

(8.1) Consider the following first-order ODE:

$$\frac{dy}{dx} = x + y \quad \text{from } x = 0 \text{ to } x = 2.4 \text{ with } y(0) = 2$$

- (a) Solve with Euler's explicit method using  $h = 0.8$ .  
 (b) Solve with the modified Euler method using  $h = 0.8$ .  
 (c) Solve with the classical fourth-order Runge-Kutta method using  $h = 0.8$ .

The analytical solution of the ODE is  $y = 3e^x - x - 1$ . In each part, calculate the error between the true solution and the numerical solution at the points where the numerical solution is determined.

### Solution

(a) Using Eqs.(8.14) and (8.15) for Euler's explicit method with  $h = 0.8$ ,

$$x_{i+1} = x_i + h = x_i + 0.8$$

$$y_{i+1} = y_i + f(x_i, y_i)h = y_i + (x_i + y_i)0.8$$

$$\text{Error: } E_i = 3e^{x_i} - x_i - 1 - y_i$$

**First step:** For the first step  $i = 1$ ,  $x_1 = 0$ , and  $y_1 = 2$ .

$$x_2 = 0 + 0.8 = 0.8 \text{ and } y_2 = y_1 + (x_1 + y_1)0.8 = 2 + (0 + 2)(0.8) = 3.6$$

$$E_2 = 3e^{x_2} - x_2 - 1 - y_2 = 3e^{0.8} - 0.8 - 1 - 3.6 = 1.2766$$

**Second step:** For the second step  $i = 2$ ,  $x_2 = 0.8$ , and  $y_2 = 3.6$

$$x_3 = x_2 + 0.8 = 1.6 \text{ and } y_3 = y_2 + (x_2 + y_2)0.8 = 3.6 + (0.8 + 3.6)(0.8) = 7.12$$

$$E_3 = 3e^{x_3} - x_3 - 1 - y_3 = 3e^{1.6} - 1.6 - 1 - 7.12 = 5.1391$$

**Third step:** For the third step,  $i = 3$ ,  $x_3 = 1.6$ , and  $y_3 = 7.12$

$$x_4 = x_3 + 0.8 = 2.4 \text{ and } y_4 = y_3 + (x_3 + y_3)0.8 = 7.12 + (1.6 + 7.12)(0.8) = 14.096$$

$$E_4 = 3e^{x_4} - x_4 - 1 - y_4 = 3e^{2.4} - 2.4 - 1 - 14.096 = 15.5735$$

(b) Using Eq. (8.56) for the modified Euler method with  $h = 0.8$ ,

$$x_{i+1} = x_i + h = x_i + 0.8$$

$$y_{i+1}^{EU} = y_i + f(x_i, y_i)h = y_i + (x_i + y_i)h$$

$$y_{i+1} = y_i + 0.5[f(x_i, y_i) + f(x_{i+1}, y_{i+1}^{EU})]h = y_i + 0.5[x_i + y_i + x_i + y_{i+1}^{EU}]h$$

$$\text{Error: } E_i = 3e^{x_i} - x_i - 1 - y_i$$

**First step:** For the first step,  $i = 1$ ,  $x_1 = 0$ , and  $y_1 = 2$ .

$$x_2 = x_1 + 0.8 = 0.8$$

$$y_2^{EU} = y_1 + (x_1 + y_1)h = 2 + (0 + 2)(0.8) = 3.6$$

$$y_2 = y_1 + 0.5[x_1 + y_1 + x_2 + y_2^{EU}]h = 2 + 0.5[0 + 2 + 0.8 + 3.6](0.8) = 4.56$$

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$$E_2 = 3e^{x_2} - x_2 - 1 - y_2 = 3e^{0.8} - 0.8 - 1 - 4.56 = 0.3166$$

**Second step:** For the second step  $i = 2$ ,  $x_2 = 0.8$ , and  $y_2 = 4.56$

$$x_3 = x_2 + 0.8 = 1.6$$

$$y_3^{\text{EU}} = y_2 + (x_2 + y_2)h = 4.56 + (0.8 + 4.56)(0.8) = 8.848$$

$$y_3 = y_2 + 0.5[x_2 + y_2 + x_3 + y_3^{\text{EU}}]h = 4.56 + 0.5[0.8 + 4.56 + 1.6 + 8.848](0.8) = 10.8832$$

$$E_3 = 3e^{x_3} - x_3 - 1 - y_3 = 3e^{1.6} - 1.6 - 1 - 10.8832 = 1.3759$$

**Third step:** For the third step,  $i = 3$ ,  $x_3 = 1.6$ , and  $y_3 = 10.8832$

$$x_4 = x_3 + 0.8 = 2.4$$

$$y_4^{\text{EU}} = y_3 + (x_3 + y_3)h = 10.8832 + (1.6 + 10.8832)(0.8) = 20.8698$$

$$y_4 = y_3 + 0.5[x_3 + y_3 + x_4 + y_4^{\text{EU}}]h = 10.8832 + 0.5[1.6 + 10.8832 + 2.4 + 20.8698](0.8) = 25.1844$$

$$E_4 = 3e^{x_4} - x_4 - 1 - y_4 = 3e^{2.4} - 2.4 - 1 - 25.1844 = 4.4851$$

(c) Using Eqs. (8.86) and (8.87) for the classical fourth-order Runge–Kutta method with  $h = 0.8$ .

