

Question 1:

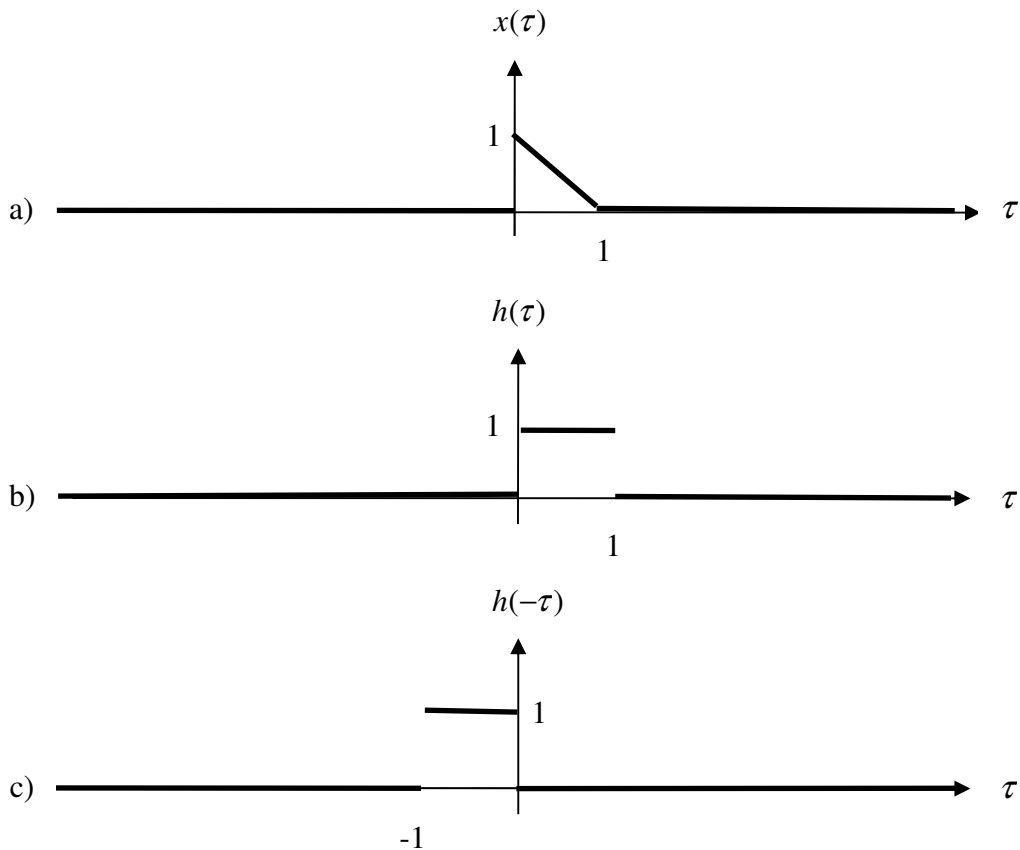
Consider a continuous-time LTI system which has impulse response of $h(t) = u(t) - u(t-1)$. If $x(t) = (1-t)\{u(t) - u(t-1)\}$ is applied at the input of the system,

