_B = \int dU_B = \int_0^i L i di = L \int_0^i i di$$

$\underbrace{\hspace{10em}}_{1/2 i^2}$

$$\Rightarrow U_B = \frac{1}{2} L i^2$$

Energy stored in the magnetic field of the inductor

of : energy stored in the electric field of a capacitor

$$\parallel U_E = \frac{1}{2} C (\Delta V)^2$$



What happens to the energy in the inductor?

6

$$i(0) = I_i = \mathcal{E}/R$$

at  $t=0$   $S_c$  switched to  $b$

internal energy of the resistor  $\frac{dE_{int}}{dt} = P = i^2 R$

$$\text{with } i = \underbrace{I_i}_{\mathcal{E}/R} e^{-t/\tau} = I_i e^{-Rt/L}$$

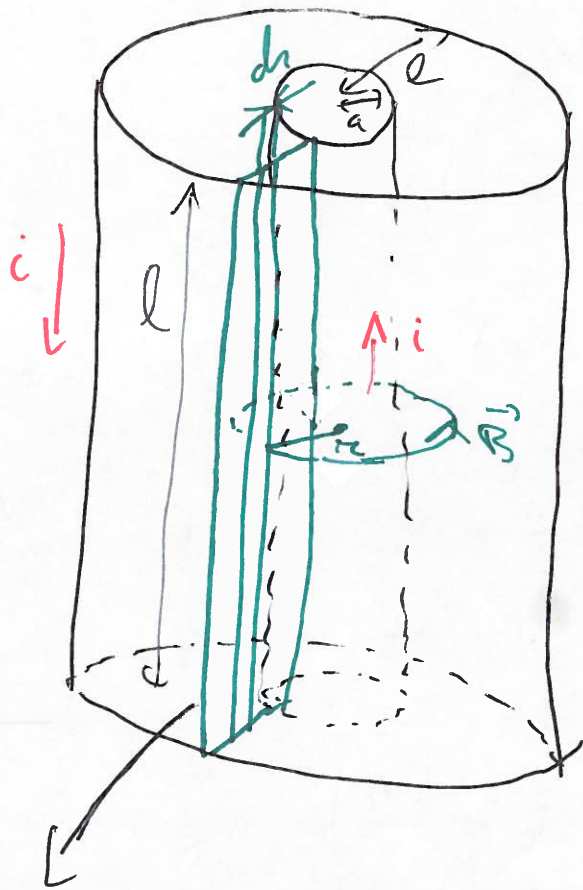
$$\begin{aligned} \Rightarrow \frac{dE_{int}}{dt} &= (I_i e^{-Rt/L})^2 R \\ &= I_i^2 R e^{-2Rt/L} \end{aligned}$$

$$E_{int} = \int_0^{+\infty} I_i^2 R e^{-2Rt/L} dt$$

$$= R I_i^2 \int_0^{+\infty} e^{-2Rt/L} dt$$

$$= I_i^2 R \left( \frac{L}{2R} \right) = \frac{1}{2} L I_i^2 = \text{initial magnetic energy stored in the inductor}$$

# Inductance Coaxial cable



Magnetic field  
between the two  
cable (Ampere law)

↓  
depends on  $r$  only

$$\Rightarrow B = \frac{\mu_0 i}{2\pi r}$$

Magnetic field outside ( $r > b$ )

$B = 0$  (Ampere law)

Let's consider this loop "closed" at the extremity of  
the cable

Flux through this loop

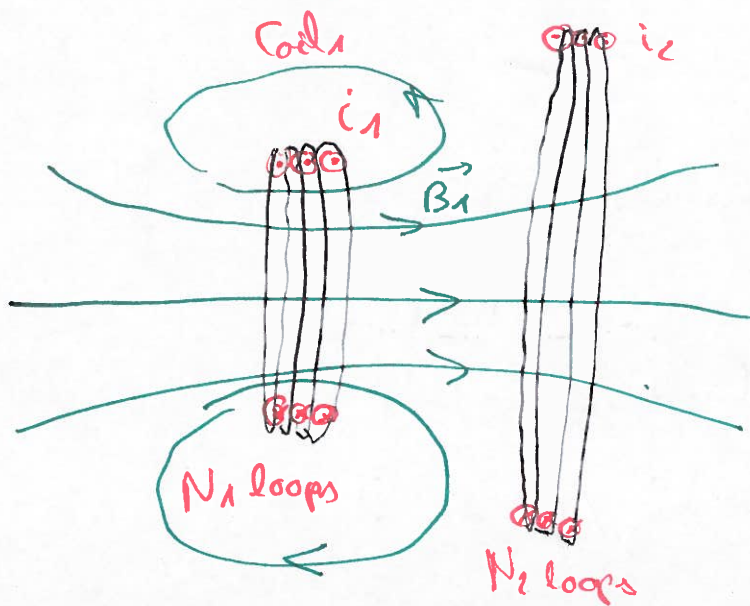
$$\Phi_B = \int_S \vec{B} \cdot d\vec{S} = \int_a^b \frac{\mu_0 i}{2\pi r} l dr$$