$$x_{i+1} = x_i + h = x_i + 0.8$$

$$f(x_i, y_i) = x_i + y_i$$

$$K_1 = f(x_i, y_i)$$

$$K_2 = f\left(x_i + \frac{1}{2}h, y_i + \frac{1}{2}K_1h\right)$$

$$K_3 = f\left(x_i + \frac{1}{2}h, y_i + \frac{1}{2}K_2h\right)$$

$$K_4 = f(x_i + h, y_i + K_3h)$$

$$y_{i+1} = y_i + \frac{h}{6}(K_1 + 2K_2 + 2K_3 + K_4)$$

$$\text{Error: } E_i = 3e^{x_i} - x_i - 1 - y_i$$

**First step:** For the first step,  $i = 1$ ,  $x_1 = 0$ , and  $y_1 = 2$ .

$$x_2 = x_1 + 0.8 = 0.8$$

$$K_1 = x_1 + y_1 = 0 + 2 = 2$$

$$x_1 + \frac{1}{2}h = 0 + \frac{0.8}{2} = 0.4; \quad y_1 + \frac{1}{2}K_1h = 2 + \frac{(2)(0.8)}{2} = 2.8$$

$$K_2 = 0.4 + 2.8 = 3.2$$

$$x_1 + \frac{h}{2} = 0 + \frac{0.8}{2} = 0.4; \quad y_1 + \frac{1}{2}K_2h = 2 + \frac{(3.2)(0.8)}{2} = 3.28$$

$$K_3 = x_1 + \frac{1}{2}h + y_1 + \frac{1}{2}K_2h = 0 + \frac{0.8}{2} + 3.28 = 3.68$$

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$$K_4 = x_1 + h + y_1 + K_3h = 0 + 0.8 + 2 + (3.68)(0.8) = 5.744$$

$$y_2 = 2 + \frac{(0.8)}{6}(2 + 2(3.2) + 2(3.68) + 5.744) = 4.8672$$

$$\text{Error : } E_2 = 3e^{x_2} - x_2 - 1 - y_2 = 3e^{0.8} - 0.8 - 1 - 4.8672 = 0.0094$$

**Second step:** For the second step  $i = 2$ ,  $x_2 = 0.8$ , and  $y_2 = 4.8672$

$$x_3 = x_2 + 0.8 = 1.6$$

$$K_1 = x_2 + y_2 = 0.8 + 4.8672 = 5.6672$$

$$x_2 + \frac{1}{2}h = 0.8 + \frac{0.8}{2} = 1.2; \quad y_2 + \frac{1}{2}K_1h = 4.8672 + \frac{(5.6672)(0.8)}{2} = 7.1341$$

$$K_2 = x_2 + \frac{1}{2}h + y_2 + \frac{1}{2}K_1h = 1.2 + 7.1341 = 8.3341$$

$$x_2 + \frac{h}{2} = 0.8 + \frac{0.8}{2} = 1.2; \quad y_2 + \frac{1}{2}K_2h = 4.8672 + \frac{(8.3341)(0.8)}{2} = 8.2008$$

$$K_3 = x_2 + \frac{1}{2}h + y_2 + \frac{1}{2}K_2h = 0.8 + \frac{0.8}{2} + 8.2008 = 9.4008$$

$$K_4 = x_2 + h + y_2 + K_3h = 0.8 + 0.8 + 4.8672 + (9.4008)(0.8) = 13.9878$$

$$y_3 = y_2 + \frac{h}{6}(K_1 + 2K_2 + 2K_3 + K_4)$$

$$= 4.8672 + \frac{0.8}{6}(5.6672 + (2)(8.3341) + (2)(9.4008) + 13.9878)$$

$$= 12.2172$$

$$\text{Error : } E_3 = 3e^{x_3} - x_3 - 1 - y_3 = 3e^{1.6} - 1.6 - 1 - 12.2172 = 0.0419$$

**Third step:** For the third step,  $i = 3$ ,  $x_3 = 1.6$ , and  $y_3 = 12.2172$

$$x_4 = x_3 + 0.8 = 2.4$$

$$K_1 = x_3 + y_3 = 1.6 + 12.2172 = 13.8172$$

$$x_3 + \frac{1}{2}h = 1.6 + \frac{0.8}{2} = 2; \quad y_3 + \frac{1}{2}K_1h = 12.2172 + \frac{(13.8172)(0.8)}{2} = 17.7441$$

$$K_2 = x_3 + \frac{1}{2}h + y_3 + \frac{1}{2}K_1h = 1.6 + 0.4 + 17.7441 = 19.7441$$

$$x_3 + \frac{h}{2} = 1.6 + \frac{0.8}{2} = 2; \quad y_3 + \frac{1}{2}K_2h = 12.2172 + \frac{(19.7441)(0.8)}{2} = 20.1148$$

$$K_3 = x_3 + \frac{1}{2}h + y_3 + \frac{1}{2}K_2h = 1.6 + \frac{0.8}{2} + 20.1148 = 22.1148$$

$$K_4 = x_3 + h + y_3 + K_3h = 1.6 + 0.8 + 12.2172 + (22.1148)(0.8) = 32.3090$$

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$$\begin{aligned}y_4 &= y_3 + \frac{h}{6}(K_1 + 2K_2 + 2K_3 + K_4) \\ &= 12.2172 + \frac{0.8}{6}(13.8172 + (2)(19.7441) + (2)(22.1148) + 32.3090) \\ &= 29.5297\end{aligned}$$

$$\text{Error: } E_4 = 3e^{x_4} - x_4 - 1 - y_4 = 3e^{2.4} - 2.4 - 1 - 29.5297 = 0.1398$$

**8.2** Consider the following first-order ODE:

$$\frac{dy}{dx} = 2y - x^2 \quad \text{from } x = 1 \text{ to } x = 2.8 \text{ with } y(1) = 2$$

- (a) Solve with Euler's explicit method using  $h = 0.6$ .  
 (b) Solve with the modified Euler method using  $h = 0.6$ .  
 (c) Solve with the classical fourth-order Runge–Kutta method using  $h = 0.6$ .

The analytical solution of the ODE is:  $y = \frac{1}{2}x + \frac{1}{2}x^2 + \frac{3}{4}e^{2x-2} + \frac{1}{4}$ . In each part, calculate the error between the true solution and the numerical solution at the points where the numerical solution is determined.