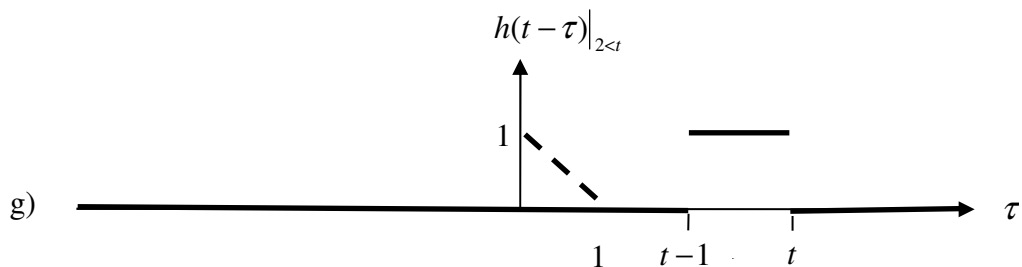
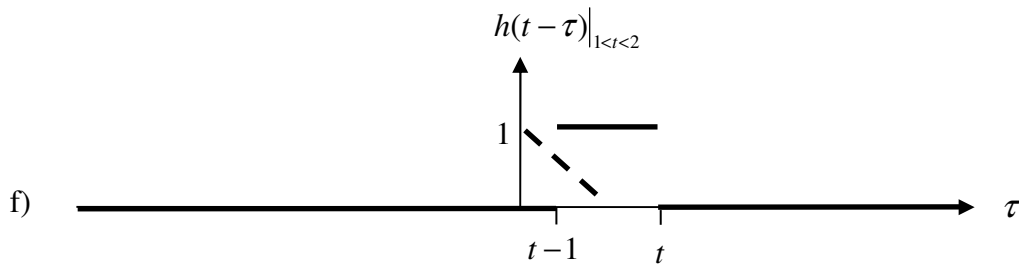
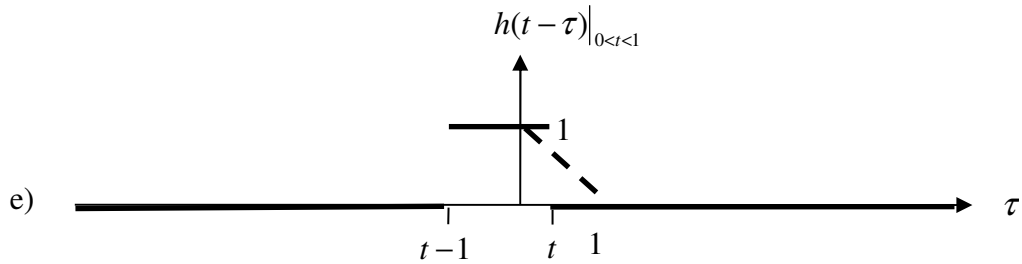
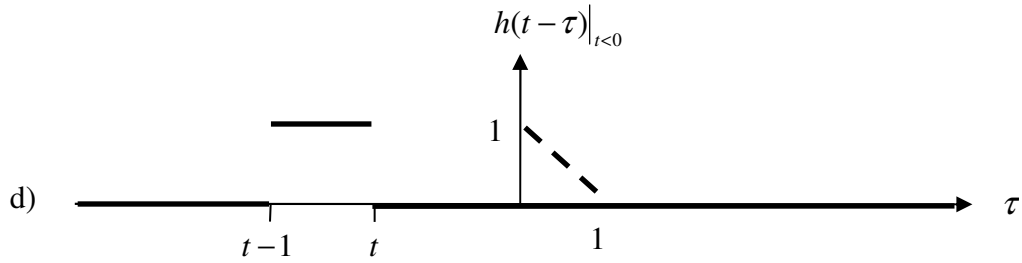
evaluate the output $y(t)$ of the system using convolution integral $y(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau)d\tau$ as follows:

- Draw $x(\tau)$ and $h(t-\tau)$ for different intervals of “ t ”.
- Write the expressions for calculating the output $y(t)$ for the intervals of “ t ” indicated in part (a). Do not calculate the result of integrals.

Solution 1a: $y(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau)d\tau$

Therefore, we draw $x(\tau)$ and $h(t-\tau)$ and perform the convolution:



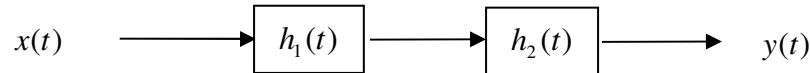


Solution 1b: Based on the overlap of $x(\tau)$ in figure “a” and $h(t - \tau)$ in figures “d”, “e”, “f” and “g”, $y(t)$ can be calculated for various regions as shown below:

$$y(t) = \begin{cases} 0 & t < 0 \quad \text{Fig. d)} \\ \int_0^t (1 - \tau) d\tau = \left[\tau - \frac{\tau^2}{2} \right]_0^t = t - \frac{t^2}{2} & 0 < t < 1 \quad \text{Fig. e)} \\ \int_{t-1}^1 (1 - \tau) d\tau = \left[\tau - \frac{\tau^2}{2} \right]_{t-1}^1 = 2 - 2t + \frac{t^2}{2} & 1 < t < 2 \quad \text{Fig. f)} \\ 0 & 2 < t \quad \text{Fig. g)} \end{cases}$$

Question 2:

Consider the interconnection of two continuous-time LTI systems, as depicted in the figure. The impulse responses of these systems are $h_1(t) = \delta(t-1) + \delta(t+1)$, $h_2(t) = 2^t u(t)$,



- Find the impulse response of the overall system.
- Determine whether or not each of the impulse responses $h_1(t)$ and $h_2(t)$ are causal, memory-less and stable. Justify your answer.

