

INFINITE SEQUENCES

Review

Let $\{a_n\}$ be a sequence. If $\lim_{n \rightarrow +\infty} a_n = L$ then the sequence converges.

If $\lim_{n \rightarrow +\infty} a_n$ results in either one of the following

forms: $\frac{0}{0}, \frac{\infty}{\infty}, 0^0, \infty^0, 1^\infty, \infty - \infty$ use

L'Hopital's Rule to evaluate the limit.

L'Hopital's Rule

$$\lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \lim_{x \rightarrow a} \frac{f'(x)}{g'(x)}$$

Properties of Sequences

Suppose that $\{a_n\}$ and $\{b_n\}$ be two convergent sequences with $\lim_{n \rightarrow +\infty} a_n = L$ and

$\lim_{n \rightarrow +\infty} b_n = M$ then the following results are true

Name	Property
Constant	$\lim_{n \rightarrow +\infty} c = c$
Constant Multiple	$\lim_{n \rightarrow +\infty} c a_n = c \lim_{n \rightarrow +\infty} a_n = cL$
Additive	$\lim_{n \rightarrow +\infty} (a_n + b_n) = \lim_{n \rightarrow +\infty} a_n + \lim_{n \rightarrow +\infty} b_n = L + M$
Difference	$\lim_{n \rightarrow +\infty} (a_n - b_n) = \lim_{n \rightarrow +\infty} a_n - \lim_{n \rightarrow +\infty} b_n = L - M$
Product	$\lim_{n \rightarrow +\infty} (a_n b_n) = \lim_{n \rightarrow +\infty} a_n \cdot \lim_{n \rightarrow +\infty} b_n = LM$
Quotient	$\lim_{n \rightarrow +\infty} \frac{a_n}{b_n} = \frac{\lim_{n \rightarrow +\infty} a_n}{\lim_{n \rightarrow +\infty} b_n} = \frac{L}{M}$ provided that $M \neq 0$
Squeeze Theorem For Sequences	Let $\{a_n\}, \{b_n\},$ and $\{c_n\}$ be sequences such that $\{a_n\} \leq \{c_n\} \leq \{b_n\}$. If $\lim_{n \rightarrow +\infty} a_n = L$ and $\lim_{n \rightarrow +\infty} b_n = L \Rightarrow \lim_{n \rightarrow +\infty} c_n = L$

TESTS TO DETERMINE THE CONVERGENCE/DIVERGENCE OF A SERIES

Name	What Does It Say
Integral Test	$\sum a_k$ is a series of positive terms

	and $f(x) = A_k$. If the function is decreasing and continuous on $[a, +\infty)$, then the series converges if $\int_a^{+\infty} f(x) dx$ is defined. The series diverges if $\int_a^{+\infty} f(x) dx = \pm \infty$
Divergence Test	$\sum a_k$ diverges if $\lim_{k \rightarrow +\infty} a_k \neq 0$
Ratio Test	$\sum a_k$ is a series of positive terms with $p = \lim_{k \rightarrow +\infty} \frac{a_{k+1}}{a_k}$ If $p > 1 \Rightarrow$ the series diverges. If $p < 1 \Rightarrow$ the series converges. If $p = 1 \Rightarrow$ no conclusion.
Root Test	$\sum a_k$ is a series of positive terms with $p = \lim_{k \rightarrow +\infty} \sqrt[k]{a_k}$ If $p > 1 \Rightarrow$ the series diverges. If $p < 1 \Rightarrow$ the series converges. If $p = 1 \Rightarrow$ no conclusion.
Comparison Test	Suppose that $\sum_1^\infty a_k$ and $\sum_1^\infty b_k$ are two series with positive terms such that $a_k \leq b_k$ for all k . If $\sum_1^\infty b_k$ converges, then $\sum_1^\infty a_k$ converges. If $\sum_1^\infty a_k$ diverges, then also $\sum_1^\infty b_k$ diverges.
Limit Comparison Test	Suppose that $\sum_1^\infty a_k$ and $\sum_1^\infty b_k$ are two series with positive terms with $p = \lim_{k \rightarrow +\infty} \frac{a_k}{b_k}$ If $p > 0 \Rightarrow$ either both series converge, or both series diverge.
Name	What Does It Say
Alternating Series Test	Suppose that $a_k > 0$ for $k = 1, 2, 3, \dots$ then the series has the form of either: $a_1 - a_2 + a_3 - a_4 + \dots$ or

