

Assignment #3

Due date: 21/11/2016

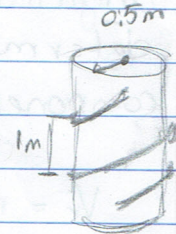
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Problem 12-183.

$$r = 0.5 \text{ m}, \theta = 0.5t^3 \text{ rad}, z = (2 - 0.2t^2) \text{ m}$$

V and a at $\theta = 2\pi \text{ rad}$



lets start by finding all $\dot{z}, \ddot{z}, \dot{r}, \ddot{r}, \dot{\theta}, \ddot{\theta}$

$$z = 2 - 0.2t^2, \quad \dot{z} = -0.4t = v_z, \quad \ddot{z} = -0.4 = a_z$$

$$r = 0.5, \quad \dot{r} = 0, \quad \ddot{r} = 0$$

$$\theta = 0.5t^3, \quad \dot{\theta} = 1.5t^2, \quad \ddot{\theta} = 3t$$

$$v_r = \dot{r} = 0, \quad v_\theta = r\dot{\theta} = 0.5(1.5t^2), \quad v_\theta = 0.75t^2$$

$$a_r = (\dot{v}_r - r\dot{\theta}^2) = (0 - 0.5(1.5t^2)^2) = a_r = -1.125t^4$$

$$a_\theta = (r\ddot{\theta} + 2\dot{r}\dot{\theta}) = (0.5(3t) + 2(0)(1.5t^2)) = a_\theta = 1.5t$$

Since we have to include z in our calculation we define \dot{z} as being v_z and \ddot{z} to be a_z

$$V = \sqrt{v_r^2 + v_\theta^2 + v_z^2}, \quad a = \sqrt{a_r^2 + a_\theta^2 + a_z^2}$$

at instant $\theta = 2\pi \text{ rad}, t =$

$$2\pi = 0.5t^3, \quad 4\pi = t^3, \quad \sqrt[3]{4\pi} = t$$

$$V = \sqrt{0 + (0.75t^2)^2 + (-0.4t)^2} = \sqrt{0.5625t^4 + 0.16t^2}$$

$$\sqrt{1.125t^4 + 0.16t^2} = \sqrt{0.5625(3\sqrt[3]{4\pi})^4 + 0.16(3\sqrt[3]{4\pi})^2}$$

$$t^s = \sqrt{16.434 + 0.865} \quad V = 4.159 \text{ m/s}$$

magnitude = no directions ?

$$a = \sqrt{(-1.125t^4)^2 + (1.5t)^2 + (-0.4)^2}$$

$$a = \sqrt{1.265625t^8 + 2.25t^2 + 0.16} =$$

$$a = \sqrt{1.265625(3\sqrt[3]{4\pi})^8 + 2.25(3\sqrt[3]{4\pi})^2 + 0.16}$$

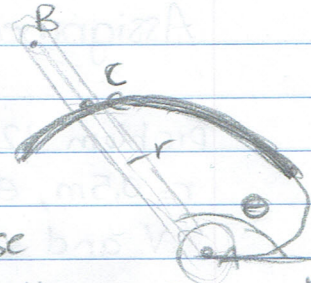
$$a = \sqrt{1080.268 + 12.162 + 0.16}$$

$$a = 33.054 \text{ m/s}^2 \leftarrow \text{magnitude} = \text{no directions} ?$$

problem 12-186.

$$r = a\theta$$

angular velocity = constant at $\dot{\theta}$
determine the radial and transverse
components of velocity and acceleration of the pin



$$V_r = \dot{r} \quad V_\theta = r\dot{\theta} \quad a_r = (\ddot{r} - r\dot{\theta}^2) \quad a_\theta = (r\ddot{\theta} + 2\dot{r}\dot{\theta})$$
$$r = a\theta \quad \dot{r} = a\dot{\theta} \quad \ddot{r} = a\ddot{\theta} = 0$$
$$\dot{\theta} = C \quad \ddot{\theta} = 0 \quad \ddot{\theta} = 0$$

