

2.4 Examples of use of quasilinear 1st order PDES

2.4.1 Conservation laws (general)

- Conservation laws are usually written in the form

$$\frac{\partial u}{\partial t} + \frac{\partial}{\partial x} (F(u, x, t)) = 0$$

(or, in more than one dimension

$$\frac{\partial u}{\partial t} + \nabla \cdot (F(u, \underline{r}, t)) = 0 \dots)$$

- Why is this called a conservation law?

⇒ Expressed in their integral form, the conservation law describes the conservation of the quantity u :

$$\int_D \frac{\partial u}{\partial t} d^3 \underline{r} + \int_D \nabla \cdot (F(u, \underline{r}, t)) d^3 \underline{r} = 0$$

$$\Leftrightarrow \frac{\partial}{\partial t} \int_D u d^3 \underline{r} + \int_{S=D} F(u, \underline{r}, t) d^2 \underline{r} = 0$$

↑
total change
of the quantity
 u in the domain
 D

$S =$
contour
of D

↑
Flux through
the surface of
the domain

Example: The standard equation for the conservation of mass in a flow stirred by a velocity field $v(\underline{r})$ is

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho v(\underline{r})) = 0$$

It can be rewritten as

$$\int_D \frac{\partial \rho}{\partial t} d^3 r + \int_D \nabla \cdot (\rho \mathbf{v}(r)) d^3 r = 0$$

$$\Leftrightarrow \frac{\partial m}{\partial t} + \int_{\text{surface of } D} \rho \mathbf{v}(r) d^2 r = 0$$

↗ change of mass within volume D
 ↖ mass carried by velocity field across surface of D

- Conservation laws occur in most domains in science.

2.4.2 Conservation law (specific)

Here for simplicity we consider conservation laws which can be written as

$$\begin{cases} \frac{\partial u}{\partial t} + \frac{\partial}{\partial x} (F(u)) = 0 \\ u(x, 0) = \phi(x) \end{cases}$$

(the flux is a function of u only)

Then we see that

$$\frac{\partial u}{\partial t} + F'(u) \frac{\partial u}{\partial x} = 0$$

→ a quasilinear homogeneous PDE that can be integrated with

$$\begin{cases} \frac{\partial t}{\partial z} = 1 & \rightarrow t = z \\ \frac{\partial x}{\partial z} = F'(u) & (*) \\ \frac{\partial u}{\partial z} = 0 & \rightarrow u \text{ is constant along characteristics:} \end{cases}$$

$$u = u_0(s) = \phi(s)$$

So from (*) we see that

$$\frac{\partial x}{\partial z} = F'(\phi(s)) \rightarrow x = F'(\phi(s))z + x_0(s)$$

in other words

$$\left\{ \begin{array}{l} z = t \\ x = F'(\phi(s))t + s \\ u = \phi(s) \end{array} \right\} \text{ so } u = \phi(x - F'(u)t)$$

Interpretation

- ① u is constant on characteristics
- ② The characteristics are straight lines in the $(x-t)$ plane with slope $\frac{1}{F'(\phi(s))}$, which depends only on the initial condition (and on F' .)
- ③ The problem of finding $u(x,t)$ becomes equivalent to solving the algebraic equation
$$u = \phi(x - F'(u)t)$$

It is sometimes possible to invert this analytically.

2.4.3 Burger's inviscid equation (Euler's equation)

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = 0$$

$$\Rightarrow \frac{\partial u}{\partial t} + \frac{\partial}{\partial x} \left(\frac{u^2}{2} \right) = 0 \quad \rightarrow \text{a conservation law with } F(u) = \frac{u^2}{2}$$

$$F'(u) = u$$

so the solution for any given initial condition $u(x,0) = \phi(x)$ can formally be written as