	$-a_1 + a_2 - a_3 + a_4 - \dots$ The series converges if and only if 1. $a_{k+1} \leq a_k$ and the series is decreasing, and 2. $\lim_{k \rightarrow +\infty} a_k = 0$
Ratio Test Absolute Convergence	$\sum a_k$ is a series of nonzero terms with $p = \lim_{k \rightarrow +\infty} \left \frac{a_{k+1}}{a_k} \right $ If $p > 1 \Rightarrow$ the series diverges. If $p < 1 \Rightarrow$ the series converges. If $p = 1 \Rightarrow$ no conclusion.

POWER OF SERIES AND RADIUS OF CONVERGENCE

Form	Sigma Notation	Radius of Convergence
$\frac{1}{1-x} = 1 + x + x^2 + x^3 + x^4 + \dots$	$= \sum_1^\infty x^n$	$-1 \leq x \leq 1$
$\frac{1}{(1-x)^2} = 1 + 2x + 3x^2 + 4x^3 + \dots$	$= \sum_1^\infty n x^{n-1}$	$-1 \leq x \leq 1$
$\ln(x+1) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots$	$= \sum_1^\infty (-1)^n \frac{x^n}{n}$	$-1 \leq x \leq 1$
$\arctan x = x - \frac{x^3}{3} + \frac{x^5}{5} - \frac{x^7}{7} + \dots$	$= \sum_1^\infty (-1)^n \frac{x^{2n+1}}{2n+1}$	$-1 \leq x \leq 1$
$e^x = 1 + \frac{x}{1!} + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \dots$	$= \sum_1^\infty \frac{x^n}{n!}$	$(-\infty, \infty)$
$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \frac{x^9}{9!} - \dots$	$= \sum_1^\infty (-1)^n \frac{x^{2n+1}}{(2n+1)!}$	$(-\infty, \infty)$
$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \frac{x^8}{8!} - \dots$	$= \sum_1^\infty (-1)^n \frac{x^{2n}}{(2n)!}$	$(-\infty, \infty)$

VECTORS AND COORDINATE GEOMETRY

Vectors & Vector Dot Products

Let \vec{u} be a vector having n components, then the length or norm of is \vec{u} defined to be

$$|\vec{u}| = \sqrt{(n_1)^2 + (n_2)^2 + (n_3)^2 + \dots + (n_n)^2}$$





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Let \vec{u} and \vec{v} be two vectors, then their dot product is defined to be:

$$\vec{u} \cdot \vec{v} = |\vec{u}| |\vec{v}| \cos \theta$$

Properties

Symmetry	$\vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{u}$
Multiplication with a scalar	$(k\vec{u}) \cdot \vec{v} = k(\vec{u} \cdot \vec{v}) \quad k \in \mathbb{R}$
Linearity	$\vec{u}(\vec{v} + \vec{w}) = \vec{u} \cdot \vec{v} + \vec{u} \cdot \vec{w}$

Uses of Dot Product

- A. Show orthogonality: $\vec{u} \cdot \vec{v} = 0 \iff \vec{u} \perp \vec{v}$
 B. Finding the angle between two vectors:

$$\theta = \cos^{-1} \left(\frac{\vec{u} \cdot \vec{v}}{|\vec{u}| |\vec{v}|} \right)$$

Unit Vectors

Suppose that \vec{u} is a vector having n components, then its unit vector is found by dividing each component of the vector by its norm. That is,

$$\vec{u}_{unit} = \frac{1}{|\vec{u}|} \vec{u} = \frac{1}{\sqrt{(n_1)^2 + (n_2)^2 + (n_3)^2 + \dots + (n_n)^2}} \vec{u}$$

VECTOR VALUED FUNCTIONS

Tangent Directions

If $\vec{r}(t) = x(t)\hat{i} + y(t)\hat{j} + z(t)\hat{k}$ is a position vector to the points on the curve $(x(t), y(t), z(t))$ then we can find the following quantities