$$= \frac{\mu_0 i l}{2\pi} \int_a^b \frac{dr}{r} = \frac{\mu_0 i l}{2\pi} \ln(b/a)$$

By definition  $L = \frac{\Phi_B}{i} = \frac{\mu_0 l}{2\pi} \ln(b/a)$

## Mutual inductance

7



Influence of the magnetic flux created by coil 1  
on coil 2

$\Phi_{12}$  : flux of magnetic field  $\vec{B}_1$  created by current  $i_1$   
in coil 1 , in coil 2

## Mutual inductance

$$\mathcal{M}_{12} = \frac{N_2 \Phi_{12}}{i_1}$$

Faraday law on coil 2 :

$$\mathcal{E}_2 = - N_2 \frac{d\Phi_{12}}{dt} = - N_2 \frac{d}{dt} \left( \frac{\mathcal{M}_{12} i_1}{N_2} \right)$$

$$\Rightarrow \mathcal{E}_2 = - \mathcal{M}_{12} di_1 / dt$$

$\mathcal{E}_2$  : emf induced on coil 2 by current  
in coil 1

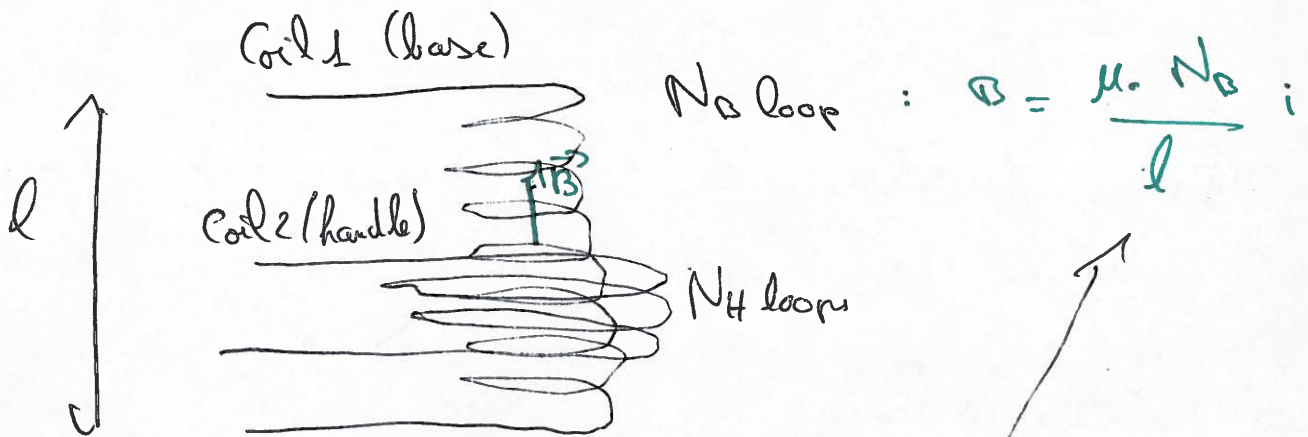
Similarly:  $\mathcal{E}_1 = -\frac{d\Phi_{21}}{dt}$