Solution 2a: $h(t) = h_1(t) * h_2(t) =$

$$h(t) = \int_{-\infty}^{\infty} [\delta(\tau-1) + \delta(\tau+1)] \times 2^{t-\tau} u(t-\tau) d\tau = \int_{-\infty}^{\infty} \delta(\tau-1) \times 2^{t-\tau} u(t-\tau) d\tau + \int_{-\infty}^{\infty} \delta(\tau+1) \times 2^{t-\tau} u(t-\tau) d\tau$$

$$h(t) = \int_{-\infty}^{\infty} \delta(\tau-1) \times 2^{t-\tau} u(t-\tau) d\tau + \int_{-\infty}^{\infty} \delta(\tau+1) \times 2^{t-\tau} u(t-\tau) d\tau =$$

$$h(t) = \int_{-\infty}^{\infty} \delta(\tau-1) \times 2^{t-1} u(t-1) d\tau + \int_{-\infty}^{\infty} \delta(\tau+1) \times 2^{t+1} u(t+1) d\tau = 2^{t-1} \int_1^{\infty} \delta(\tau-1) d\tau + 2^{t+1} \int_{-1}^{\infty} \delta(\tau+1) d\tau =$$

$$h(t) = 2^{t-1} u(t-1) + 2^{t+1} u(t+1)$$

Solution 2b:

If the impulse response of a system is zero for all values of $t < 0$, then the system is causal. Therefore:

Since $h_1(t) = \delta(t-1) + \delta(t+1)$, which is non-zero at $t = -1$ is non-causal.

Since $h_2(t) = 2^t u(t)$ is zero for all values of $t < 0$ (due to $u(t)$), therefore $h_2(t)$ is causal.

A system is memory-less if the impulse response is in the form of $K\delta(t)$ and obviously both $h_1(t)$ and $h_2(t)$ are not in this form and they have memory.

A system is stable if the impulse response satisfies, $\int_{-\infty}^{\infty} |h(\tau)| d\tau < \infty$. Therefore:

$$\int_{-\infty}^{\infty} |h_1(\tau)| d\tau = \int_{-\infty}^{\infty} |\delta(\tau-1) + \delta(\tau+1)| d\tau = 2 < \infty \text{ and } h_1(t) \text{ is stable.}$$

$$\int_{-\infty}^{\infty} |h_2(\tau)| d\tau = \int_{-\infty}^{\infty} |2^\tau u(\tau)| d\tau = \int_0^{\infty} |2^\tau| d\tau = \infty \text{ and } h_2(t) \text{ is unstable.}$$

Question 3:

Consider a continuous-time LTI system which has input of $x(t)$ and output of $y(t) = 2x(t-2) + x(t-1) + x(t+1) + 2x(t+2)$.

- a- Evaluate Fourier series coefficients a_k of $x(t) = \sum_{k=-\infty}^{\infty} \delta(t-5k)$.
- b- Using a_k and the properties of Fourier series, evaluate the Fourier series coefficients b_k of the output $y(t)$. Simplify b_k and show the result as weighted sum of cosine functions.