Average Velocity	$v_{avg} = \frac{\vec{r}(t + \Delta t) - \vec{r}(t)}{\Delta t}, \quad \Delta t = \text{change in time}$
Velocity	$v(t) = r'(t) = \frac{dx}{dt} \hat{i} + \frac{dy}{dt} \hat{j} + \frac{dz}{dt} \hat{k}$
Speed	$ \vec{v}(t) $
Acceleration	$a(t) = r''(t) = \frac{d^2x}{dt^2} \hat{i} + \frac{d^2y}{dt^2} \hat{j} + \frac{d^2z}{dt^2} \hat{k}$

Arc - length

$$s = s(t) = \int_{t_0}^t |\vec{r}'(t)| dt$$

Formulas for Curvature, Torsion, Radius of Curvature

Name	Formula
Unit Tangent Vector	$\vec{T} = \frac{\vec{v}}{ \vec{v} }$
Curvature	$\kappa = \frac{ \vec{v} \times \vec{a} }{ \vec{v} ^3}$
Radius of Curvature	$\rho = \frac{1}{\kappa}$
Binormal Vector	$\vec{B} = \frac{\vec{v} \times \vec{a}}{ \vec{v} \times \vec{a} }$
Unit Normal Vector	$\vec{N} = \vec{B} \times \vec{T} = \frac{d\vec{T}}{ds}$
Tangential and Normal Components	$\vec{a} = \frac{dv}{dt} \vec{T} + \vec{v} ^2 \kappa \vec{N}$
Torsion	$\tau = \frac{(\vec{v} \times \vec{a}) \cdot \frac{d\vec{a}}{dt}}{ \vec{v} \times \vec{a} ^2}$

Frenet - Serret Formulas

$\frac{d\vec{T}}{ds} = \kappa \vec{N}$	$\frac{d\vec{B}}{ds} = -\tau \vec{N}$	$\frac{d\vec{N}}{ds} = -\kappa \vec{T} + \tau \vec{B}$
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PARTIAL DIFFERENTIATION

Definition of Limit on a plane

$$\lim_{(x,y) \rightarrow (a,b)} f(x,y) = L$$

Implies that

- A. Every neighborhood of (a, b) contains points of the domain of $f(x, y)$ different from (a, b).
 B. For every ϵ (positive) there exists a positive δ such that $|f(x, y) - L| < \epsilon$ whenever (x, y) is in the domain of f and satisfies the inequality: $0 < \sqrt{(x-a)^2 + (y-b)^2} < \delta$

Definition of Continuity on a Plane

For continuity to happen, the following 2 conditions must hold:

1. $\lim_{(x,y) \rightarrow (a,b)} f(x, y)$ exists

$$2. \lim_{(x,y) \rightarrow (a,b)} f(x, y) = f(a, b)$$

Partial Derivatives

Given a function $f(x, y)$, the partial with respect to x , denoted as f_x , at the point (a, b) is defined to be

$$f_x(a, b) = \lim_{h \rightarrow 0} \frac{f(a+h, b) - f(a, b)}{h}$$

Similarly the partial with respect to y , at the point (a, b) , denoted as f_y , is defined to be

$$f_y = \lim_{k \rightarrow 0} \frac{f(a, b+k) - f(a, b)}{k}$$

In practice we use the following

$f_x = f_1 = \frac{\partial f}{\partial x}$	\Rightarrow	differentiate the function f with respect to x while holding all other variables as constants.
$f_y = f_2 = \frac{\partial f}{\partial y}$	\Rightarrow	differentiate the function f with respect to y while holding all other variables as constants.

The idea can easily be extended to functions having more than 2 variables.

