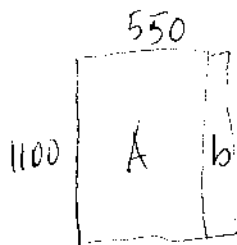


1. Complete the following phrase to make a true statement:

"A system of 1100 linear equations in 550 unknowns..."

- A. ... always has a solution. \times
 B. ... always has a unique solution. \times
 (C) ... may be inconsistent. \checkmark
 D. ... which is consistent always has a unique solution. \times
 E. ... which is consistent never has a unique solution. \times
 F. ... is never consistent. \times



2. If $\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & j \end{vmatrix} = 7$, find $\begin{vmatrix} 3a-5g & g & d \\ 3b-5h & h & e \\ 3c-5j & j & f \end{vmatrix} =$

$$\begin{vmatrix} 3a & g & d \\ 3b & h & e \\ 3c & j & f \end{vmatrix} = 3 \begin{vmatrix} a & g & d \\ b & h & e \\ c & j & f \end{vmatrix}$$

A. 7

B. 21

(C) -21

D. 35

E. -35

$$= 3 \begin{vmatrix} a & b & c \\ g & h & j \\ d & e & f \end{vmatrix}$$

$$= -3 \begin{vmatrix} a & b & c \\ d & e & f \\ g & h & j \end{vmatrix}$$

$= -21$

3. If $A = \begin{bmatrix} 3 & 2 \\ -1 & 0 \end{bmatrix}$ and $B^{-1} = \begin{bmatrix} 4 & 1 \\ 3 & 4 \end{bmatrix}$, then $(AB)^{-1} = B^{-1}A^{-1} = \begin{bmatrix} 4 & 1 \\ 3 & 4 \end{bmatrix} \cdot \frac{1}{2} \begin{bmatrix} 0 & -2 \\ 1 & 3 \end{bmatrix}$

A. $\begin{bmatrix} 1 & -5 \\ 2 & 3 \end{bmatrix}$ B. $\begin{bmatrix} 1/2 & -1/2 \\ -5 & 2 \end{bmatrix}$ C. $\begin{bmatrix} 1/2 & -5/2 \\ 2 & 3 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & -5 \\ 4 & 6 \end{bmatrix}$

D. $\begin{bmatrix} 1 & 2 \\ -5/2 & 3/2 \end{bmatrix}$ E. $\begin{bmatrix} 1 & 3 \\ 5 & 3 \end{bmatrix}$ F. $\begin{bmatrix} -1 & -3/2 \\ 5/2 & 2 \end{bmatrix} = \begin{bmatrix} 1/2 & -5/2 \\ 2 & 3 \end{bmatrix}$

4. If c_j denotes the j^{th} column of

$$A = \begin{bmatrix} 1 & 4 & -1 & -2 \\ 3 & 1 & 0 & 5 \\ 4 & 5 & -1 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & 4 & -1 & -2 \\ 3 & 1 & 0 & 5 \\ 0 & 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 4 & -1 & -2 \\ 0 & -11 & * & * \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

($j = 1, \dots, 4$), which of the following sets is a basis for $U = \text{span}\{c_1, c_2, c_3, c_4\}$?

- A. $\{c_1\}$
- B. $\{c_2\}$
- C. $\{c_3\}$
- D. $\{c_1, c_2\}$
- E. $\{c_1, c_2, c_3\}$
- F. $\{c_1, c_3, c_4\}$

$$\sim \begin{bmatrix} 1 & 4 & * & * \\ 0 & -11 & * & * \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

5. Compute $\begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \end{bmatrix}^{2006}$

$$A \begin{bmatrix} 0 & I_2 \\ -I_2 & 0 \end{bmatrix} \begin{bmatrix} 0 & I_2 \\ -I_2 & 0 \end{bmatrix} = \begin{bmatrix} -I_2 & 0 \\ 0 & -I_2 \end{bmatrix} = -I_4 \therefore A^2 = -I_4$$

$$\therefore A^{2006} = (-I_4)^{1003} = -I_4$$

A. $\begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \end{bmatrix}$

B. $\begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$

C. $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

(D) $\begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix}$

E. $\begin{bmatrix} 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$

F. $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix}$

6. Let M_{22} denote, as usual, the vector space of real 2×2 matrices, and A^t denote the transpose of $A \in M_{22}$. The dimension of $V = \{A \in M_{22} \mid A = -A^t\}$ is:

A. 0

(B. 1)