Solution 3a:

The signal $x(t)$ has fundamental period of $T_0 = 5$ and fundamental frequency of $\omega_0 = 2\pi/5$. Note that in each period there is a unit impulse function.

$$a_k = \frac{1}{T} \int_T x(t) e^{-jk\omega_0 t} dt = \frac{1}{5} \int_{-2.5}^{2.5} \delta(t) e^{-jk(2\pi/5)t} dt = \frac{1}{5} \int_{-2.5}^{2.5} \delta(t) e^{-jk(2\pi/5)0} dt = \frac{1}{5} \int_{-2.5}^{2.5} \delta(t) dt = \frac{1}{5}$$

$$a_k = \frac{1}{5} \text{ for all integer values of } k.$$

Solution 3b:

From properties, we have $x(t) \leftrightarrow a_k$, then $x(t-t_0) \leftrightarrow a_k e^{-jk(2\pi/T)t_0}$. By considering the linearity property as well, we have:

$$2x(t-2) + x(t-1) + x(t+1) + 2x(t+2) \leftrightarrow 2a_k e^{-jk(2\pi/5)2} + a_k e^{-jk(2\pi/5)1} + a_k e^{jk(2\pi/5)1} + 2a_k e^{jk(2\pi/5)2}$$

$$2x(t-2) + x(t-1) + x(t+1) + 2x(t+2) \leftrightarrow 2a_k (e^{-jk(2\pi/5)2} + e^{jk(2\pi/5)2}) + a_k (e^{-jk(2\pi/5)} + e^{jk(2\pi/5)})$$

$$2x(t-2) + x(t-1) + x(t+1) + 2x(t+2) \leftrightarrow 4a_k \cos \frac{4\pi k}{5} + 2a_k \cos \frac{2\pi k}{5}$$

$$2x(t-2) + x(t-1) + x(t+1) + 2x(t+2) \leftrightarrow \frac{4}{5} \cos \frac{4\pi k}{5} + \frac{2}{5} \cos \frac{2\pi k}{5}$$

$$y(t) = 2x(t-2) + x(t-1) + x(t+1) + 2x(t+2) \leftrightarrow b_k = \frac{4}{5} \cos \frac{4\pi k}{5} + \frac{2}{5} \cos \frac{2\pi k}{5} \text{ for all}$$

integer values of k .

Question 4)

Consider a continuous-time LTI system which has input of $x(t)$ and output

of $y(t) = \int_{-\infty}^t x(\tau) d\tau$. The input to the system is $x(t) = 2 \sin(2t)$.

- a- Evaluate impulse response of the system $h(t)$ and its frequency domain equivalent $H(j\omega)$.
- b- Evaluate Fourier series coefficients of the input signal $x(t)$ and output signal $y(t)$.

Solution 4a:

$$h(t) = y(t) \Big|_{x(t)=\delta(t)} = \int_{-\infty}^t \delta(\tau) d\tau = u(t)$$

$$H(j\omega) = \int_{-\infty}^{+\infty} h(\tau) e^{-j\omega\tau} d\tau = \int_{-\infty}^{+\infty} u(\tau) e^{-j\omega\tau} d\tau = \int_0^{+\infty} e^{-j\omega\tau} d\tau = \left[\frac{e^{-j\omega\tau}}{-j\omega} \right]_0^{\infty} = \frac{1}{j\omega}$$

Solution 4b:

The fundamental frequency of $x(t) = 2 \sin(2t)$ is $\omega_0 = 2$ and fundamental period would be

$$T = \frac{2\pi}{\omega_0} = \frac{2\pi}{2} = \pi.$$

$$x(t) = 2 \sin(2t) = 2 \left(\frac{e^{j2t} - e^{-j2t}}{2j} \right) = \frac{1}{j} (e^{j2t} - e^{-j2t})$$

$$x(t) = \frac{1}{j} (e^{j2t} - e^{-j2t}) = je^{-j2t} - je^{j2t}$$

Comparing above equation with the Fourier series expansion of

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk(2\pi/T)t} = \sum_{k=-\infty}^{\infty} a_k e^{jk2t}$$

We have: $a_{-1} = j$, $a_1 = -j$ and $a_k = 0$ for $k \neq \pm 1$

Fourier series coefficients of $y(t)$ are

$$b_k = a_k H(jk\omega_0) = a_k H(j2k) = a_k \frac{1}{j2k}$$

$$b_k = -\frac{ja_k}{2k} \Rightarrow b_{-1} = -\frac{1}{2}, \quad b_1 = -\frac{1}{2} \quad \text{and} \quad b_k = 0 \text{ for } k \neq \pm 1$$