$$u(x,t) = \phi(x - u(x,t)t)$$

which may or may not be solvable analytically

① Suppose

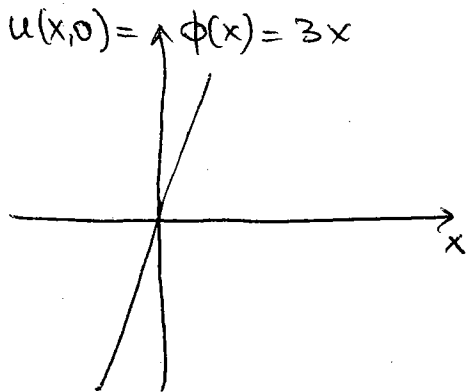
$$\phi(x) = 3x \quad \text{then}$$

$$u(x, t) = 3(x - u(x, t)t)$$

$$\Rightarrow u(x, t) [1 + 3t] = 3x$$

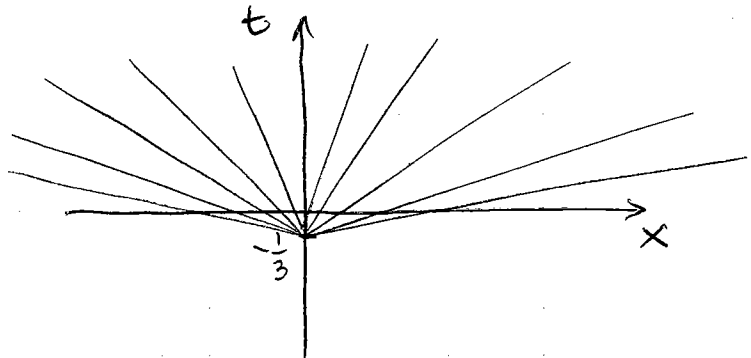
$$\Rightarrow u(x, t) = \frac{3x}{1 + 3t}$$

Interpretation



Characteristics are lines in the $(x-t)$ plane with slope $\frac{1}{F'(\phi(s))}$

Here the slope is $\frac{1}{3s}$



$$C^{(s)} : x = 3s \cdot t + s$$

$$\Rightarrow t = \frac{x-s}{3s}$$

(they all pass through the point $(0, -\frac{1}{3})$)

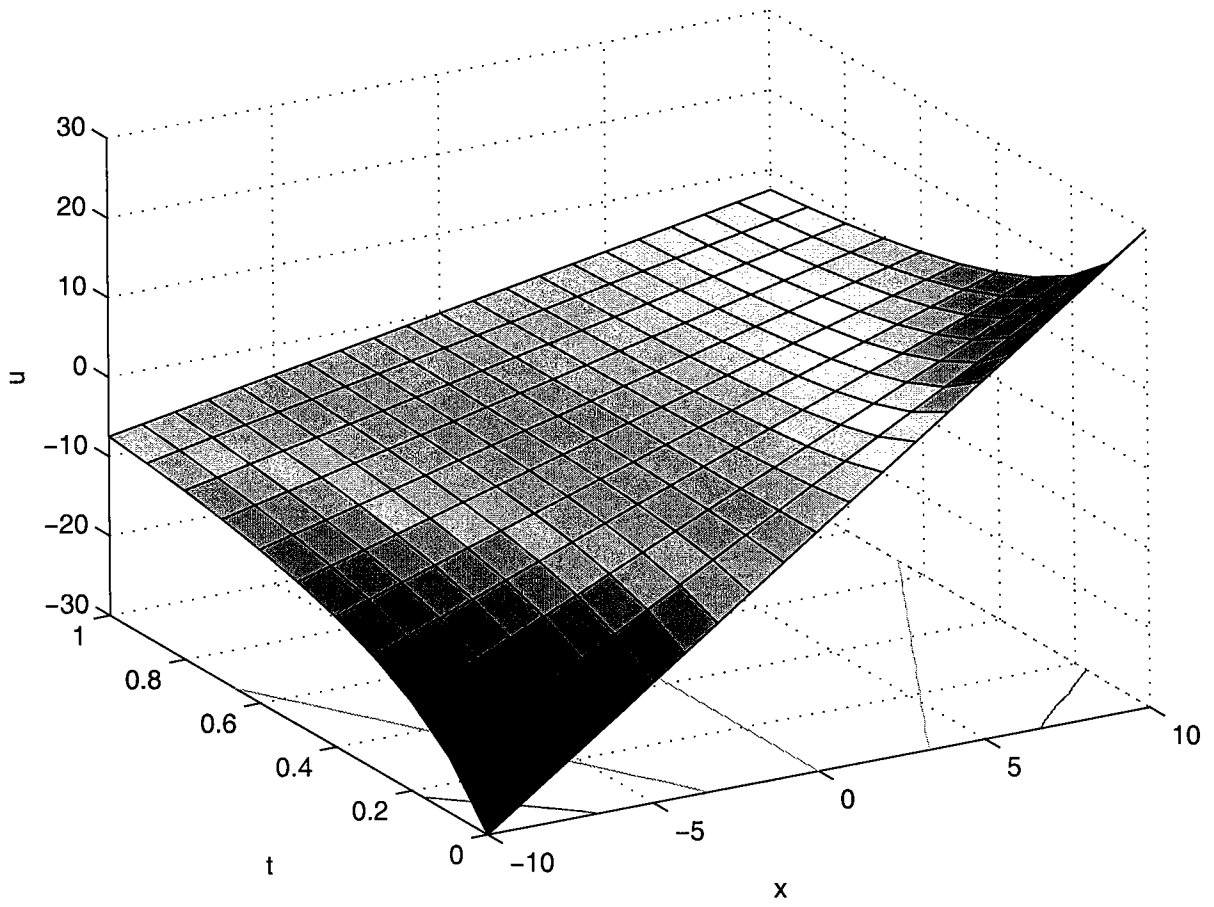
$u(x, t)$ is constant along a characteristic