C. 2

D. 3

E. 4

F. V is not a subspace of M_{22} , so we cannot speak of its dimension.

$$-\begin{bmatrix} a & b \\ c & d \end{bmatrix}^t = \begin{bmatrix} -a & -c \\ -b & -d \end{bmatrix}$$

$$= \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$\Leftrightarrow \begin{matrix} a=0 & b=-c \\ & d=0 \end{matrix}$$

$$V = \left\{ \begin{bmatrix} 0 & b \\ -b & 0 \end{bmatrix} \mid b \in \mathbb{R} \right\}$$

$$\dim V = 1$$

7. The matrix $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$ is not diagonalizable over the reals. Why?

Evals are $1 \in \mathbb{R}$

$$Ae_3 = 2e_3$$

$$[A - 2I] = \begin{bmatrix} -1 & 1 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \text{ (rank 2)}$$

$$\therefore \dim \ker A - 2I = 1$$

$$\therefore \dim E_2 = 1$$

$$[A - I] = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ (rk=2)}$$

$$\therefore \dim E_1 = 1$$

$$\dim E_1 + \dim E_2 = 2 < 3.$$

\therefore not enough l.i. evcs.

A. Because A does not have real eigenvalues. \times

B. Because A does not have any eigenvectors. \times $Ae_3 = 2e_3$

C. Because A does not have three distinct eigenvalues.

D. Because A does not have three independent eigenvectors.

E. Because A is upper triangular. \times

F. Because there 'k' in 'ice-cream.' \times

8. The set of vectors $\{(0, 3, 4), (1, 0, 0), (0, 4, -3)\}$ is orthogonal. Find the Fourier coefficients (a_1, a_2, a_3) of $v = (0, -1, -1)$.

A. $(-\frac{7}{25}, 0, -\frac{1}{25})$

B. $(-\frac{7}{5}, 0, -\frac{1}{5})$

C. $(-7, 0, -1)$

D. $(0, -1, -1)$

E. $(\frac{7}{25}, 0, \frac{1}{25})$

F. $(-\frac{7}{25}, 0, \frac{1}{25})$

$$a_1 = \frac{(0, 3, 4) \cdot (0, -1, -1)}{25} = -\frac{7}{25}$$

$$a_2 = \frac{(1, 0, 0) \cdot (0, -1, -1)}{1} = 0$$

$$a_3 = \frac{(0, 4, -3) \cdot (0, -1, -1)}{25} = -\frac{1}{25}$$

9. Let $W = \{(x, y, z, w) \in \mathbf{R}^4 \mid xyzw \leq 0\}$. Then,
- A. $(0, 0, 0, 0) \in W$ but W is not closed under multiplication by scalars
 - B. $(0, 0, 0, 0) \notin W$ but W is closed under addition
 - C. W is closed under addition but W is not closed under multiplication by scalars
 - D. W is closed under addition and W is closed under multiplication by scalars
 - E. W is not closed under addition but W is closed under multiplication by scalars
 - F. None of the other statements is true.

Solution: (If you'd studied the W04 final, this was especially easy.)

A. is False: If $k \in \mathbf{R}$ and $(x, y, z, w) \in W$ then $k(x, y, z, w) = (kx, ky, kz, kw) \in W$ because

$$kxkykzkw = k^4xyzw \leq 0,$$

since $k^4 \geq 0$ and $xyzw \leq 0$.

So now we know W is closed under multiplication by scalars.

B. is False: since $(0, 0, 0, 0) \in W$.

C. is False: since we know already know W is closed under multiplication by scalars.

D. is False: $w = (-1, -1, 0, 0) \in W$ and $w' = (0, 0, 1, 1) \in W$ but $w + w' = (-1, -1, 1, 1) \notin W$.

So now we know W is not closed under addition.

E. is True: From what we learned from A and D.

So:

F. is False.

10. Suppose A is an $n \times n$ matrix. Among the following statements, which one is **not equivalent** to the others?

A. A is not invertible.

B. $Ax = 0$ has infinitely many solutions $x \in \mathbf{R}^n$.

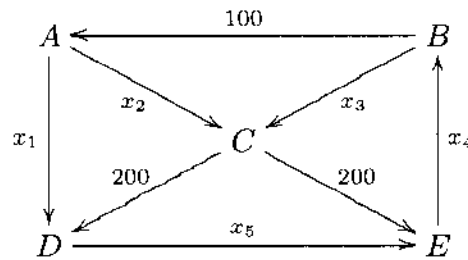
C. There is $b \in \mathbf{R}^n$ such that $Ax = b$ is inconsistent.