**Solution**

- (a) Using Eqs.(8.14) and (8.15) for Euler's explicit method with  $h = 0.6$ ,

$$x_{i+1} = x_i + h = x_i + 0.6$$

$$y_{i+1} = y_i + f(x_i, y_i)h = y_i + (2y_i - x_i^2)0.6$$

$$\text{Error: } E_i = \frac{x_i}{2} + \frac{x_i^2}{2} + \frac{3}{4}e^{2x_i-2} + \frac{1}{4} - y_i$$

**First step:** For the first step  $i = 1$ ,  $x_1 = 1$ , and  $y_1 = 2$ .

$$x_2 = 1 + 0.6 = 1.6 \text{ and } y_2 = y_1 + (2y_1 - x_1^2)0.6 = 2 + (2(2) - 1)(0.6) = 3.8$$

$$E_2 = \frac{1.6}{2} + \frac{(1.6)^2}{2} + \frac{3}{4}e^{2(1.6)-2} + \frac{1}{4} - 3.8 = 4.8201 - 3.8 = 1.0201$$

**Second step:** For the second step  $i = 2$ ,  $x_2 = 1.6$ , and  $y_2 = 3.8$

$$x_3 = x_2 + 0.6 = 2.2 \text{ and } y_3 = y_2 + (2y_2 - x_2^2)0.6 = 3.8 + (2(3.8) - 2.56)(0.6) = 6.824$$

$$E_3 = \frac{2.2}{2} + \frac{(2.2)^2}{2} + \frac{3}{4}e^{2(2.2)-2} + \frac{1}{4} - 6.824 = 12.0374 - 6.824 = 5.2134$$

**Third step:** For the third step,  $i = 3$ ,  $x_3 = 2.2$ , and  $y_3 = 6.824$

$$x_4 = x_3 + 0.6 = 2.8 \text{ and}$$

$$y_4 = y_3 + (2y_3 - x_3^2)0.6 = 6.824 + (2(6.824) - 4.84)(0.6) = 12.1088$$

$$E_4 = \frac{2.8}{2} + \frac{(2.8)^2}{2} + \frac{3}{4}e^{2(2.8)-2} + \frac{1}{4} - 12.1088 = 33.0187 - 12.1088 = 20.9099$$

- (b) Using Eq. (8.56) for the modified Euler method with  $h = 0.6$ ,

$$x_{i+1} = x_i + h = x_i + 0.6$$

$$y_{i+1}^{\text{EU}} = y_i + f(x_i, y_i)h = y_i + (2y_i - x_i^2)h$$

$$y_{i+1} = y_i + 0.5[f(x_i, y_i) + f(x_{i+1}, y_{i+1}^{\text{EU}})]h = y_i + 0.5[2y_i - x_i^2 + 2y_{i+1}^{\text{EU}} - x_{i+1}^2]h$$

$$\text{Error: } E_i = \frac{x_i}{2} + \frac{x_i^2}{2} + \frac{3}{4}e^{2x_i-2} + \frac{1}{4} - y_i$$

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**First step:** For the first step,  $i = 1$ ,  $x_1 = 1$ , and  $y_1 = 2$ .

$$x_2 = x_1 + 0.6 = 1.6$$

$$y_2^{\text{EU}} = y_1 + (2y_1 - x_1^2)h = 2 + (2(2) - 1)(0.6) = 3.8$$

$$y_2 = y_1 + 0.5[2y_1 - x_1^2 + 2y_2^{\text{EU}} - x_2^2]h = 2 + 0.5[2(2) - 1 + 2(3.8) - 2.56](0.6) = 4.412$$

$$E_2 = \frac{1.6}{2} + \frac{(1.6)^2}{2} + \frac{3}{4}e^{2(1.6)-2} + \frac{1}{4} - 4.412 = 4.8201 - 4.412 = 0.4081$$

**Second step:** For the second step  $i = 2$ ,  $x_2 = 1.6$ , and  $y_2 = 4.412$

$$x_3 = x_2 + 0.6 = 2.2$$

$$y_3^{\text{EU}} = y_2 + (2y_2 - x_2^2)h = 4.412 + (2(4.412) - 2.56)(0.6) = 8.1704$$

$$y_3 = y_2 + 0.5[2y_2 - x_2^2 + 2y_3^{\text{EU}} - x_3^2]h \\ = 4.412 + 0.5[2(4.412) - 2.56 + 2(8.1704) - 4.84](0.6) = 9.7414$$

$$E_3 = \frac{2.2}{2} + \frac{(2.2)^2}{2} + \frac{3}{4}e^{2(2.2)-2} + \frac{1}{4} - 9.7414 = 12.0374 - 9.7414 = 2.296$$

**Third step:** For the third step,  $i = 3$ ,  $x_3 = 2.2$ , and  $y_3 = 9.7414$

$$x_4 = x_3 + 0.6 = 2.8$$

$$y_4^{\text{EU}} = y_3 + (2y_3 - x_3^2)h = 9.7414 + (2(9.7414) - 4.84)(0.6) = 18.5271$$

$$y_4 = y_3 + 0.5[2y_3 - x_3^2 + 2y_4^{\text{EU}} - x_4^2]h \\ = 9.7414 + 0.5[2(9.7414) - 4.84 + 2(18.5271) - 7.84](0.6) = 22.8985$$

$$E_3 = \frac{2.8}{2} + \frac{(2.8)^2}{2} + \frac{3}{4}e^{2(2.8)-2} + \frac{1}{4} - 22.8985 = 33.0187 - 22.8985 = 10.1202$$

(c) Using Eqs. (8.86) and (8.87) for the classical fourth-order Runge–Kutta method with  $h = 0.6$ .

$$x_{i+1} = x_i + h = x_i + 0.6$$

$$f(x_i, y_i) = 2y_i - x_i^2$$

$$K_1 = f(x_i, y_i)$$

$$K_2 = f(x_i + \frac{1}{2}h, y_i + \frac{1}{2}K_1h)$$

$$K_3 = f(x_i + \frac{1}{2}h, y_i + \frac{1}{2}K_2h)$$

$$K_4 = f(x_i + h, y_i + K_3h)$$

$$y_{i+1} = y_i + \frac{h}{6}(K_1 + 2K_2 + 2K_3 + K_4)$$

$$\text{Error: } E_i = \frac{x_i}{2} + \frac{x_i^2}{2} + \frac{3}{4}e^{2x_i-2} + \frac{1}{4} - y_i$$

