

1. (13 marks) For the mechanical system shown in figure 1 where  $F_a(t)$  is the known force applied to the top of the lever as shown (assuming the mass of the lever is negligible and that the motion of the lever is small):

- (a) Draw the free body diagram(s) that model the system.
- (b) Write the state-space representation, in matrix form, of the system by
  - i. defining an appropriate set of state variables and
  - ii. writing the set of first order state-space equations in matrix form.

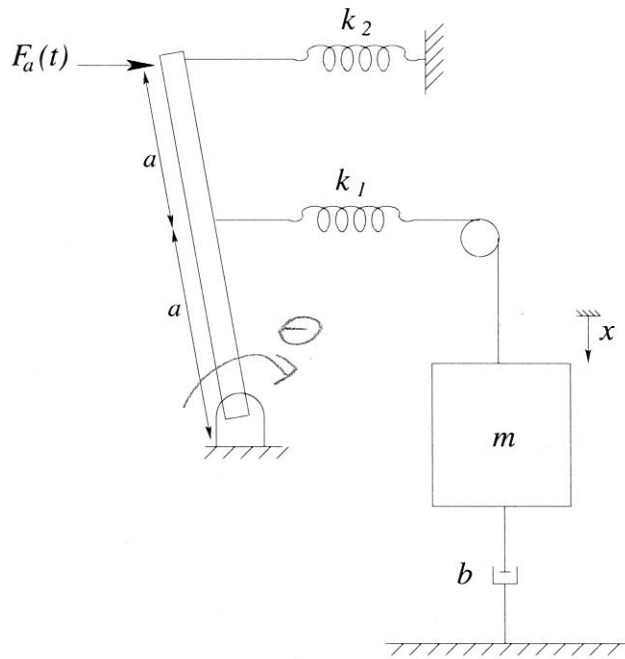
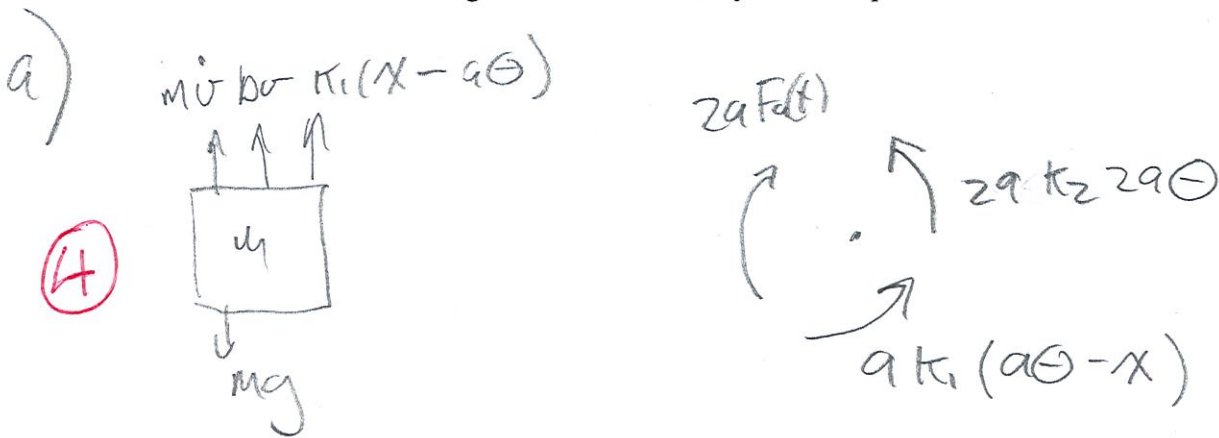


Figure 1: Mechanical system for question 1.



b) i) define  $\theta, x, v$  (of mass) as state variables

(c)  $\dot{x} = v$

$$\dot{v} = -\frac{b}{m} v - \frac{k_1}{m} x + \frac{k_1 a}{m} \theta + g$$

(6)

$$2a F_a(t) = 4a^2 k_2 \theta + a k_1 \theta - a k_1 x$$

$$2a F_a(t) = a^2 (4k_2 + k_1) \theta - a k_1 x$$

$$\dot{\Theta} = \frac{k_1}{a(4k_2+k_1)} U + \frac{2}{a(4k_2+k_1)} \dot{F}_a(t)$$

so

$$\begin{bmatrix} \dot{\Theta} \\ \dot{\chi} \\ \dot{U} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \frac{k_1 g}{m} \end{bmatrix} + \begin{bmatrix} 0 & \frac{k_1}{a(4k_2+k_1)} \\ 0 & 1 \\ -\frac{k_1}{m} & -\frac{b}{m} \end{bmatrix} \begin{bmatrix} \Theta \\ \chi \\ U \end{bmatrix} + \begin{bmatrix} \frac{2\dot{F}_a(t)}{a(4k_2+k_1)} \\ 0 \\ g \end{bmatrix}$$

