

# Math 119B: Week 5

David Thomson

October 12, 2011

# Table of Contents

Recap

Span

What does a parametric solution set look like?

Recap of test topics

Linear independence

# Recap

- ▶ Some previous test recap.
- ▶ Homogeneous systems.
- ▶ What is the trivial solution of a homogeneous systems?
- ▶ Leontief's exchange problem. (And re-done today).

## Two dimensions

Solve the following system of equations

$$\begin{aligned}3x_1 + 3x_2 &= 9 \\ x_1 + x_2 &= 3.\end{aligned}$$

Ans.:

## Two dimensions

Solve the following system of equations

$$\begin{aligned}3x_1 + 3x_2 &= 9 \\ x_1 + x_2 &= 3.\end{aligned}$$

Ans.:

$$\begin{bmatrix} 3 \\ 0 \end{bmatrix} + v \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

Let's draw what this means:

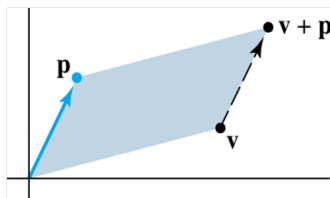
## Two dimensions

Solve the following system of equations

$$\begin{aligned}3x_1 + 3x_2 &= 9 \\ x_1 + x_2 &= 3.\end{aligned}$$

Ans.:

$$\begin{bmatrix} 3 \\ 0 \end{bmatrix} + v \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$



Let's draw what this means:

# The span of one vector

The **span** of a vector  $v$  is simply every scalar multiple of that vector.

For example, if  $v = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ , then  $\text{Span}(v) =$

# The span of one vector

The **span** of a vector  $v$  is simply every scalar multiple of that vector.

For example, if  $v = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ , then  $\text{Span}(v) = a \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ ,  $a \in \mathbb{R}$ .

**Skill testing question:** How many vectors are in  $\{v\}$ ?:

# The span of one vector

The **span** of a vector  $v$  is simply every scalar multiple of that vector.

For example, if  $v = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ , then  $\text{Span}(v) = a \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ ,  $a \in \mathbb{R}$ .

**Skill testing question:** How many vectors are in  $\{v\}$ ?: 1.  
How many vectors are in  $\text{Span}(v)$ ?:

# The span of one vector

The **span** of a vector  $v$  is simply every scalar multiple of that vector.

For example, if  $v = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ , then  $\text{Span}(v) = a \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ ,  $a \in \mathbb{R}$ .

**Skill testing question:** How many vectors are in  $\{v\}$ ?: 1.  
How many vectors are in  $\text{Span}(v)$ ?: Infinitely many.

# The span of many vectors

**Definition.** The **span** of a set of vectors  $v_1, v_2, \dots, v_n$  is the set of **all** linear combinations of  $v_1, v_2, \dots, v_n$ . That is,

$$c_1 v_1 + c_2 v_2 + \cdots + c_n v_n, \quad c_1, c_2, \dots, c_n \in \mathbb{R}.$$

**Skill testing question:** How many vectors are in  $\{v_1, v_2, \dots, v_n\}$ ?:

# The span of many vectors

**Definition.** The **span** of a set of vectors  $v_1, v_2, \dots, v_n$  is the set of **all** linear combinations of  $v_1, v_2, \dots, v_n$ . That is,

$$c_1 v_1 + c_2 v_2 + \cdots + c_n v_n, \quad c_1, c_2, \dots, c_n \in \mathbb{R}.$$

**Skill testing question:** How many vectors are in  $\{v_1, v_2, \dots, v_n\}$ ?:  
 $n$ .

How many vectors are in  $\text{Span}(v)$ ?:

# The span of many vectors

**Definition.** The **span** of a set of vectors  $v_1, v_2, \dots, v_n$  is the set of **all** linear combinations of  $v_1, v_2, \dots, v_n$ . That is,

$$c_1 v_1 + c_2 v_2 + \cdots + c_n v_n, \quad c_1, c_2, \dots, c_n \in \mathbb{R}.$$

**Skill testing question:** How many vectors are in  $\{v_1, v_2, \dots, v_n\}$ ?:  
 $n$ .

How many vectors are in  $\text{Span}(v)$ ?: Infinitely many.

## Span of two vectors – how many ways can we do this?

**Blackboard.** Suppose we have any two vectors  $u$  and  $v$ . How many different pictures can we draw for  $\text{Span}(u, v)$ ?

## Span of two vectors – how many ways can we do this?

**Blackboard.** Suppose we have any two vectors  $u$  and  $v$ . How many different pictures can we draw for  $\text{Span}(u, v)$ ?

- ▶  $u = v = 0$ .

# Span of two vectors – how many ways can we do this?

**Blackboard.** Suppose we have any two vectors  $u$  and  $v$ . How many different pictures can we draw for  $\text{Span}(u, v)$ ?

- ▶  $u = v = 0$ .
- ▶  $u = cv$ .