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**First step:** For the first step,  $i = 1$ ,  $x_1 = 1$ , and  $y_1 = 2$ .

$$x_2 = x_1 + 0.6 = 1.6$$

$$K_1 = 2y_1 - x_1^2 = 2(2) - 1 = 3$$

$$x_1 + \frac{1}{2}h = 1 + \frac{0.6}{2} = 1.3; \quad y_1 + \frac{1}{2}K_1h = 2 + \frac{(3)(0.6)}{2} = 2.9$$

$$K_2 = 2\left(y_1 + \frac{1}{2}K_1h\right) - \left(x_1 + \frac{1}{2}h\right)^2 = 2\left[2 + \frac{(3)(0.6)}{2}\right] - (1 + 0.3)^2 = 4.11$$

$$x_1 + \frac{h}{2} = 1 + \frac{0.6}{2} = 1.3; \quad y_1 + \frac{1}{2}K_2h = 2 + \frac{(4.11)(0.6)}{2} = 3.233$$

$$K_3 = 2\left(y_1 + \frac{1}{2}K_2h\right) - \left(x_1 + \frac{1}{2}h\right)^2 = 2\left[2 + \frac{(4.11)(0.6)}{2}\right] - (1 + 0.3)^2 = 4.776$$

$$K_4 = 2(y_1 + K_3h) - (x_1 + h)^2 = 2[2 + (4.776)(0.6)] - (1.6)^2 = 7.1712$$

$$y_2 = 2 + \frac{(0.6)}{6}(3 + 2(4.11) + 2(4.776) + 7.1712) = 4.7943$$

$$E_2 = \frac{1.6}{2} + \frac{(1.6)^2}{2} + \frac{3}{4}e^{2(1.6)-2} + \frac{1}{4} - 4.7943 = 4.8201 - 4.7943 = 0.0258$$

**Second step:** For the second step  $i = 2$ ,  $x_2 = 1.6$ , and  $y_2 = 4.7943$

$$x_3 = x_2 + 0.6 = 2.2$$

$$K_1 = 2y_2 - x_2^2 = 2(4.7943) - 2.56 = 7.0286$$

$$x_2 + \frac{1}{2}h = 1.6 + \frac{0.6}{2} = 1.9; \quad y_2 + \frac{1}{2}K_1h = 4.7943 + \frac{(7.0286)(0.6)}{2} = 6.9029$$

$$K_2 = 2\left(y_2 + \frac{1}{2}K_1h\right) - \left(x_2 + \frac{1}{2}h\right)^2 = 2[6.9029] - (1.9)^2 = 10.1958$$

$$x_2 + \frac{h}{2} = 1.6 + \frac{0.6}{2} = 1.9; \quad y_2 + \frac{1}{2}K_2h = 4.7943 + \frac{(10.1958)(0.6)}{2} = 7.8530$$

$$K_3 = 2\left(y_2 + \frac{1}{2}K_2h\right) - \left(x_2 + \frac{1}{2}h\right)^2 = 2[7.8530] - (1.9)^2 = 12.096$$

$$K_4 = 2(y_2 + K_3h) - (x_2 + h)^2 = 2[4.7943 + (12.096)(0.6)] - (2.2)^2 = 19.2638$$

$$y_3 = y_2 + \frac{h}{6}(K_1 + 2K_2 + 2K_3 + K_4)$$

$$= 4.7943 + \frac{0.6}{6}(7.0286 + (2)(10.1958) + (2)(12.096) + 19.2638)$$

$$= 11.8819$$

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$$E_3 = \frac{2.2}{2} + \frac{(2.2)^2}{2} + \frac{3}{4}e^{2(2.2)-2} + \frac{1}{4} - 11.8819 = 12.0374 - 11.8819 = 0.1555$$

**Third step:** For the third step,  $i = 3$ ,  $x_3 = 2.2$ , and  $y_3 = 11.8819$

$$x_4 = x_3 + 0.6 = 2.8$$

$$K_1 = 2y_3 - x_3^2 = 2(11.8819) - 4.84 = 18.9238$$

$$x_3 + \frac{1}{2}h = 2.2 + \frac{0.6}{2} = 2.5; \quad y_3 + \frac{1}{2}K_1h = 11.8819 + \frac{(18.9238)(0.6)}{2} = 17.5590$$

$$K_2 = 2\left(y_3 + \frac{1}{2}K_1h\right) - \left(x_3 + \frac{1}{2}h\right)^2 = 2[17.559] - (2.5)^2 = 28.868$$

$$x_3 + \frac{h}{2} = 2.2 + \frac{0.6}{2} = 2.5; \quad y_3 + \frac{1}{2}K_2h = 11.8819 + \frac{(28.868)(0.6)}{2} = 20.5423$$

$$K_3 = 2\left(y_3 + \frac{1}{2}K_2h\right) - \left(x_3 + \frac{1}{2}h\right)^2 = 2(20.5423) - (2.5)^2 = 34.8346$$

$$K_4 = 2(y_3 + K_3h) - (x_3 + h)^2 = 2[11.8819 + (34.8346)(0.6)] - (2.8)^2 = 57.7253$$

$$y_4 = y_3 + \frac{h}{6}(K_1 + 2K_2 + 2K_3 + K_4)$$

$$= 11.8819 + \frac{0.6}{6}(18.9238 + (2)(28.868) + (2)(34.8346) + 57.7253)$$

$$= 32.2873$$

$$E_4 = \frac{2.8}{2} + \frac{(2.8)^2}{2} + \frac{3}{4}e^{2(2.8)-2} + \frac{1}{4} - 32.2873 = 33.0187 - 32.2873 = 0.7314$$

**8.3** Consider the following first-order ODE:

$$\frac{dy}{dt} = t^2 - \frac{3y}{t} \quad \text{from } t = 1 \text{ to } t = 2.2 \text{ with } y(1) = 1$$

- (a) Solve with Euler's explicit method using  $h = 0.4$ .  
 (b) Solve with the midpoint method using  $h = 0.4$ .  
 (c) Solve with the classical fourth-order Runge–Kutta method using  $h = 0.4$ .