2. (6 marks) For a system modelled by the differential equation shown below where  $x(t)$  is the response, show the numerical solution of the equation using the first order Euler approximation at  $t = 0$ ,  $t = 0.1$ , and  $t = 0.2$  for a time step of  $\Delta t = 0.1$  and given  $x(0) = 0$ .

$$10\dot{x}(t) + x(t) = 3$$
$$\dot{x}(t) = \frac{3}{10} - \frac{x(t)}{10} \quad |$$

$$t=0 \quad x(0) = 0 \quad (\text{given}) \quad |$$

$$t=0.1 \quad x(0.1) = x(0) + \Delta t \dot{x}(0)$$
$$= 0 + 0.1 \left( \frac{3}{10} - \frac{x(0)}{10} \right)$$
$$= 0.03$$

$$t=0.2 \quad x(0.2) = x(0.1) + \Delta t \dot{x}(0.1)$$
$$= 0.03 + 0.1 \left( \frac{3}{10} - \frac{x(0.1)}{10} \right)$$
$$= 0.03 + 0.1(0.3 - 0.003)$$
$$= 0.0597$$

3. (12 marks) For a system modelled by the following differential equation

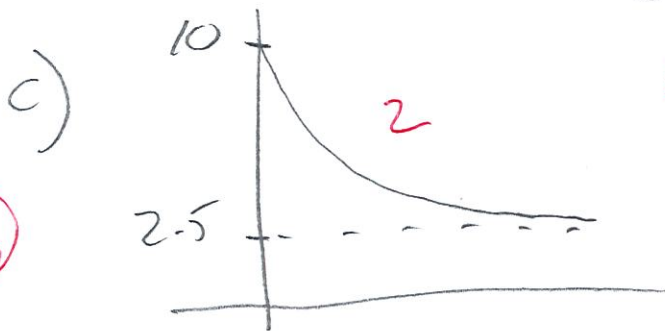
$$4Dy(t) + 2y(t) = 5$$

- (a) What is the steady state solution?  
 (b) What is the time constant,  $\tau$  of the system?  
 (c) Solve for and sketch the response,  $y(t)$ , given the initial value  $y(0) = 10$ .  
 (d) Using the initial condition above, at what time,  $t_0$ , is the value of the response  $y(t_0) = 5$ ?

$$2Dy(t) + y(t) = \frac{5}{2}$$

a)  $y_{ss} = \frac{5}{2}$  (2)

b)  $\tau = 2$  (2)



$$y(t) = Ae^{-t/\tau} + B$$

4  $B = 2.5$   
 $A + B = 10 \rightarrow A = 7.5$

$$y(t) = 7.5e^{-t/2} + 2.5$$

d)  $5 = 7.5e^{-t/2} + 2.5$

(2)  $\ln\left(\frac{2.5}{7.5}\right) = -t/2$

$$t = 2.197$$

4. (17 marks) The thermal characteristics of a travel mug for keeping coffee hot can be modelled as shown below in figure 2. The heating element that plugs into the car lighter socket is capable of delivering  $Q(t)=100$  W of heat. The volume of the coffee is 300 ml, and the mug has a total surface area of  $0.3$  m<sup>2</sup>.

- (a) Sketch the flow graph that models the system.
- (b) What is the time constant of the system?
- (c) Calculate the thermal capacitance,  $C$ , of the coffee (assume the properties of water).
- (d) You wish to calculate how much insulation is required for the mug.
  - i. Given an ambient temperature of  $T_a = 15$  °C and the thermal capacitance,  $C$ , calculated as above, calculate the thermal resistance,  $R$ , that will cause a temperature drop from an initial temperature of  $T(0) = 85$  °C, to a temperature of  $70$  °C over a 10 minute period with no heating.
  - ii. Given an insulating material with a thermal conductivity of  $k_t = 0.03$  W/m·K, what is the required thickness of the insulation to achieve the above thermal resistance,  $R$ ?
  - iii. For the above results, is the heating element sufficient to maintain a coffee temperature of  $80$  °C given an ambient temperature of  $T_a = 15$  °C? Justify your result.