Hence, the velocities are

$$V_r = \dot{r} = a\dot{\theta} \quad V_\theta = r\dot{\theta} = a\theta\dot{\theta}$$
$$V_r = a\dot{\theta} \quad V_\theta = a\theta\dot{\theta}$$

Also, the accelerations are

$$a_r = \ddot{r} - r\dot{\theta}^2 = 0 - a\theta\dot{\theta}^2 \quad a_r = -a\theta\dot{\theta}^2$$
$$a_\theta = r\ddot{\theta} + 2\dot{r}\dot{\theta} = 0 + 2(a\dot{\theta})(\dot{\theta}) \quad a_\theta = 2a\dot{\theta}^2$$

Therefore:

$$V_r = a\dot{\theta} \quad V_\theta = a\theta\dot{\theta}$$
$$a_r = -a\theta\dot{\theta}^2 \quad a_\theta = 2a\dot{\theta}^2$$

problem 15.69

$$V = 80 \text{ km/h}$$

$$d = 560 \text{ mm} = 0,56 \text{ m}$$

$$r = 0,28 \text{ m}$$

$$\rightarrow V_A = 80 \text{ km/h} = 22,22 \text{ m/s}$$

$$\rightarrow V_C = 0 \text{ m/s}$$

$$\omega = \frac{V_A}{r} = \frac{22,22 \text{ m/s}}{0,28 \text{ m}} = 79,3571 \text{ rad/s} \downarrow$$

$$V_{B/A} = V_{D/A} = V_{E/A} = r\omega \\ = (0,28 \text{ m})(79,3571 \text{ rad/s}) = 22,22 \frac{\text{m}}{\text{s}}$$

$$V_B = V_A + V_{B/A} = (22,22 \text{ m/s} \rightarrow) + (22,22 \text{ m rad/s})$$

$$\rightarrow V_B = 44,44 \text{ m rad/s}$$

$$V_D = V_A + V_{D/A} =$$

$$V_{D/A} = 22,22 \frac{\text{m}}{\text{s}}$$

$$\nearrow 30^\circ$$

$$22,22 \sin 30 = 11,11$$

$$22,22 \cos 30 = 19,24$$

$$V_{Dx} = 22,22 + 19,24 = 41,46 \text{ m/s}$$

$$V_{Dy} = 11,11 \text{ m/s}$$

$$\sqrt{41,46^2 + 11,11^2} = 42,92 \text{ m/s}$$

$$\theta = \tan^{-1} \frac{11,11}{42,92 \text{ m/s}} = \theta = 14,51^\circ$$

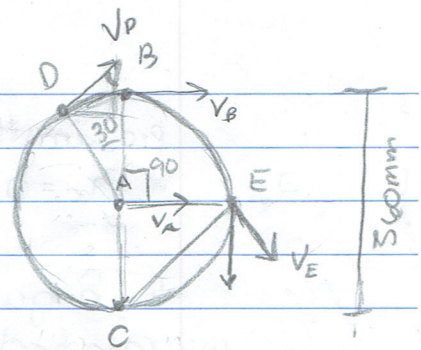
$$\rightarrow V_D = 42,92 \text{ m/s} \nearrow 14,51^\circ$$

$$V_E = V_A + V_{E/A} = 22,22 \text{ m/s} \rightarrow + 22,22 \text{ m/s} \downarrow$$

$$\sqrt{22,22^2 + 22,22^2} = 31,42 \text{ m/s}$$

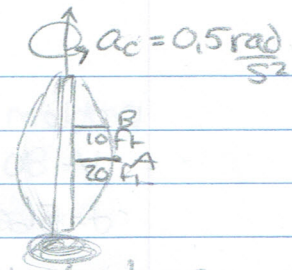
$$\theta = \tan^{-1} \frac{22,22}{22,22} \quad \theta = 45^\circ$$

$$\rightarrow V_E = 31,42 \text{ m/s} \searrow 45^\circ$$



Problem 16-19.

$$\alpha_c = 0.5 \text{ rad/s}^2$$



The angular velocity of the blade after blade has rotated $2(2\pi) = 4\pi$ rad.