The analytical solution of the ODE is  $y = \frac{1}{6} \left( \frac{5}{t^3} + t^3 \right)$ . In each part, calculate the error between the true solution and the numerical solution at the points where the numerical solution is determined.

### Solution

(a) The following script file solves the ODE with Euler's explicit method using  $h = 0.4$ .

```
clear, clc
% Chapter 8se Problem 3 Part (a)
dF=@ (t,y) t.^2-3*y./t;
Fsol=@ (t) (5./t.^3+t.^3)/6;
h=0.4; N=3;
t(1) = 1; y(1) = 1;
for i = 1:N
    t(i+1) = t(i) + h;
    y(i+1) = y(i) + dF(t(i),y(i))*h;
end
t
y
ys=Fsol(t);
error=ys-y
```

When the program is executed, the following results are displayed in the Command Window:

```
t =
    1.0000    1.4000    1.8000    2.2000
y =
    1.0000    0.2000    0.8126    1.5669
```

---

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```
error =  
      0      0.5610      0.3023      0.2861
```

(b) The following script file solves the ODE with modified Euler method using  $h = 0.4$ .

```
clear, clc  
% Chapter 8se Problem 3 Part (b)  
dF=@ (t,y) t.^2-3*y./t;  
Fsol=@ (t) (5./t.^3+t.^3)/6;  
h=0.4; N=3;  
t(1) = 1; y(1) = 1;;  
for i = 1:N  
    t(i+1) = t(i) + h;  
    tm = t(i) + h/2;  
    ym=y(i) + dF(t(i),y(i))*h/2;  
    y(i+1) = y(i) + (dF(tm,ym))*h;  
end  
t  
y  
ys=Fsol(t);  
error=ys-y
```

When the program is executed, the following results are displayed in the Command Window:

```
t =  
    1.0000    1.4000    1.8000    2.2000  
y =  
    1.0000    0.9760    1.2877    1.9838  
error =  
      0    -0.2150    -0.1728    -0.1309
```

(c) The following script file solves the ODE with classical fourth-order Runge–Kutta method using  $h = 0.4$ .

---

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---

```
clear, clc
% Chapter 8se Problem 3 Part (c)
dF=@ (t,y) t.^2-3*y./t;
Fsol=@ (t) (5./t.^3+t.^3)/6;
h=0.4; N=3;
t(1) = 1; y(1) = 1;
for i = 1:N
    t(i+1) = t(i) + h;
    K1= dF(t(i),y(i));
    K2= dF(t(i)+0.5*h,y(i)+K1*h/2);
    K3= dF(t(i)+0.5*h,y(i)+K2*h/2);
    K4= dF(t(i+1),y(i)+K3*h);
    y(i+1) = y(i) + (K1+2*K2+2*K3+K4)*h/6;
end
t
y
xsolp=linspace(t(1),t(N+1),20);
ysolp=Fsol(xsolp);
ys=Fsol(t);
error=ys-y
```

When the program is executed, the following results are displayed in the Command Window:

```
t =
    1.0000    1.4000    1.8000    2.2000
y =
    1.0000    0.7680    1.1194    1.8559
error =
     0   -0.0070   -0.0045   -0.0030
```

---

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**8.4** Consider the following first-order ODE:

$$\frac{dy}{dt} = t^2 - \frac{2y}{t} \quad \text{from } t = 1 \text{ to } t = 4 \text{ with } y(1) = 2$$

- (a) Solve with Euler's explicit method using  $h = 1$ .  
 (b) Solve with the modified Euler method using  $h = 1$ .  
 (c) Solve with the classical third-order Runge–Kutta method using  $h = 1$ .

The analytical solution of the ODE is  $y = \frac{9}{5t^2} + \frac{t^3}{5}$ . In each part, calculate the error between the true solution and the numerical solution at the points where the numerical solution is determined.

**Solution**

(a) The following script file solves the ODE with Euler's explicit method using  $h = 1$ .

```
clear, clc
% Chapter 8se Problem 4 Part (a)
dF=@ (t,y) t.^2-2*y./t;
Fsol=@ (t) 9./(5*t.^2)+t.^3/5;
h=1; N=3;
t(1) = 1; y(1) = 2;
for i = 1:N
    t(i+1) = t(i) + h;
    y(i+1) = y(i) + dF(t(i),y(i))*h;
end
t
y
ys=Fsol(t);
error=ys-y
```

When the program is executed, the following results are displayed in the Command Window:

```
t =
    1    2    3    4
y =
  2.0000  -1.0000   4.0000  10.3333
error =
```

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0      3.0500      1.6000      2.5792

(b) The following script file solves the ODE with modified Euler method using  $h = 1$  .

```
clear, clc
% Chapter 8se Problem 4 Part (b)
dF=@ (t,y) t.^2-2*y./t;
Fsol=@ (t) 9./(5*t.^2)+t.^3/5;
h=1; N=3;
t(1) = 1; y(1) = 2;
for i = 1:N
    t(i+1) = t(i) + h;
    K1=dF(t(i),y(i));
    yEU=y(i) + K1*h;
    K2=dF(t(i+1),yEU);
    y(i+1) = y(i) + (K1+K2)/2*h;
end
t
y
ys=Fsol(t);
error=ys-y
```

When the program is executed, the following results are displayed in the Command Window:

```
t =
    1     2     3     4
y =
    2.0000    3.0000    6.6667   14.1389
error =
    0   -0.9500   -1.0667   -1.2264
```

(c) The following script file solves the ODE with classical fourth-order Runge–Kutta method using  $h = 1$  .

---

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---

```
clear, clc
% Chapter 8se Problem 4 Part (c)
dF=@ (t,y) t.^2-2*y./t;
Fsol=@ (t) 9./(5*t.^2)+t.^3/5;
h=1; N=3;
t(1) = 1; y(1) = 2;
for i = 1:N
    t(i+1) = t(i) + h;
    K1= dF(t(i),y(i));
    K2= dF(t(i)+0.5*h,y(i)+K1*h/2);
    K3= dF(t(i)+h,y(i)-K1*h+2*K2*h);
    y(i+1) = y(i) + (K1+4*K2+K3)*h/6;
end
t
y
ys=Fsol(t);
error=ys-y
```

When the program is executed, the following results are displayed in the Command Window:

```
t =
    1     2     3     4
y =
    2.0000    1.8611    5.4843   12.8245
error =
         0    0.1889    0.1157    0.0880
```

---

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**8.5** Consider the following system of two ODEs:

$$\frac{dx}{dt} = x + y \quad \frac{dy}{dt} = y - x \quad \text{from } t = 0 \text{ to } t = 2 \text{ with } x(0) = 1, \text{ and } y(0) = 2$$

(a) Solve with Euler's explicit method using  $h = 0.5$ .

(b) Solve with the modified Euler method using  $h = 0.5$ .

The analytical solution of the system is  $x = e^t[2\sin(t) + \cos(t)]$ ,  $y = e^t[2\cos(t) - \sin(t)]$ . In each part, calculate the error between the true solution and the numerical solution at the points where the numerical solution is determined.

### Solution

(a) The following script file solves the system of the ODEs with Euler's explicit method using  $h = 0.5$ .

```
clear, clc
dxdt = @(x,y) x+y;
dydt = @(x,y) y-x;
x(1) = 1; y(1) = 2;
t(1)=0;
h = 0.5;
N=4;
for i = 1:N
    t(i+1) = t(i) + h;
    x(i+1) = x(i) + dxdt(x(i),y(i))*h;
    y(i+1) = y(i) + dydt(x(i),y(i))*h;
end
t
x
y
Xerror=exp(t).*(2*sin(t)+cos(t))-x
Yerror=exp(t).*(2*cos(t)-sin(t))-y
```

When the program is executed, the following results are displayed in the Command Window:

```
t =
    0    0.5000    1.0000    1.5000    2.0000
```

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```
x =
    1.0000    2.5000    5.0000    8.7500   13.7500
y =
    2.0000    2.5000    2.5000    1.2500   -2.5000
Xerror =
    0    0.5278    1.0434    0.5079   -3.3872
Yerror =
    0   -0.3967   -1.8500   -5.0864  -10.3687
```

(b) The following script file solves the system of the ODEs with the modified Euler method using  $h = 0.5$ .

```
clear, clc
dxdt = @ (x,y) x+y;
dydt = @ (x,y) y-x;
x(1) = 1; y(1) = 2;
t(1)=0;
h = 0.5;
N=4;
for i = 1:N
    t(i+1) = t(i) + h;
    xEU = x(i) + dxdt(x(i),y(i))*h;
    yEU = y(i) + dydt(x(i),y(i))*h;
    x(i+1) = x(i) + (dxdt(x(i),y(i))+dxdt(xEU,yEU))*h/2;
    y(i+1) = y(i) + (dydt(x(i),y(i))+dydt(xEU,yEU))*h/2;
end
t
x
y
Xerror=exp(t).*(2*sin(t)+cos(t))-x
Yerror=exp(t).*(2*cos(t)-sin(t))-y
```

When the program is executed, the following results are displayed in the Command Window:

```
t =
```

---

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---

x =	0	0.5000	1.0000	1.5000	2.0000
y =	1.0000	3.0000	6.1875	10.1250	12.9727
Xerror =	2.0000	2.2500	1.1250	-2.9531	-12.0234
Yerror =	0	0.0278	-0.1441	-0.8671	-2.6099
	0	-0.1467	-0.4750	-0.8833	-0.8453

---

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**8.6** Consider the following system of two ODEs:

$$\frac{dx}{dt} = xt - y \quad \frac{dy}{dt} = yt + x \quad \text{from } t = 0 \text{ to } t = 1.2 \text{ with } x(0) = 1, \text{ and } y(0) = 0.5$$

(a) Solve with Euler's explicit method using  $h = 0.4$ .

(b) Solve with the classical fourth-order Runge–Kutta method using  $h = 0.4$ .

The analytical solution of the system is  $x = e^{\frac{1}{2}t^2} \left( \cos t - \frac{1}{2} \sin t \right)$ ,  $y = \left( -e^{\frac{1}{2}t^2} \right) \left( -\sin t - \frac{1}{2} \cos t \right)$ . In each part, calculate the error between the true solution and the numerical solution at the points where the numerical solution is determined.

### Solution

(a) The following script file solves the system of the ODEs with Euler's explicit method using  $h = 0.4$ .

```
clear all
dxdt = inline('x*t-y');
dydt = inline('y*t+x');
x(1) = 1; y(1) = 0.5;
t(1)=0;
h = 0.4;
N=3;
for i = 1:N
    t(i+1) = t(i) + h;
    x(i+1) = x(i) + dxdt(t(i),x(i),y(i))*h;
    y(i+1) = y(i) + dydt(t(i),x(i),y(i))*h;
end
t
x
y
Xerror=exp(0.5*t.^2).*(cos(t)-0.5*sin(t))-x
Yerror=-exp(0.5*t.^2).*(-sin(t)-0.5*cos(t))-y
```

When the program is executed, the following results are displayed in the Command Window:

```
t =
```

---

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```
x =
    0    0.4000    0.8000    1.2000
1.0000    0.8000    0.5680    0.2042
y =
    0.5000    0.9000    1.3640    2.0277
Xerror =
    0   -0.0132   -0.1025   -0.4171
Yerror =
    0    0.0207    0.1036    0.2594
```

(b) The following script file solves the system of the ODEs with the fourth-order Runge-Kutta method using  $h = 0.4$ .

