
MCG 3130

DGD 4

OCTOBER 3, 2014

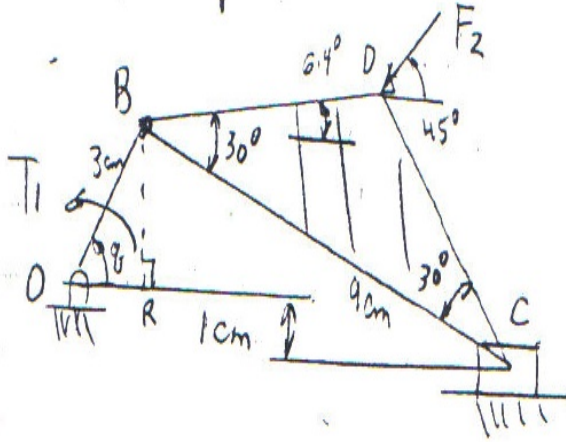
Pls Note:

First Question is the **BOARD PROBLEM QUESTION**
(VIRTUAL WORK)

Second question, will be the **ASSIGNED QUESTIONS To Students**
(Vector statics)

Question 1: Board Problem: Using Virtual Work Principle

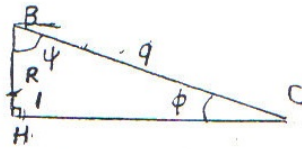
-2-V.W. Example



Find - T_1
Given $\theta = 60^\circ$
 $F_2 = 200\text{N}$

SOLUTION:

Position



$$\sin \phi = \frac{3 \sin 60 + 1}{9} = \frac{3.598}{9} = 0.4$$

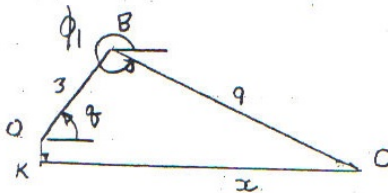
$$\phi = 23.6^\circ$$

$$\psi = 66.4^\circ$$

$$HC = 9 \cos \phi = 8.247$$

$$OR = 3 \cos 60 = 1.5$$

$$x = 9.747$$



Position

$$3 \cos \theta + 9 \cos \phi_1 - x = 0$$

$$3 \sin \theta + 9 \sin \phi_1 + KO = 0$$

Inverse

Diff wrt time

$$-9 \sin \phi_1 \dot{\phi}_1 - \dot{x} = 3 \sin \theta \dot{\theta}$$

$$9 \cos \phi_1 \dot{\phi}_1 = -3 \cos \theta \dot{\theta}$$

$$3.60 \dot{\phi}_1 - \dot{x} = 2.598 \dot{\theta}$$

$$8.25 \dot{\phi}_1 = -1.5 \dot{\theta}$$

$$\theta = 60^\circ$$

$$\phi_1 = 360 - 23.6^\circ$$

$$= 336.4^\circ$$

$$\dot{\phi}_1 = -\frac{1.5}{8.25} \dot{\theta}$$

$$= -0.182 \dot{\theta}$$

$$\dot{x} = [3.6(-0.182) - 2.598] \dot{\theta}$$

$$= -3.25 \dot{\theta}$$

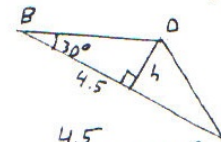
Forward

$$x_D = 3 \cos \theta + 5.196 \cos (\phi_1 + 30^\circ)$$

$$y_D = 3 \sin \theta + 5.196 \sin (\phi_1 + 30^\circ)$$

$$\dot{x}_D = -3 \sin \theta \dot{\theta} - 5.196 \sin (\phi_1 + 30^\circ) \dot{\phi}_1 = [-2.598 - 0.579 \times (-0.182)] \dot{\theta}$$

$$\dot{y}_D = -3 \cos \theta \dot{\theta} + 5.196 \cos (\phi_1 + 30^\circ) \dot{\phi}_1 = [1.5 + 5.164 \times (-0.182)] \dot{\theta}$$