$$\omega^2 = \omega_0^2 + 2\alpha_c(\theta - \theta_0)$$

$$\omega^2 = 0^2 + 2(0.5)(4\pi - 0)$$

$$\omega = 3.545 \text{ rad/s}$$

$$\rightarrow V_A = \omega r_A = 3.545(20) = 70.9 \text{ ft/s}$$

$$\rightarrow V_B = \omega r_B = 3.545(10) = 35.45 \text{ ft/s}$$

Need tangential and normal components of acceleration.

$$(a_T)_A = \alpha r_A = 0.5(20) = 10 \text{ ft/s}^2$$

$$(a_n)_A = \omega^2 r_A = (3.545)^2(20) = 251.34 \text{ ft/s}^2$$

$$(a_T)_B = \alpha r_B = 0.5(10) = 5 \text{ ft/s}^2$$

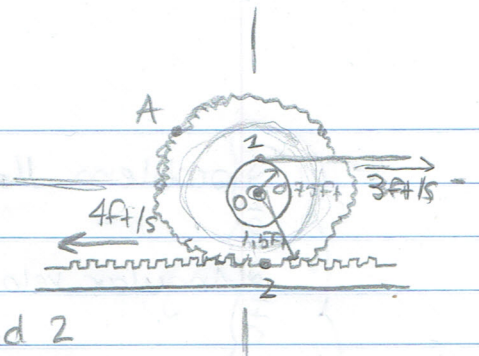
$$(a_n)_B = \omega^2 r_B = (3.545)^2(10) = 125.67 \text{ ft/s}^2$$

magnitude of the acceleration of point A and B

$$a_A = \sqrt{(a_T)_A^2 + (a_n)_A^2} = \sqrt{10^2 + 251.34^2} = 251.54 \text{ ft/s}^2$$

$$a_B = \sqrt{(a_T)_B^2 + (a_n)_B^2} = \sqrt{5^2 + 125.67^2} = 125.77 \text{ ft/s}^2$$

problem 16-59



Angular velocity:

$r_{1/2}$ = distance between point 1 and 2

$$r_{1/2} = 1.50 \text{ ft} + 0.75 \text{ ft} = 2.25 \text{ ft}$$

$$V_1 = V_2 + \omega \times r_{1/2}$$

$$3\bar{i} = -4\bar{i} + \omega \bar{k} \times 2.25 \text{ ft} \bar{j}$$

$$\omega \bar{k} \times 2.25 \bar{j} = \begin{vmatrix} 0 & 0 & \omega \\ 0 & 2.25 & 0 \end{vmatrix} = -2.25\omega \bar{i}$$

$$3\bar{i} = -4\bar{i} - 2.25\omega \bar{i}$$

$$7 = -2.25\omega$$

$$\omega = -3.111 \text{ rad/s}$$

$$V_0 = V_2 + \omega \times r_{0/2}$$

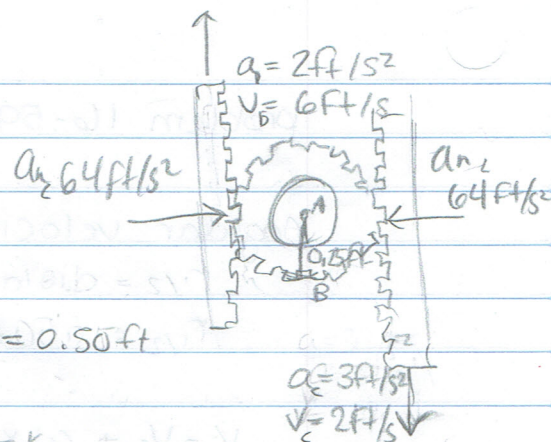
$$V_0 = -4\bar{i} + -3.111 \bar{k} \times 1.5\bar{j}$$

$$3.111 \bar{k} \times 1.5\bar{j} = \begin{vmatrix} 0 & 0 & -3.111 \\ 0 & 1.5 & 0 \end{vmatrix} = 4.666\bar{i}$$

$$V_0 = -4\bar{i} + 4.666\bar{i} = 0.666\bar{i}$$

$$V_0 = 0.666 \text{ ft/s}$$

Ans $\bar{a}_A = -0.5j \text{ ft/s}^2$, $\bar{a}_B = (-2.5i + 63.5j) \text{ ft/s}^2$



problem 16-127.