② Suppose $\phi(x) = e^{-x^2/2}$

then we have to invert

$$u(x, t) = e^{-\left(x - u(x, t)t\right)^2/2}$$

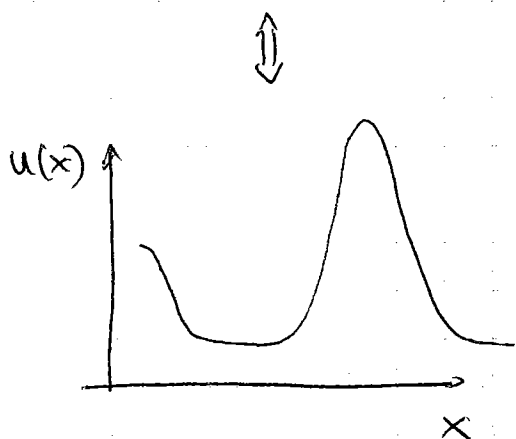
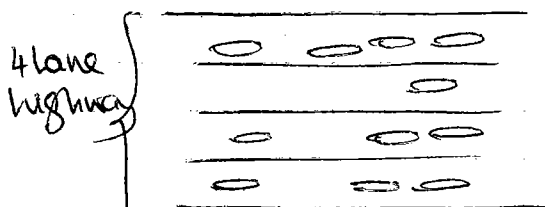
to find $u(x, t) \rightarrow$ difficult.



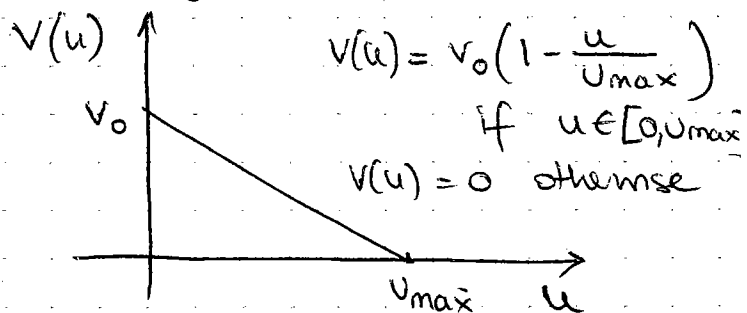
2.4.4 Traffic flow

The study of traffic flow is an attempt at modelling (for example) the flow of cars on a road/highway, but also for example of information on a network, etc..

Idea: ① Model the road/network as a 1D line, with some density $u(x, t)$ of traffic (cars/information packets) at time t , position x ...



② Model the velocity of the traffic flow as a function of the traffic density..



→ Flowing traffic has optimal velocity v_0 when u is small, and stalls when $u > u_{max}$.

The conservation law for the car density $u(x, t)$ is simply

$$\frac{\partial u}{\partial t} + \frac{\partial}{\partial x} (u v(u)) = 0$$

$$\Leftrightarrow \frac{\partial u}{\partial t} + \frac{\partial}{\partial x} \left[v_0 u \left(1 - \frac{u}{u_{max}} \right) \right] = 0$$

So here we have a conservation law with

$$F(u) = v_0 u \left(1 - \frac{u}{u_{max}} \right) \quad \text{if } 0 \leq u < u_{max}$$

$$= 0 \quad \text{otherwise}$$

$$\Rightarrow F'(u) = v_0 \left(1 - \frac{u}{u_{\max}}\right) - \frac{v_0 u}{u_{\max}}$$