D. The determinant of A is zero.

E. A is row-equivalent to the identity matrix. \times

F. The rank of A is less than n .

11. Consider the network of streets and intersections below. The arrows indicate the direction of traffic flow along the one-way streets, and the numbers refer to the exact number of cars observed to enter or leave the intersections during one minute. Each x_i denotes the unknown number of cars which passed along the indicated streets during the same period.



3 a) Write down a system of linear equations which describes the traffic flow, **together with all the constraints** on the variables $x_i, i = 1, \dots, 5$. (Do not perform any operations on your equations: this is done for you in (b), and *do not simply copy out the equations implicit in (b)*. You will not get any marks if you do this.)

† b) The reduced row-echelon form of the augmented matrix from part (a) is

$$\left[\begin{array}{ccccc|c} 1 & 0 & 0 & 0 & -1 & -200 \\ 0 & 1 & 0 & 0 & 1 & 300 \\ 0 & 0 & 1 & 0 & -1 & 100 \\ 0 & 0 & 0 & 1 & -1 & 200 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

Give the general solution. (Ignore the constraints at this point.)

2 c) Find the maximum and minimum flow along BC, **using your results from (b)**.

(You must justify all your answers.)

a)

A	Flow in	=	Flow out	
100	=	$x_1 + x_2$		
B	x_4	=	$100 + x_3$	
C	$x_2 + x_3$	=	400	
D	$x_1 + 200$	=	x_5	
E	$200 + x_5$	=	x_4	

$x_i \in \mathbb{Z} \quad i=1, \dots, 5 \quad \frac{1}{5}$
 $x_i \geq 0 \quad \text{''} \quad \frac{1}{5}$

b)

$$\begin{aligned} x_1 &= -200 + \Delta \\ x_2 &= 300 - \Delta \\ x_3 &= 100 + \Delta \\ x_4 &= 200 + \Delta \\ x_5 &= \Delta \end{aligned} \quad ; \Delta \in \mathbb{R} \quad \left(\frac{1}{5} \text{ each}\right)$$

c) Flow along BC is $x_3 = 100 + \Delta$. Now $x_1 \geq 0 \Leftrightarrow \Delta \geq 200$ while $x_2 \geq 0 \Leftrightarrow \Delta \leq 300$. No other constraints change this. Hence $200 \leq \Delta \leq 300$

1 - correct answers
 1 - justification

7

$$\begin{aligned} \therefore 300 &\leq 100 + \Delta \leq 400 \\ \text{Max flow along BC} &= 400 \\ \text{Min} &= 300. \end{aligned}$$

12. Let $U = \{(x, y, z, w) \in \mathbf{R}^4 \mid x + z + w = 0\}$.

$$[1 \ 0 \ 1 \ 1 \mid 0]$$

2 a) Find a basis of U and give the dimension of U .

2 b) Find an orthogonal basis of U .

2 c) Find the best approximation to $(1, 1, 0, 0)$ by vectors in U .

a) $x = -s - t$
 $y = s$
 $z = s$
 $w = t$

$; s, t \in \mathbf{R} ; \therefore \{ \overset{v_1}{(-1, 0, 1, 0)}, \overset{v_2}{(-1, 0, 0, 1)}, \overset{v_3}{(0, 1, 0, 0)} \}$
 is a basis of U .
 $\therefore \dim U = 3$ $\frac{1}{2}$ (consistent w/↑)

(justified) basis $\frac{1}{2}$ - (no just)

b) $w_1 = v_1$

$$w_2 = v_2 - \frac{w_1 \cdot v_2}{\|w_1\|^2} w_1 = (-1, 0, 0, 1) - \frac{1}{2}(-1, 0, 1, 0)$$

$$= (-\frac{1}{2}, 0, -\frac{1}{2}, 1)$$

$\frac{1}{2} : G.S$

$$w_3 = v_3 - \frac{w_1 \cdot v_3}{\|w_1\|^2} w_1 - \frac{w_2 \cdot v_3}{\|w_2\|^2} w_2 = v_3 = (0, 1, 0, 0)$$

$\therefore \{ \overset{w_1}{(-1, 0, 1, 0)}, \overset{\tilde{w}_2}{(-1, 0, -1, 2)}, \overset{w_3}{(0, 1, 0, 0)} \}$ $\frac{1}{2}, 1$ orthog
 orthogonal basis of U . $\frac{1}{2}$ an
 $\frac{1}{2} \subset U$