# Span of two vectors – how many ways can we do this?

**Blackboard.** Suppose we have any two vectors  $u$  and  $v$ . How many different pictures can we draw for  $\text{Span}(u, v)$ ?

- ▶  $u = v = 0$ .
- ▶  $u = cv$ .
- ▶  $u \neq cv$ .

**Note:** In general, we have a set of vectors is either:

1. All zero.

## Span of two vectors – how many ways can we do this?

**Blackboard.** Suppose we have any two vectors  $u$  and  $v$ . How many different pictures can we draw for  $\text{Span}(u, v)$ ?

- ▶  $u = v = 0$ .
- ▶  $u = cv$ .
- ▶  $u \neq cv$ .

**Note:** In general, we have a set of vectors is either:

1. All zero.
2. One vector can be expressed as a linear combination of the others.

## Span of two vectors – how many ways can we do this?

**Blackboard.** Suppose we have any two vectors  $u$  and  $v$ . How many different pictures can we draw for  $\text{Span}(u, v)$ ?

- ▶  $u = v = 0$ .
- ▶  $u = cv$ .
- ▶  $u \neq cv$ .

**Note:** In general, we have a set of vectors is either:

1. All zero.
2. One vector can be expressed as a linear combination of the others.
3. No vectors can be given as linear combination of the others.

## Some examples

Let  $v_1 = \begin{bmatrix} 4 \\ 5 \\ -6 \end{bmatrix}$ ,  $v_2 = \begin{bmatrix} -3 \\ -2 \\ 2 \end{bmatrix}$  and  $v_3 = \begin{bmatrix} 1 \\ 5 \\ -3 \end{bmatrix}$ . Set  $b = \begin{bmatrix} -7 \\ -3 \\ 10 \end{bmatrix}$ .

- (i) How many vectors are in  $\{v_1, v_2, v_3\}$ ?
- (ii) How many vectors are in  $\text{Span}(v_1, v_2, v_3)$ ?
- (iii) Is  $b \in \text{Span}(v_1, v_2, v_3)$ ?

Ans.

## Some examples

Let  $v_1 = \begin{bmatrix} 4 \\ 5 \\ -6 \end{bmatrix}$ ,  $v_2 = \begin{bmatrix} -3 \\ -2 \\ 2 \end{bmatrix}$  and  $v_3 = \begin{bmatrix} 1 \\ 5 \\ -3 \end{bmatrix}$ . Set  $b = \begin{bmatrix} -7 \\ -3 \\ 10 \end{bmatrix}$ .

- (i) How many vectors are in  $\{v_1, v_2, v_3\}$ ?
- (ii) How many vectors are in  $\text{Span}(v_1, v_2, v_3)$ ?
- (iii) Is  $b \in \text{Span}(v_1, v_2, v_3)$ ?

Ans. (i) 3

## Some examples

Let  $v_1 = \begin{bmatrix} 4 \\ 5 \\ -6 \end{bmatrix}$ ,  $v_2 = \begin{bmatrix} -3 \\ -2 \\ 2 \end{bmatrix}$  and  $v_3 = \begin{bmatrix} 1 \\ 5 \\ -3 \end{bmatrix}$ . Set  $b = \begin{bmatrix} -7 \\ -3 \\ 10 \end{bmatrix}$ .

- (i) How many vectors are in  $\{v_1, v_2, v_3\}$ ?
- (ii) How many vectors are in  $\text{Span}(v_1, v_2, v_3)$ ?
- (iii) Is  $b \in \text{Span}(v_1, v_2, v_3)$ ?

**Ans.** (i) 3    (ii) Infinitely many

## Some examples

Let  $v_1 = \begin{bmatrix} 4 \\ 5 \\ -6 \end{bmatrix}$ ,  $v_2 = \begin{bmatrix} -3 \\ -2 \\ 2 \end{bmatrix}$  and  $v_3 = \begin{bmatrix} 1 \\ 5 \\ -3 \end{bmatrix}$ . Set  $b = \begin{bmatrix} -7 \\ -3 \\ 10 \end{bmatrix}$ .

- (i) How many vectors are in  $\{v_1, v_2, v_3\}$ ?
- (ii) How many vectors are in  $\text{Span}(v_1, v_2, v_3)$ ?
- (iii) Is  $b \in \text{Span}(v_1, v_2, v_3)$ ?

**Ans.** (i) 3    (ii) Infinitely many

(iii) Set  $A = [v_1 \ v_2 \ v_3 \ b]$  and row reduce to get

## Some examples

Let  $v_1 = \begin{bmatrix} 4 \\ 5 \\ -6 \end{bmatrix}$ ,  $v_2 = \begin{bmatrix} -3 \\ -2 \\ 2 \end{bmatrix}$  and  $v_3 = \begin{bmatrix} 1 \\ 5 \\ -3 \end{bmatrix}$ . Set  $b = \begin{bmatrix} -7 \\ -3 \\ 10 \end{bmatrix}$ .