Angular velocity: $\omega = \frac{v_B}{r_{B/C}} - \frac{v_C}{r_{C/D}}$

$\frac{6}{r_{B/C}} = \frac{2}{r_{C/D}}$ where $r_{B/C} + r_{C/D} = 0.50 \text{ ft}$

$r_{B/C} = \frac{2r_{C/D}}{6}$ $r_{C/D} = 2(0.5 - r_{C/D})$

$r_{C/D} = \frac{1 - 2r_{C/D}}{6}$ $r_{C/D} = \frac{1}{6} - \frac{2}{3}r_{C/D}$ $r_{C/D} + \frac{2}{3}r_{C/D} = \frac{1}{6}$

$1.33 r_{C/D} = \frac{1}{6}$ $r_{C/D} = 0.125 \text{ ft}$ $r_{B/C} = 0.375 \text{ ft}$

thus $\omega = \frac{6}{0.375} - \frac{2}{0.125} = 16 \text{ rad/s}$

$a_{cm} = 16^2(0.125) = 64i$

$a_A = a_C + \alpha R + \omega^2 R$

$a_A = a_C + \alpha R_{AC} - \omega^2 R_{AC}$

$a_A = a_C + \alpha R_{AC} - \omega^2 R_{AC}$

$64i + 2j = -64i - 3j + (-\alpha k) \times 0.5j - 16^2 \cdot 1(-0.5i)$

$64i + 2j = -64i - 3j - \alpha k \times 0.5j + 128i$

$-\alpha k \times 0.5j$	i	j	k	$i(0-0) - j(0-0.5\alpha)$
	0	0	$-\alpha$	$= +0.5\alpha j$
	-0.5	0	0	

$64i + 2j = -64i + 3j + 0.5\alpha + 128i$ $i = \text{cancel out}$

$2 = -3 + 0.5\alpha = 5 = 0.5\alpha$ $\alpha = 10 \text{ rad/s}^2$

$a_A = a_C + \alpha \times R_{AC} - \omega^2 R_{AC}$

$a_A = -64i - 3j + (-10k) \times (-0.25j) - 16^2(-0.25i)$

	i	j	k	$-j(0-2.5) = 2.5j$
	0	0	-10	
	-0.25	0	0	

$a_A = -64i - 3j + 2.5j + 64i$ $i = \text{cancel out}$
 $a_A = 0.5j \text{ ft/s}^2$ $a_A = 0.5 \text{ ft/s}^2 \downarrow$

need it to cancel $\omega^2 R$ out (the i component) (even if the video it says otherwise)

problem 16-127 (suite)

$$r_{B/C} = -0,25i - 0,25j$$

$$a_B = a_C + \alpha + r_{B/C} - \omega^2 r_{B/C}$$
$$= -64i - 3j + \underbrace{(-10k) \times (-0,25i - 0,25j)}_{\substack{= \hat{i}(0 - 2,5) - \hat{j}(0 - 2,5) + k(0) \\ = -2,5\hat{i} + 2,5\hat{j}}} - (6^2 (-0,25i - 0,25j))$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & k \\ 0 & 0 & -10 \\ -0,25 & -0,25 & 0 \end{vmatrix} = \hat{i}(0 - 2,5) - \hat{j}(0 - 2,5) + k(0)$$
$$= -2,5\hat{i} + 2,5\hat{j}$$

$$= -64i - 3j - 2,5i + 2,5j + 64i + 64j$$

$$= -3j - 2,5i - 2,5j + 64j$$

$$= -2,5\hat{i} + 63,5\hat{j} \text{ ft/s}^2$$

$$a_B = \sqrt{(-2,5)^2 + (63,5)^2} = 63,5 \text{ ft/s}^2$$

$$\theta = \tan^{-1} \frac{63,5}{2,5} = 87,7^\circ \quad \Delta$$

$$a_B = 63,5 \text{ ft/s}^2 \quad \Delta 87,7^\circ$$