```
clear all
dxdt = inline('x*t-y');
dydt = inline('y*t+x');
x(1) = 1; y(1) = 0.5;
t(1)=0;
h = 0.4;
N=3;
for i = 1:N
    t(i+1) = t(i) + h;
    Kx1= dxdt(t(i),x(i),y(i));
    Ky1= dydt(t(i),x(i),y(i));
    Kx2= dxdt(t(i)+0.5*h,x(i)+Kx1*h/2,y(i)+Ky1*h/2);
    Ky2= dydt(t(i)+0.5*h,x(i)+Kx1*h/2,y(i)+Ky1*h/2);
    Kx3= dxdt(t(i)+0.5*h,x(i)+Kx2*h/2,y(i)+Ky2*h/2);
    Ky3= dydt(t(i)+0.5*h,x(i)+Kx2*h/2,y(i)+Ky2*h/2);
    Kx4= dxdt(t(i+1),x(i)+Kx3*h,y(i)+Ky3*h);
    Ky4= dydt(t(i+1),x(i)+Kx3*h,y(i)+Ky3*h);
    x(i+1) = x(i) + (Kx1+2*Kx2+2*Kx3+Kx4)*h/6;
    y(i+1) = y(i) + (Ky1+2*Ky2+2*Ky3+Ky4)*h/6;
end
```

---

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---

```
t
x
y
Xerror=exp(0.5*t.^2).*(cos(t)-0.5*sin(t))-x
Yerror=-exp(0.5*t.^2).*(-sin(t)-0.5*cos(t))-y
```

When the program is executed, the following results are displayed in the Command Window:

```
t =
      0      0.4000      0.8000      1.2000
x =
  1.0000      0.7869      0.4654     -0.2134
y =
  0.5000      0.9206      1.4675      2.2875
Xerror =
  1.0e-003 *
      0     -0.0026      0.1099      0.3956
Yerror =
  1.0e-003 *
      0      0.0922      0.0760     -0.4700
```

---

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**8.7** Write the following second-order ODE as a system of two first-order ODEs:

$$\left(\frac{dy}{dt}\right)\frac{d^2y}{dt^2} + 5\frac{dy}{dt} - 6y + \sin t = 0$$

**Solution**

Let  $y_1 = y$ ;  $y_2 = \frac{dy_1}{dt} = \frac{dy}{dt}$ ; This allows the ODE to be re-written as follows:

$$y_2 \frac{dy_2}{dt} + 5y_2 - 6y_1 + \sin t = 0$$
$$\text{or } \frac{dy_2}{dt} = \frac{-5y_2 + 6y_1 - \sin t}{y_2}$$

Therefore, the two first order ODEs are:

$$\frac{dy_1}{dt} = y_2, \text{ and}$$

$$\frac{dy_2}{dt} = \frac{-5y_2 + 6y_1 - \sin t}{y_2}$$

**8.8** Write the following second-order ODEs as systems of two first-order ODEs:

(a)  $EI \frac{d^2y}{dx^2} = -P \sin y + \frac{QL}{2}x - \frac{Q}{2}x^2$ , where  $E, I, P, Q$ , and  $L$  are constants.

(b)  $EI \frac{d^2y}{dx^2} = M \left[ 1 + \left( \frac{dy}{dx} \right)^2 \right]^{3/2}$ , where  $E, I$ , and  $M$  are constants.

**Solution**

(a) Define  $w = \frac{dy}{dx}$ ,  $\frac{dw}{dx} = \frac{d^2y}{dx^2}$ . With these definitions, the system of two first-order ODEs is:

$$\begin{aligned} \frac{dy}{dx} &= w \\ \frac{dw}{dx} &= \frac{1}{EI} \left( -P \sin y + \frac{QL}{2}x - \frac{Q}{2}x^2 \right) \end{aligned}$$

(b) Define  $w = \frac{dy}{dx}$ ,  $\frac{dw}{dx} = \frac{d^2y}{dx^2}$ . With these definitions, the system of two first-order ODEs is:

$$\begin{aligned} \frac{dy}{dx} &= w \\ \frac{dw}{dx} &= \frac{M}{EI} [1 + (w)^2]^{3/2} \end{aligned}$$

---

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**8.9** Write the following second-order ODEs as systems of two first-order ODEs:

$$(a) \frac{1}{g} \frac{d^2 h}{dt^2} = \frac{T}{w} - 1 - \frac{0.008}{w} \left( \frac{dh}{dt} \right)^2, \text{ where } g, T, \text{ and } w \text{ are constants.}$$

$$(b) \frac{d^2 Q}{dt^2} + \frac{500}{15} \frac{dQ}{dt} + \frac{250}{15} \left( \frac{dQ}{dt} \right)^3 + \frac{Q}{15 \cdot 4.2 \times 10^{-6}} = \frac{1000}{15}.$$

**Solution**

(a) Define  $u = \frac{dh}{dt}$ ,  $\frac{du}{dt} = \frac{d^2 h}{dt^2}$ . With these definitions, the system of two first-order ODEs is:

$$\begin{aligned} \frac{dh}{dt} &= u \\ \frac{du}{dt} &= \frac{gT}{w} - g - \frac{0.008g}{w} u^2 \end{aligned}$$

(b) Define  $u = \frac{dQ}{dt}$ ,  $\frac{du}{dt} = \frac{d^2 Q}{dt^2}$ . With these definitions, the system of two first-order ODEs is:

$$\begin{aligned} \frac{dQ}{dt} &= u \\ \frac{du}{dt} &= \frac{1000}{15} - \frac{500}{15} u - \frac{250}{15} u^3 - \frac{Q}{15 \cdot 4.2 \times 10^{-6}} \end{aligned}$$

---

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**8.10** Consider the following second-order ODE:

$$\frac{d^2y}{dx^2} - 1.8\frac{dy}{dx} + 0.8y = 0 \quad \text{from } x = 0 \text{ to } x = 3, \text{ with } y(0) = 1 \text{ and } \left.\frac{dy}{dx}\right|_{x=0} = 0.5$$

(a) Solve with Euler's explicit method using  $h = 1$ .

(b) Solve with the modified Euler method using  $h = 1$ .

**Solution**

Define  $w = \frac{dy}{dx}$ ,  $\frac{dw}{dx} = \frac{d^2y}{dx^2}$ . With these definitions, the system of two first-order ODEs is:

$$\frac{dy}{dx} = w \quad \text{with} \quad y(0) = 1$$

$$\frac{dw}{dx} = 1.8w - 0.8y \quad \text{with} \quad w(0) = 0.5$$

(a) The following script file solves the system of the ODEs with Euler's explicit method using  $h = 1$ .