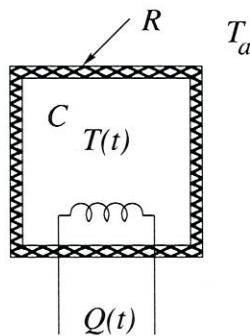
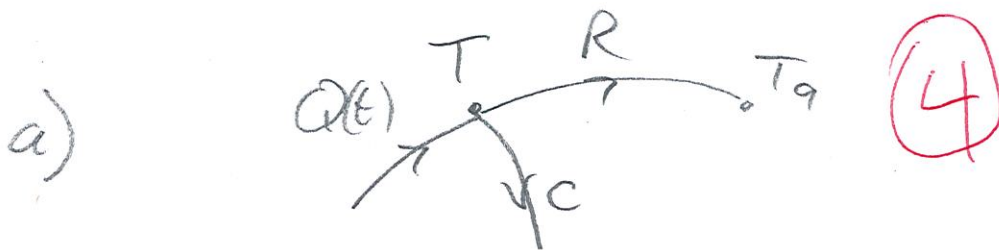


Figure 2: Thermal system for question 4.



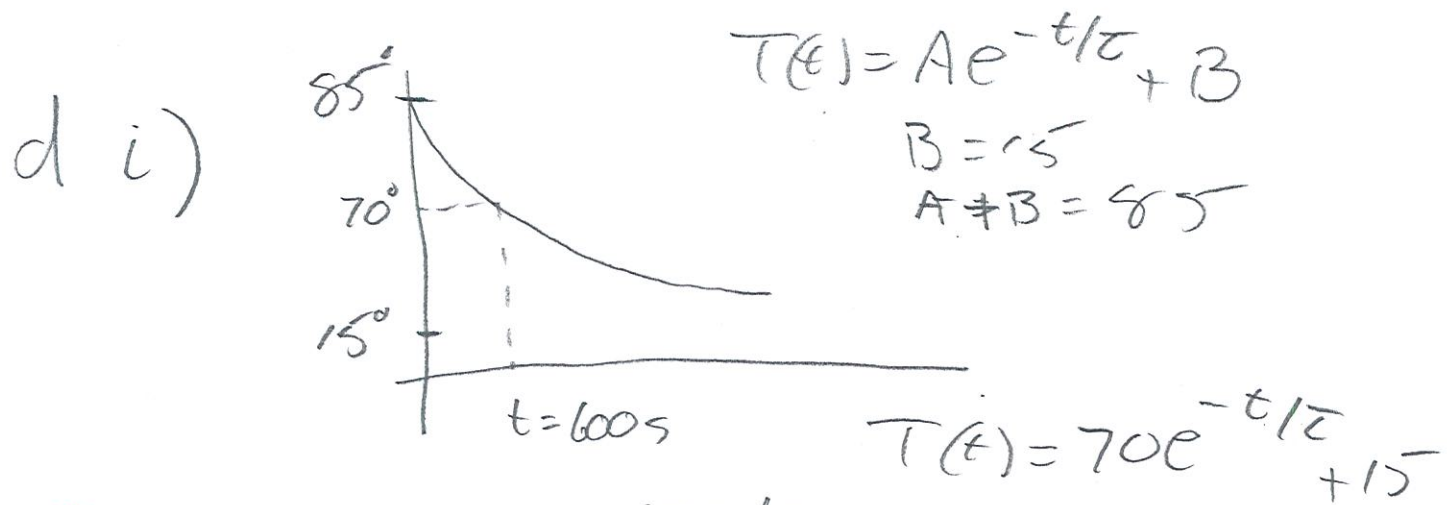
b)  $Q(t) = C \frac{dT(t)}{dt} + \frac{1}{R} (T(t) - T_a)$

$$RQ(t) + T_a = RC \frac{dT(t)}{dt} + T(t)$$

$$\tau = RC \quad \text{①}$$

c)  $C = mC_p$        $m = 0.3$  kg  
 $C_p = 4200 \frac{J}{kg \cdot K}$

$$C = 1260 \frac{J}{K} \quad \text{②}$$



⑥  $70 = 70e^{-600/\tau} + 15$

$$\ln\left(\frac{55}{70}\right) = -\frac{600}{\tau}$$

$$\tau = 2488 \text{ s}$$

$$2488 \text{ s} = R \cdot 1260 \frac{\text{J}}{\text{K}}$$

$$R = 1.97 \frac{\text{K}}{\text{W}}$$

ii  $R = \frac{L}{k_c A}$

②  $L = 1.97 \frac{\text{K}}{\text{W}} \cdot 0.03 \frac{\text{W}}{\text{mK}} \cdot 0.3 \text{ m}^2$

$$= 0.0178 \text{ m} = 1.78 \text{ cm}$$

iii  $Q = \frac{1}{R} \Delta T$

②  $= \frac{1}{1.97} \cdot 65^\circ = 33 \text{ W}$

∴ 100 W is sufficient