- (i) How many vectors are in  $\{v_1, v_2, v_3\}$ ?
- (ii) How many vectors are in  $\text{Span}(v_1, v_2, v_3)$ ?
- (iii) Is  $b \in \text{Span}(v_1, v_2, v_3)$ ?

**Ans.** (i) 3    (ii) Infinitely many

(iii) Set  $A = [v_1 \ v_2 \ v_3 \ b]$  and row reduce to get

$$\begin{bmatrix} 1 & 0 & 0 & -3 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 2 \end{bmatrix}.$$

Thus,  $b$  is a linear combination of  $v_1, v_2, v_3$  (what are the scalars?)  
and so  $b \in \text{Span}(v_1, v_2, v_3)$ .

## More examples

Let  $w_1 = \begin{bmatrix} 3 \\ -2 \end{bmatrix}$ ,  $w_2 = \begin{bmatrix} 7 \\ 3 \end{bmatrix}$  and  $w_3 = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$  and  $d = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ .

Determine if  $d$  is in  $\text{Span}(v_1, v_2, v_3)$ .

**Ans.** Form the matrix  $[w_1 \ w_2 \ w_3 \ d]$  and row-reduce to get

$$\begin{bmatrix} 1 & 0 & -13/23 & 0 \\ 0 & 1 & -1/23 & 0 \end{bmatrix}.$$

The system is **consistent** and so  $d$  is in the span of  $v_1, v_2$  and  $v_3$ .

**Note!!** We didn't need to reduce all the way to RREF! If the question asks only "is  $d$  in the span...?", then all we care about is **existence** of solutions. Thus, row-echelon form is sufficient.

# Test topics

- ▶ Solving systems of equations with multiple parameters,
- ▶ Vector equations,
- ▶ Matrix equations,
- ▶ Linear combinations,
- ▶ Leontief exchange protocol,
- ▶ Span.

The format of the test will be mostly the same as the previous test. There will be some skill-testing questions (true/false style) and some long answer.

## Definition

A set of vectors  $v_1, v_2, \dots, v_n \in \mathbb{R}^m$  is called **linearly independent** if there is **only** the trivial solution to the vector equation  $c_1 v_1 + c_2 v_2 + \dots + c_n v_n = 0$ . If a set of vectors is not linearly independent, it is linearly **dependent**.

I often write l.i for “linearly independent” and l.d for “linearly dependent”.

You can solve for linear independence in the following way: Let  $A = [v_1 \ v_2 \ \dots \ v_n]$ , and solve  $Ax = 0$ . If the **only** solution is  $x = 0$ , then the vectors are linearly independent.

If there is a non-trivial solution to a homogeneous solution, then there are free variables!

# When are vectors linearly independent?

**Theorem.** The following are all equivalent:

1. A set of vectors  $v_1, v_2, \dots, v_n \in \mathbb{R}^m$  are linearly independent.
2. The vector equation  $c_1 v_1 + c_2 v_2 + \dots + c_n v_n = 0$  has only the trivial solution.
3. If  $A = [v_1 \ v_2 \ \dots \ v_n]$ , the matrix equation  $Ax = 0$  has only the trivial solution.
4. The matrix  $A$  has a pivot in every column.

## Linear independence in $\mathbb{R}^2$

There were 3 ways to draw a set of 2 vectors in  $\mathbb{R}^2$

1. Both were the 0 vector,
2. They were both on the same line ( $u = cv$ ),
3. They were not on the same line ( $u \neq cv$ ).

Let's look at the solutions to  $Ax = b$  in the previous cases:

(1)  $A = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ , so  $Ax = 0$  has

## Linear independence in $\mathbb{R}^2$

There were 3 ways to draw a set of 2 vectors in  $\mathbb{R}^2$

1. Both were the 0 vector,
2. They were both on the same line ( $u = cv$ ),
3. They were not on the same line ( $u \neq cv$ ).

Let's look at the solutions to  $Ax = b$  in the previous cases:

(1)  $A = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ , so  $Ax = 0$  has 2 free variables, no pivots.

(2)  $A = \begin{bmatrix} v & cv \end{bmatrix}$  so  $Ax = 0$  has

## Linear independence in $\mathbb{R}^2$

There were 3 ways to draw a set of 2 vectors in  $\mathbb{R}^2$

1. Both were the 0 vector,
2. They were both on the same line ( $u = cv$ ),
3. They were not on the same line ( $u \neq cv$ ).

Let's look at the solutions to  $Ax = b$  in the previous cases:

(1)  $A = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ , so  $Ax = 0$  has 2 free variables, no pivots.

(2)  $A = \begin{bmatrix} v & cv \end{bmatrix}$  so  $Ax = 0$  has a free variable in the solution.

(3) (Example.)  $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ , so  $Ax = 0$  has no free variables (only trivial solution).