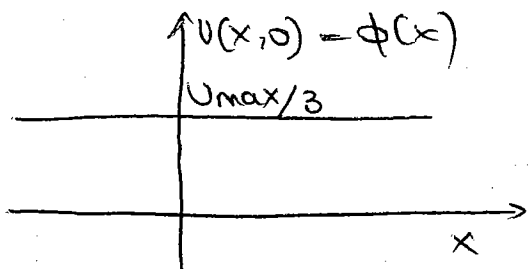
$$F'(u) = \begin{cases} v_0 \left(1 - \frac{2u}{u_{\max}}\right) & \text{if } u \in [0, u_{\max}] \\ 0 & \text{otherwise} \end{cases}$$

- The solution to any initial traffic condition $u(x, 0) = \phi(x)$ is given by the algebraic equation

$$u(x, t) = \phi(x - F(u), t)$$

- The solution $u(x, t)$ is constant along characteristics, which are straight lines with slope $\frac{1}{F'(\phi(s))}$

Example 1 Suppose we start with a uniform density of cars $u(x, 0) = \frac{u_{\max}}{3} \quad \forall x$.



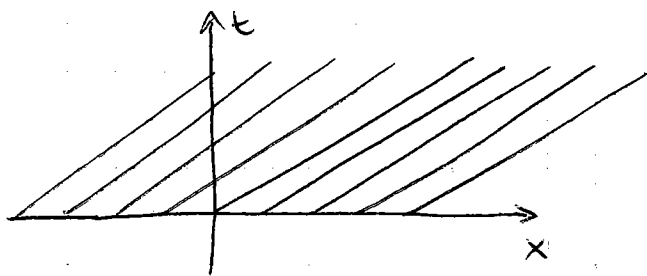
so $\phi(s) = \frac{u_{\max}}{3} \quad \forall s$.

The characteristics are straight lines with equation

$$x = F'(\phi(s))t + s$$

$$\Leftrightarrow x = F'\left(\frac{u_{\max}}{3}\right)t + s$$

$$\Leftrightarrow x = \frac{v_0}{3}t + s$$

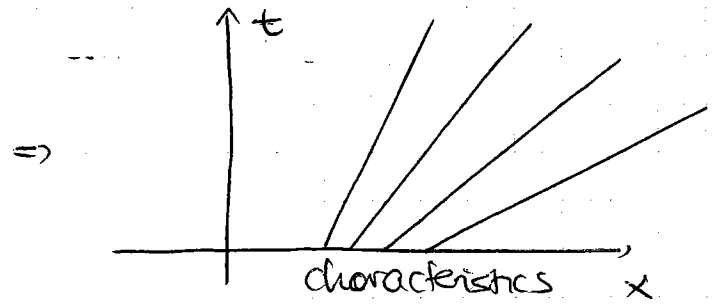
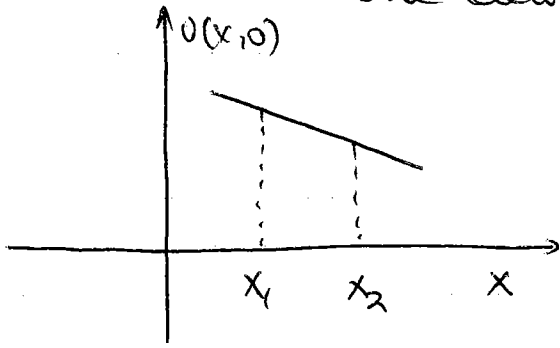


\rightarrow since u is constant along a characteristic, we see that traffic is smoothly flowing at velocity $\frac{v_0}{3}$ and

$$u(x, t) = \frac{u_{\max}}{3} \text{ is always constant}$$

Example 2

Suppose there is a local decrease in the density of cars with x ($U(x,0) < \frac{U_{max}}{2}$)