↳ Mutual inductance:  $\underline{\underline{\mathcal{M}_{12} = \mathcal{M}_{21} = \mathcal{M}}}$

$$\mathcal{E}_2 = -\frac{d\Phi_{12}}{dt}$$

$$\mathcal{E}_1 = -\frac{d\Phi_{21}}{dt}$$

eg: "Wireless" battery charger

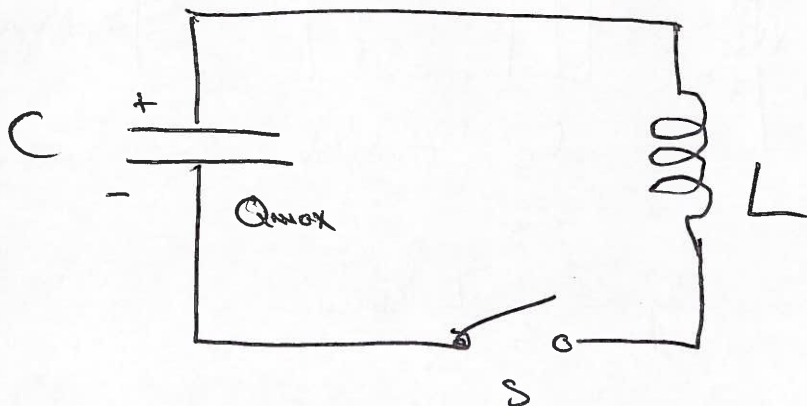


$$\mathcal{M} = \frac{N_H \Phi_{BH}}{i} = \frac{N_H B S}{i}$$

$$\mathcal{M} = \mu_0 \frac{N_H N_B}{l} S$$

$\Rightarrow$  used to charge wireless device

# Oscillations in an LC circuits



C fully charged for  $t < 0$

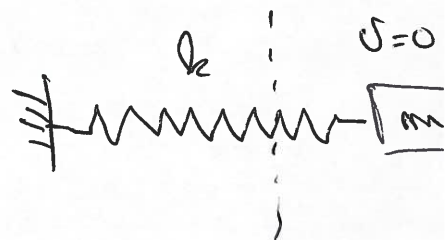
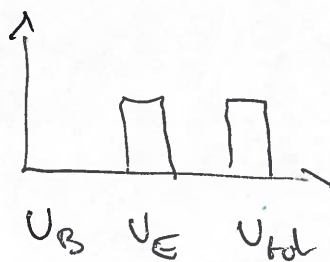
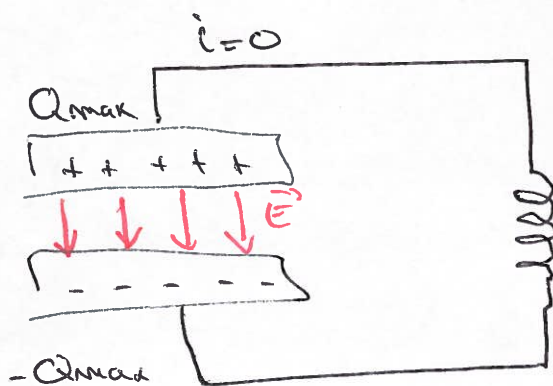
Open for  $t < 0$  at  $t = 0$   $S = \text{close}$

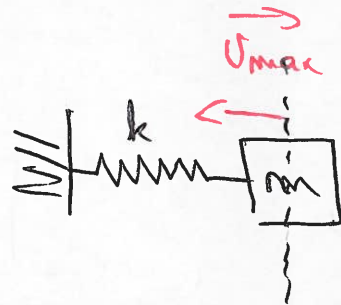
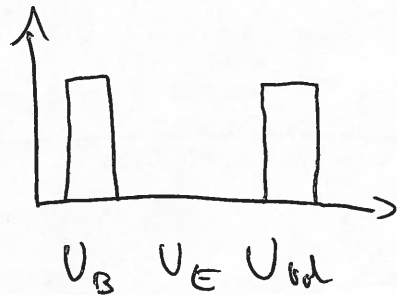
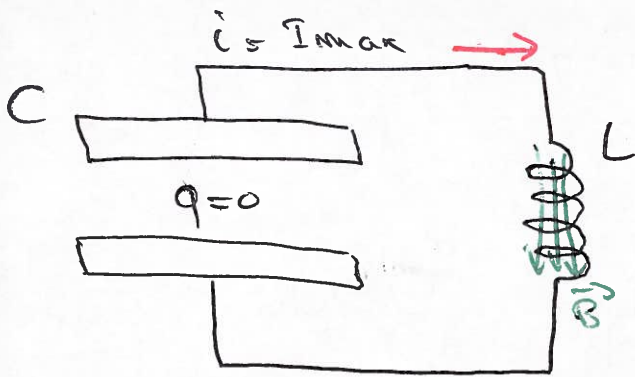
We assume :