c) $\underbrace{\text{proj}_U}_{1} (1, 1, 0, 0) = \frac{(1, 1, 0, 0) \cdot w_1}{\|w_1\|^2} w_1$
 $+ \frac{(1, 1, 0, 0) \cdot \tilde{w}_2}{\|\tilde{w}_2\|^2} \tilde{w}_2$
 $+ \frac{(1, 1, 0, 0) \cdot w_3}{\|w_3\|^2} w_3$
 $= \frac{-1}{2} w_1 + \frac{-1}{6} \tilde{w}_2 + 1 \cdot w_3$
 $= \left(\frac{1}{2}, 0, -\frac{1}{2}, 0 \right) + \left(\frac{1}{6}, 0, \frac{1}{6}, -\frac{1}{3} \right) + (0, 1, 0, 0)$
 $= \left(\frac{2}{3}, 1, -\frac{1}{3}, -\frac{1}{3} \right)$
 $= \frac{1}{3} (2, 3, -1, -1)$
 $\frac{1}{3} \in U$
 1 - correct, $\frac{1}{2} \in U$

13. Let $A = \begin{bmatrix} 0 & 0 & -2 \\ 1 & 2 & 1 \\ 1 & 0 & 3 \end{bmatrix}$.

a) Find the characteristic polynomial $\det(A - \lambda I)$ of A , and deduce that the eigenvalues of A are 1 and 2.

b) Find a basis of $E_1 = \{x \in \mathbb{R}^3 \mid Ax = x\}$.

c) Find a basis of $E_2 = \{x \in \mathbb{R}^3 \mid Ax = 2x\}$.

d) Find an invertible matrix P such that $P^{-1}AP = D$ is diagonal, and give this diagonal matrix D . Explain why your choice of P is invertible.

a) $|A - \lambda I| = \begin{vmatrix} -\lambda & 0 & -2 \\ 1 & 2-\lambda & 1 \\ 1 & 0 & 3-\lambda \end{vmatrix} = (2-\lambda) \begin{vmatrix} -\lambda & -2 \\ 1 & 3-\lambda \end{vmatrix} = (2-\lambda) \begin{vmatrix} -\lambda & \lambda-2 \\ 1 & 2-\lambda \end{vmatrix}$
 $= (2-\lambda)^2 \begin{vmatrix} -\lambda & -1 \\ 1 & 1 \end{vmatrix} = (2-\lambda)^2 (-\lambda + 1)$ ①
($\frac{1}{2}$ if merely check 1&2 give 0 here)
 $\therefore |A - \lambda I| = 0 \Leftrightarrow \lambda = 2 \text{ or } \lambda = 1$

b) $E_1 = \ker(A - I) = \ker \begin{bmatrix} -1 & 0 & -2 \\ 1 & 1 & 1 \\ 1 & 0 & 2 \end{bmatrix} = \ker \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$
 $\text{or } = \left\{ (-2s, s, s) \mid s \in \mathbb{R} \right\} = \left\{ (-2, 1, 1) \right\} \left(\frac{1}{2} \right)$

is a basis for E_1

c) $E_2 = \ker(A - 2I) = \ker \begin{bmatrix} -2 & 0 & -2 \\ 1 & 0 & 1 \\ 1 & 0 & 1 \end{bmatrix} = \ker \begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \left\{ (-t, s, t) \mid s, t \in \mathbb{R} \right\}$
 $\frac{1}{2} - \text{rank } 1$

$\therefore \{(-1, 0, 1), (0, 1, 0)\}^1$ is a basis for E_2

d) Let $P = \begin{bmatrix} -2 & -1 & 0 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$ ①, $D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$ ②. Then $P^{-1}AP = D$.

$\det P = - \begin{vmatrix} -2 & -1 \\ 1 & 1 \end{vmatrix} = -(-1) = 1 \neq 0 \therefore P$ is invertible
②

14. Define a linear transformation $S: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ by

$$S\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x+y \\ y+z \\ z-x \end{pmatrix}.$$

$\frac{1}{2}$ a) Find the standard matrix of S .

$\frac{1}{2}$ b) Find a basis for $\ker S$.

$\frac{1}{2}$ c) Give a complete geometric description of $\ker S$.

$\frac{1}{2}$ d) Find $\dim \operatorname{im} S$.

$\frac{1}{2}$ a) $A = (S e_1, S e_2, S e_3) = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ -1 & 0 & 1 \end{bmatrix}$ $\frac{1}{2}$

$$A^t = \begin{bmatrix} 1 & 0 & -1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \frac{1}{2}$$

$\frac{1}{2}$ b) $\ker S = \ker A = \ker \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ -1 & 0 & 1 \end{bmatrix} = \ker \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} = \ker \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$ $\frac{1}{2}$

$= \left\{ \begin{bmatrix} \lambda \\ -\lambda \\ \lambda \end{bmatrix} \mid \lambda \in \mathbb{R} \right\} \therefore \textcircled{1} \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$ is a basis for $\ker S$

$\ker A^t = \ker A$!