$$U(x_2,0) < U(x_1,0)$$

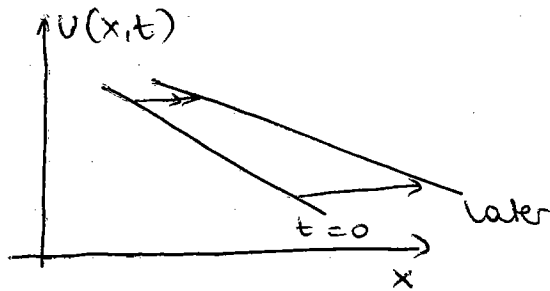
then $\phi(s_2) < \phi(s_1)$

$$\Rightarrow F'(s_2) > F'(s_1)$$

$$\Rightarrow \frac{1}{F'(s_2)} < \frac{1}{F'(s_1)}$$

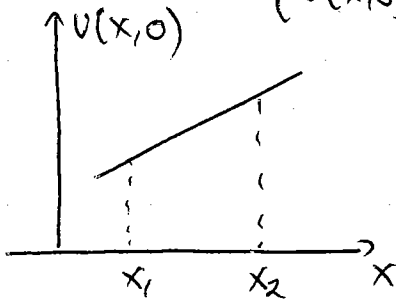
the slope of the characteristics in the (x,t) plane decreases

regions of less dense traffic move faster

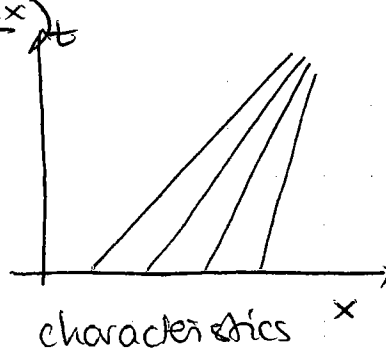


Example 3

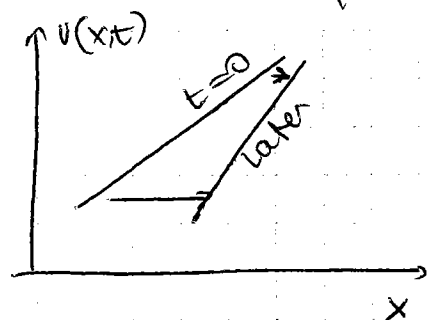
suppose there is a local increase in traffic ($U(x,0) > \frac{U_{max}}{2}$)



→

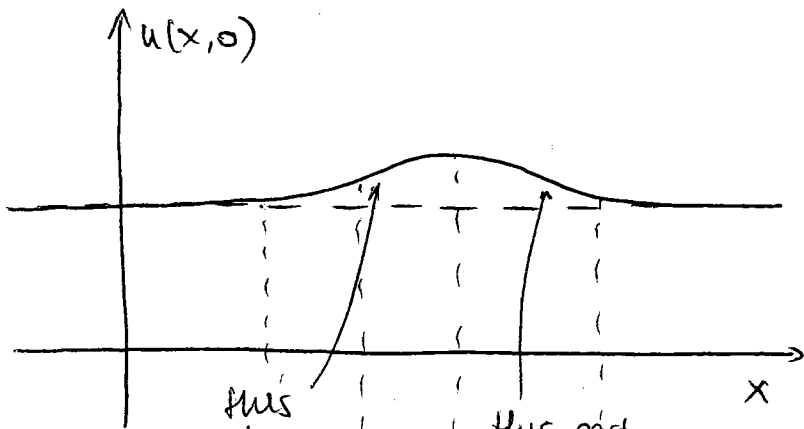


→



⇒ This behavior leads to the emergence of traffic waves spontaneously.

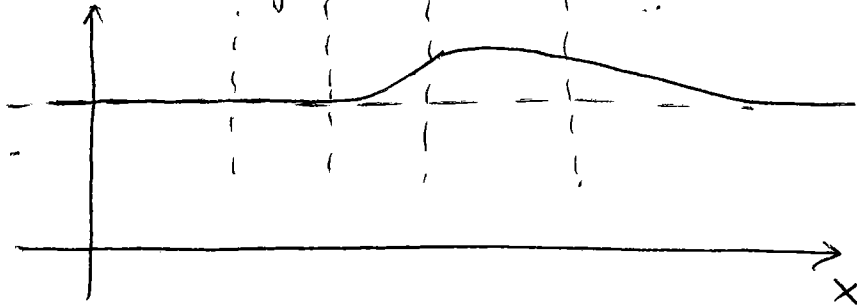
The traffic wave moves forward or backward depending on the density of traffic compared with $\frac{U_{max}}{2}$



initial small perturbation on otherwise smooth traffic

this part becomes steeper as moves forward

this part becomes shallower as moves forward



→ overall motion of perturbation .

Homework

what happens when $u > \frac{u_{max}}{2}$?