- no resistance, no energy transformed to internal energy
- no radiation

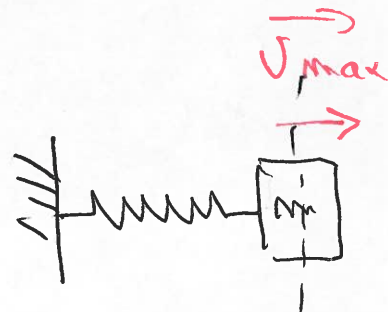
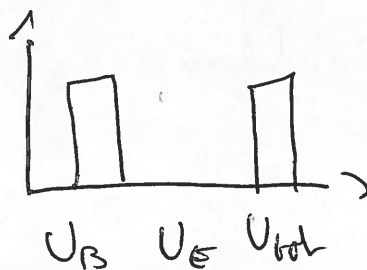
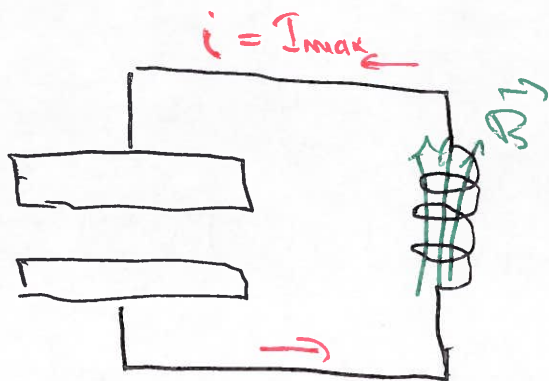
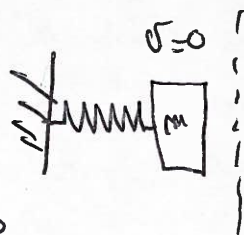
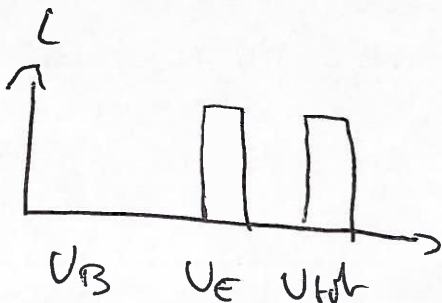
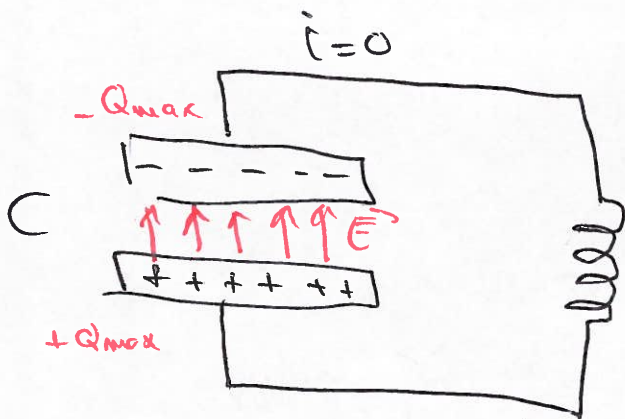
$\Rightarrow$  Energy conservation

$$\left. \begin{aligned} \text{at } t=0 \quad U_E &= \frac{1}{2} \frac{Q_{\max}^2}{C} \\ U_B &= 0 \end{aligned} \right\} U_{\text{tot}} = U_E + U_B$$





$$U_B = \frac{1}{2} L I_{max}^2$$



$\Rightarrow$  oscillation

At any time

$$U_{\text{tot}} = U_E + U_B = \frac{q^2}{2C} + \frac{1}{2} Li^2 = \frac{Q_{\text{max}}^2}{2C}$$

initial condition

$$U_{\text{tot}} = \text{constant} \Rightarrow \frac{dU_{\text{tot}}}{dt} = 0$$

$$\frac{d}{dt} \left( \frac{q^2}{2C} + \frac{1}{2} Li^2 \right) = \frac{q}{C} \frac{dq}{dt} + Li \frac{di}{dt} = 0$$