Higher Derivatives

Second derivatives for functions of 2 variables

$f_{xx} = f_{11} = \frac{\partial^2 f}{\partial x^2} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right)$	Second derivative of f with respect to x
$f_{yy} = f_{22} = \frac{\partial^2 f}{\partial y^2} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial y} \right)$	Second derivative of f with respect to y
$f_{xy} = f_{12} = \frac{\partial^2 f}{\partial y \partial x} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right)$	Mixed partial
$f_{yx} = f_{21} = \frac{\partial^2 f}{\partial x \partial y} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right)$	Mixed partial

Chain Rule

$z = f(x, y)$ is a differentiable function of x and y with $x = x(t)$ and $y = y(t)$ then

$$z'(t) = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt}$$



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Example: $z(x, y) = x \sin y$ where $x(t) = e^t$ and $y(t) = t^2$

Solution:

$$z'(t) = \frac{\partial z}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial t}$$

$$\frac{\partial x}{\partial t} = e^t \quad \frac{\partial y}{\partial t} = 2t$$

$$\frac{\partial z}{\partial x} = \sin y \quad \frac{\partial z}{\partial y} = x \cos y$$

$$z'(t) = e^t \sin y + 2tx \cos y$$

The chain rule can be extended to include functions which have more than one variable.

Let Z be a differentiable function of n variables, $X_1, X_2, X_3, \dots, X_n$ and each X_j is a

differentiable function of m variables, $t_1, t_2, t_3, \dots, t_m$ then Z is ultimately a function of $t_1, t_2, t_3, \dots, t_m$. So

$$\frac{\partial z}{\partial t_i} = \frac{\partial z}{\partial x_1} \frac{\partial x_1}{\partial t_i} + \frac{\partial z}{\partial x_2} \frac{\partial x_2}{\partial t_i} + \dots + \frac{\partial z}{\partial x_n} \frac{\partial x_n}{\partial t_i}$$

Tangent Planes & Gradients

Suppose that $z = f(x, y)$ has tangent planes everywhere, then the gradient is:

$$\nabla f(x, y) = \hat{i} \frac{\partial}{\partial x}(x, y) + \hat{j} \frac{\partial}{\partial y}(x, y)$$

$\nabla f(x, y)$ = Direction of the steepest slope upwards in the XY plane

$-\nabla f(x, y)$ = Direction of the steepest slope downwards in the XY plane.

$\|\nabla f(x, y)\|$ = Slope in steepest direction

$D_u f = \hat{u} \cdot \nabla f$ = Directional derivative of f with respect to \hat{u}

$\hat{u} + \hat{k} D_u f$ = Tangent vector with respect to \hat{u} direction

$\hat{k} - \nabla f$ = Upward normal vector to the surface
= Perpendicular to all tangent vectors
= Normal vector to the tangent plane.

LOCAL EXTREMAS

Suppose that the surface $z = f(x, y)$ has tangent planes at every point. The points (x_0, y_0, z_0) on the surface where the tangent plane is horizontal

$\Rightarrow \nabla f|_{(x_0, y_0)} = 0$, are called critical point (local extrema).

$D_u^2 f$ positive for all $\theta \Rightarrow$ nearby slopes are up
 \Rightarrow surface bends up
 \Rightarrow local minimum

$D_u^2 f$ negative for all $\theta \Rightarrow$ nearby slopes are down
 \Rightarrow surface bends down
 \Rightarrow local maximum

$D_u^2 f$ changes slope \Rightarrow nearby slopes is up in some directions and down in other directions
 \Rightarrow surface bends up and down
 \Rightarrow saddle

The test can be expressed in terms of the Jacobian matrix

$$D = \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial x \partial y} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

If $\det(D) < 0 \Rightarrow$ we have a saddle point

If $\det(D) < 0$ and $a + c > 0 \Rightarrow$ we have a local minimum

If $\det(D) < 0$ and $a + c < 0 \Rightarrow$ we have a local maximum

Lagrange Multipliers

To find the extreme values:

1. First get it into a Lagrangian function: $L(x, y) = f(x, y) + \lambda g(x, y)$

2. Solve for the critical point by finding out when

$$0 = \frac{\partial L}{\partial x} = f_x(x, y) + \lambda g_x(x, y) \quad 0 = \frac{\partial L}{\partial y} = f_y(x, y) + \lambda g_y(x, y) \quad 0 = \frac{\partial L}{\partial \lambda} = g(x, y)$$

3. Once the critical points have been found, plug it back into the function and test to see which point satisfies the given criteria.



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