$\frac{1}{2}$ c) $\ker S$ is the line through 0 in \mathbb{R}^3 with $\dim \frac{1}{2} \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$.

$\frac{1}{2}$ d) $\dim \operatorname{im} S = \dim \operatorname{col} A = \operatorname{rank} A = \underline{2}$.

$\left(\frac{1}{2} \right)$ just- (1)

$$\left(\frac{1}{2}\right) + \left(\frac{1}{2}\right) + \left(\frac{1}{2}\right)$$

15. State whether the following are true or false. If true, explain why, if false, give an explicit counter-example to illustrate.

- (a) If u, v and w are three linearly independent vectors in a vector space E , then $u \in \text{span}\{u-v, v-w\}$.

FALSE

$$u = a(u-v) + b(v-w)$$

$$\Leftrightarrow 0 = (a-1)u + (-a+b)v - bw$$

$$\Leftrightarrow \begin{cases} a-1=0 \\ -a+b=0 \\ -b=0 \end{cases} \quad \left. \begin{array}{l} a=1 \\ b=0 \end{array} \right\} \text{which} \\ \text{is impossible.}$$

- (b) Let A be a real 3×2 matrix and suppose there is a vector $v \in \mathbf{R}^2$ with $v \neq 0$ and $Av = 0$. Then the columns of A are dependent.

TRUE

$$A = [c_1 \ c_2] \quad A \begin{bmatrix} x \\ y \end{bmatrix} = xc_1 + yc_2 = 0$$

with $\begin{bmatrix} x \\ y \end{bmatrix} \neq \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \{c_1, c_2\}$ dependent.

- c) Suppose B is an invertible 3×3 matrix, and v_1, v_2 , and v_3 span \mathbf{R}^3 . Then $\{Bv_1, Bv_2, Bv_3\}$ also spans \mathbf{R}^3 .

TRUE

$\{v_1, v_2, v_3\}$ span $\mathbf{R}^3 \Leftrightarrow A = [v_1 \ v_2 \ v_3]$ is invertible.

But $[Bv_1 \ Bv_2 \ Bv_3] = B[v_1 \ v_2 \ v_3] = BA$ is therefore invertible too, so $\{Bv_1, Bv_2, Bv_3\}$ spans \mathbf{R}^3

- d) Let A be a 4×6 matrix, and define a linear transformation $T_A : \mathbf{R}^6 \rightarrow \mathbf{R}^4$ by $T_A(v) = Av$, for all $v \in \mathbf{R}^6$. Then $\ker T_A \neq \{0\}$.

TRUE

$$\dim \ker T_A + \dim \operatorname{im} T_A = 6$$

But $\operatorname{im} T_A$ is a s.s. of $\mathbf{R}^4 \therefore \dim \operatorname{im} T_A \leq 4$

$$\therefore \dim \ker T_A \geq 2$$

$$\therefore \ker T_A \neq \{0\}$$

16. (4 bonus marks) Make sure you finish and check the rest of the paper before trying this. Bonus marks are much harder to earn.

Let A be a symmetric $n \times n$ matrix.

a) Prove that $(Au) \cdot u' = u \cdot (Au')$ for all $u, u' \in \mathbf{R}^n$. (Here " \cdot " denotes the dot product)

Let u, u' be written as column vectors. Then

$$\begin{aligned}
 (Au) \cdot u' &= (Au)^t u' &&= u^t A^t u' &&= u^t A u' \\
 &\quad \uparrow && && \\
 &\text{matrix product} && && \\
 & && && \uparrow \\
 & && && \text{dot product}
 \end{aligned}$$

$$\therefore (Au) \cdot u' = u \cdot (Au')$$

Now let $v_\lambda \in \mathbf{R}^n$ be an eigenvector of A with eigenvalue λ , and set $W = \{w \in \mathbf{R}^n \mid w \cdot v_\lambda = 0\}$.

b) Prove that if $w \in W$, then $Aw \in W$.

$$\begin{aligned}
 \text{Consider } (Aw) \cdot v_\lambda &\quad \text{By (a)} \quad (Aw) \cdot v_\lambda \\
 &= w \cdot (Av_\lambda) \\
 &= w \cdot (\lambda v_\lambda) \\
 &= \lambda (w \cdot v_\lambda) \\
 &= \lambda (0) \quad (\text{since } w \in W) \\
 &= 0 \\
 \therefore (Aw) \cdot v_\lambda &= 0, \text{ so } Aw \in W.
 \end{aligned}$$