$$i = dq/dt \text{ by definition} \Rightarrow di/dt = d^2q/dt^2$$

$$\Rightarrow \frac{q}{C} + L \frac{di}{dt} = 0$$

$$\Rightarrow \frac{q}{C} + L \frac{d^2q}{dt^2} = 0$$

$$\Rightarrow \frac{d^2q}{dt^2} = -\frac{1}{LC} q \Rightarrow \text{analogous to simple harmonic motion}$$

$$d: \quad \frac{d^2x}{dt^2} = -\frac{k}{m} x = -\omega^2 x$$

$k =$  spring constant,  $m =$  mass

$$\Rightarrow \text{solution: } x = A \cos(\omega t + \phi)$$

$$\omega = \sqrt{k/m}, \quad A \text{ and } \phi \text{ depend on initial conditions.}$$

$$\Rightarrow \parallel q = Q_{\max} \cos(\omega t + \phi)$$

natural

$$\omega = 1/\sqrt{LC}$$

angular frequency of the oscillation

$$(\omega = 2\pi f)$$

frequency in Hz

$$i = \frac{dq}{dt} = -\omega Q_{\max} \sin(\omega t + \phi)$$

$$\text{at } t = 0, \quad i = 0 \Rightarrow \underline{\underline{\phi = 0}}$$

$$\parallel q = Q_{\max} \cos(\omega t), \quad i = -\overbrace{\omega Q_{\max}}^{I_{\max}} \sin \omega t$$

$$\omega = 1/\sqrt{LC}$$

$$U_{\text{tot}} = U_E + U_B$$

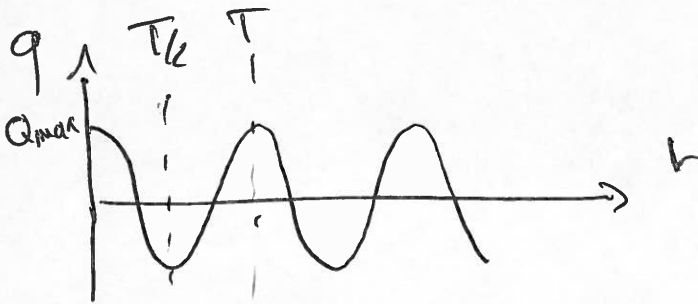
$$= \frac{Q_{\text{max}}^2}{2C} \cos^2 \omega t + \frac{1}{2} L I_{\text{max}}^2 \sin^2 (\omega t)$$

⇒ what happens when  $q=0$  and  $i=0$

$$\Rightarrow \left\| \frac{Q_{\text{max}}^2}{2C} = \frac{1}{2} L I_{\text{max}}^2 \right.$$

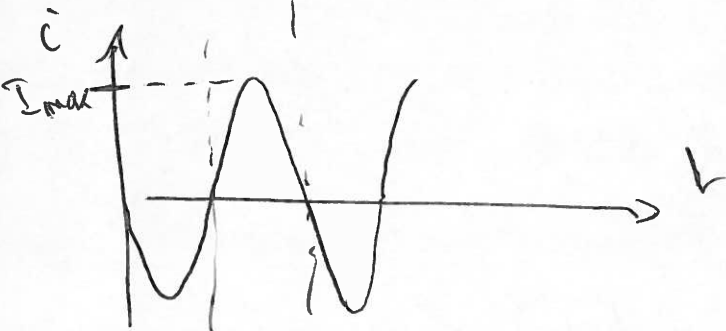
$$\Rightarrow U_{\text{tot}} = \frac{Q_{\text{max}}^2}{2C} (\underbrace{\cos^2 \omega t + \sin^2 \omega t}_{= 1}) = \frac{Q_{\text{max}}^2}{2C}$$