$$\frac{4.5}{BD} = \cos 30^\circ =$$

$$BD = \frac{4.5}{0.866} = 5.196$$

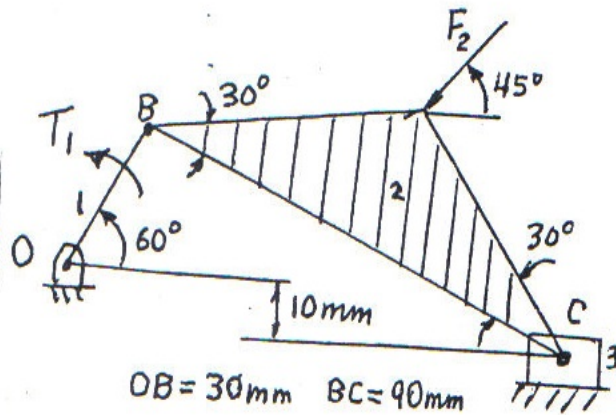
VW Eqn $\sum \underline{F}_m \cdot \underline{V}_m + \sum \underline{T}_n \cdot \underline{W}_n = 0$

$$(-200 \cos 45^\circ \underline{i} - 200 \sin 45^\circ \underline{j}) \cdot (-2.49 \underline{i} + 0.560 \underline{j}) + T_1 \underline{k} \cdot \dot{\theta} \underline{k} = 0$$

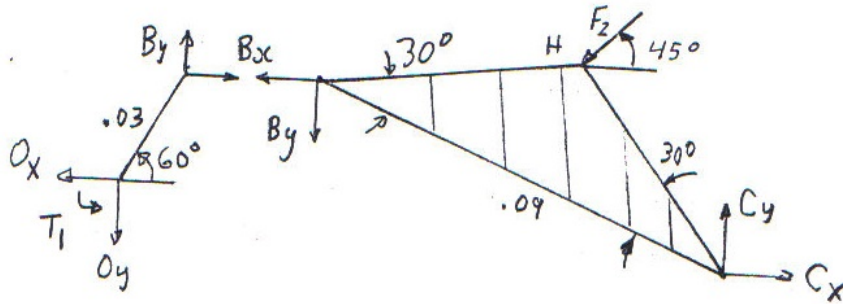
$$T_1 = -279.9 \text{ N}$$

Question 2: Assigned Problem: Using Vector static method.

Determine the required input torque T_1 for static equilibrium of the mechanism shown. Force F_2 has a magnitude of 200 N.



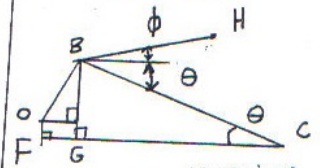
SOLN:



$$F_2 = 200 \text{ N}$$

$$F_x = F_y = 200/\sqrt{2} = 141.4$$

Geometry



$$\sin \theta = \frac{10 + 30 \sin 60^\circ}{90} = 0.4$$

$$\theta = 23.56^\circ \quad \phi = 30^\circ - \theta$$

$$\approx 24^\circ \quad = 6^\circ$$

$$\frac{0.045}{BH} = \cos 30^\circ$$

$$BH = 0.052 \text{ m}$$

$$C_x = 0 \quad \text{no friction}$$

Member BC $\sum F_x = 0 \quad -B_x - F_x = 0$

$$\sum F_y = 0 \quad C_y - B_y - F_y = 0$$

$$\sum M_B = 0 \quad 0.09 \cos 24^\circ C_y + BH \sin 6^\circ F_x - BH \cos 6^\circ F_y = 0$$

$$C_y = 79.5 \text{ N} \quad B_x = -141.4 \text{ N}$$

$$B_y = -61.8 \text{ N}$$

Member OB $T_1 - 0.03 \sin 60^\circ B_x + 0.03 \cos 60^\circ B_y = 0$

$$T_1 = -2.75 \text{ Nm}$$