```
clear, clc
dydx = @ (w) w;
dwdx = @ (w,y) 1.8*w-0.8*y;
w(1) = 0.5; y(1) = 1;
x(1)=0;
h = 1;
N=3;
for i = 1:N
    x(i+1) = x(i) + h;
    y(i+1) = y(i) + dydx(w(i))*h;
    w(i+1) = w(i) + dwdx(w(i),y(i))*h;
end
x
y
w
```

---

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When the program is executed, the following results are displayed in the Command Window:

```
x =  
    0     1     2     3  
y =  
  1.0000    1.5000    2.1000    2.5800  
w =  
  0.5000    0.6000    0.4800   -0.3360
```

(b) The following script file solves the system of the ODEs with the modified Euler method using  $h = 1$ .

```
clear, clc  
dydx = @ (w) w;  
dwdx = @ (w,y) 1.8*w-0.8*y;  
w(1) = 0.5; y(1) = 1;  
x(1)=0;  
h = 1;  
N=3;  
for i = 1:N  
    x(i+1) = x(i) + h;  
    yEU = y(i) + dydx(w(i))*h;  
    wEU = w(i) + dwdx(w(i),y(i))*h;  
    y(i+1) = y(i) + (dydx(w(i))+dydx(wEU))*h/2;  
    w(i+1) = w(i) + (dwdx(w(i),y(i))+dwdx(wEU,yEU))*h/2;  
  
end  
x  
y  
w
```

When the program is executed, the following results are displayed in the Command Window:

```
x =
```

---

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---

	0	1	2	3
$Y =$	1.0000	1.5500	1.8610	0.3828
$w =$	0.5000	0.4900	-0.3862	-4.3812

---

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**8.11** Consider the following second-order ODE:

$$\frac{d^2y}{dx^2} = 1.5(e^{3x} - y^2)^{1/2} \quad \text{from } x = 0 \text{ to } x = 1.5, \text{ with } y(0) = 0 \text{ and } \left. \frac{dy}{dx} \right|_{x=0} = 1$$

(a) Solve with Euler's explicit method using  $h = 0.5$ .

(b) Solve with the classical fourth-order Runge–Kutta method using  $h = 0.5$ .

**Solution**

Define  $w = \frac{dy}{dx}$ ,  $\frac{dw}{dx} = \frac{d^2y}{dx^2}$ . With these definitions, the system of two first-order ODEs is:

$$\frac{dy}{dx} = w \quad \text{with} \quad y(0) = 0$$

$$\frac{dw}{dx} = 1.5(e^{3x} - y^2)^{1/2} \quad \text{with} \quad w(0) = 1$$

(a) The following script file solves the system of the ODEs with Euler's explicit method using  $h = 0.5$ .

```
clear, clc
dydx = @ (w) w;
dwdx = @ (x,y) 1.5*(exp(3*x)-y^2)^(1/2);
w(1) = 1; y(1) = 0;
x(1)=0;
h = 0.5;
N=3;
for i = 1:N
    x(i+1) = x(i) + h;
    y(i+1) = y(i) + dydx(w(i))*h;
    w(i+1) = w(i) + dwdx(x(i),y(i))*h;
end
x
y
w
```

---

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When the program is executed, the following results are displayed in the Command Window:

```
x =  
      0      0.5000      1.0000      1.5000  
y =  
      0      0.5000      1.3750      3.0214  
w =  
  1.0000      1.7500      3.2928      6.4920
```

(b) The following script file solves the system of the ODEs with the classical fourth-order Runge–Kutta method using  $h = 0.5$ .

```
clear, clc  
dydx = @ (w) w;  
dwdx = @ (x,y) 1.5*(exp(3*x)-y^2)^(1/2);  
w(1) = 1; y(1) = 0;  
x(1)=0;  
h = 0.5;  
N=3;  
for i = 1:N  
    x(i+1) = x(i) + h;  
    xm = x(i) + h/2;  
    Kw1 = dwdx(x(i),y(i));  
    Ky1 = dydx(w(i));  
    Kw2 = dwdx(xm,y(i)+Ky1*h/2);  
    Ky2 = dydx(w(i)+Kw1*h/2);  
    Kw3 = dwdx(xm,y(i)+Ky2*h/2);  
    Ky3 = dydx(w(i)+Kw2*h/2);  
    Kw4 = dwdx(x(i+1),y(i)+Ky3*h);  
    Ky4 = dydx(w(i)+Kw3*h);  
    w(i+1) = w(i) + (Kw1 + 2*Kw2 + 2*Kw3 + Kw4)*h/6;  
    y(i+1) = y(i) + (Ky1 + 2*Ky2 + 2*Ky3 + Ky4)*h/6;  
end
```

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---

x  
y  
w

When the program is executed, the following results are displayed in the Command Window:

```
x =  
    0    0.5000    1.0000    1.5000  
y =  
    0    0.7404    2.2517    5.2794  
w =  
  1.0000  2.0833  4.1937  8.4076
```

---

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**8.12** Write the following system of two second-order ODEs as a system of four first-order ODEs:

$$\frac{d^2x}{dt^2} = -\frac{\gamma}{m}\left(\frac{dx}{dt}\right)\sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} \quad \frac{d^2y}{dt^2} = -g - \frac{\gamma}{m}\left(\frac{dy}{dt}\right)\sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2}$$

**Solution**

Define  $w = \frac{dy}{dt}$ ,  $\frac{dw}{dt} = \frac{d^2y}{dt^2}$ , and  $u = \frac{dx}{dt}$ ,  $\frac{du}{dt} = \frac{d^2x}{dt^2}$

With these definitions, the system of four first-order ODEs is:

$$\frac{dx}{dt} = u \quad \frac{dy}{dt} = w$$

$$\frac{du}{dt} = -\frac{\gamma}{m}u\sqrt{u^2 + w^2}, \quad \frac{dw}{dt} = -g - \frac{\gamma}{m}w\sqrt{u^2 + w^2}$$

---

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