⇒ ideal situation



$$T = 2\pi / \omega, \quad \omega = 2\pi / T$$

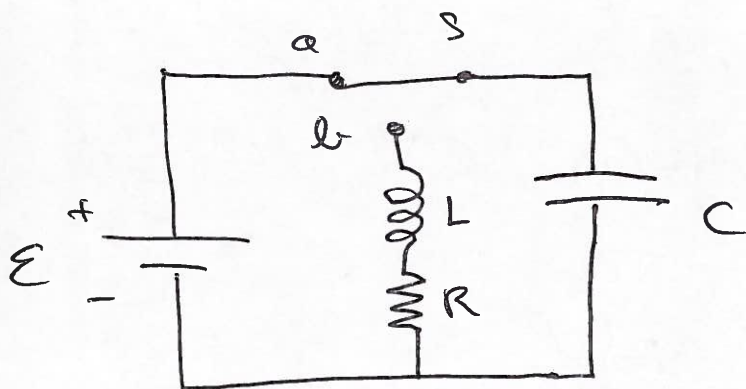
$$T = 1/f, \quad \omega = 2\pi / f$$



## The RLC circuit

↳ One need to take into account the presence of resistor in the circuit

⇒ energy transformed to internal energy in the resistor (heat)



at  $t = 0$ , C is fully charged  $U_E = \frac{Q_{\max}^2}{2C}$

⇒ switch on a

dissipation of energy in the resistor

$$\frac{dU_{\text{oh}}}{dt} = -i^2 R$$

↓  
decrease of energy

$$U_{\text{oh}} = U_E + U_R = \frac{1}{2} q^2 / C + \frac{1}{2} Li^2$$

$$\Rightarrow \frac{dU_{tot}}{dt} = \frac{q}{c} \frac{dq}{dt} + Li \frac{di}{dt} = -i^2 R$$

$$\dot{i} = dq/dt$$

$$Li \frac{d^2q}{dt^2} + Ri^2 + \frac{q}{c} i = 0$$

division by  $i$

$$L \frac{d^2q}{dt^2} + Ri + \frac{q}{c} = 0$$

$$L \frac{d^2q}{dt^2} + R \frac{dq}{dt} + \frac{q}{c} = 0$$

$\Rightarrow$  damped harmonic oscillator

cf:  $m \frac{d^2x}{dt^2} + b \frac{dx}{dt} + kx = 0$   
 damping coefficient (friction, air resistance)

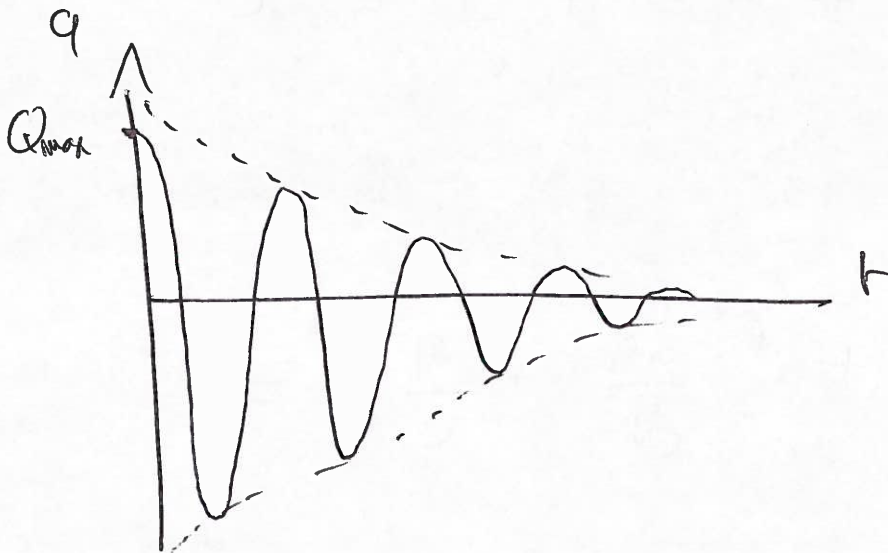
$$q = Q_{\max} e^{-Rt/2L} \cos \omega_d t$$

$$\text{with } \omega_d = \left( \frac{1}{LC} - \left( \frac{R}{2L} \right)^2 \right)^{1/2}$$

of block spring in a viscous medium

$$R \ll \sqrt{4L/c}$$

$$\omega_d \cong \sqrt{1/LC}$$



Critical resistance  $R_c = \sqrt{4L/c}$  no oscillation  
critically damped

$R > R_c \Rightarrow$  overdamped

$$q \leftrightarrow x$$

$$i \leftrightarrow Jx$$

$$\Delta V \leftrightarrow F_x \text{ (force)}$$

$$R \leftrightarrow b \text{ viscous damping coeff}$$

$$C \leftrightarrow 1/k$$

$$L \leftrightarrow m$$

