

Q1 (5 Marks) Determine if the columns of matrix $A = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix}$ are linearly independent.

Sol. We only need to show that $A\vec{x} = \vec{0}$ has only trivial solution. (1)

The augmented matrix $\begin{bmatrix} 1 & 0 & 0 & | & 0 \\ 2 & 1 & 0 & | & 0 \\ 0 & 2 & 1 & | & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & | & 0 \\ 0 & 1 & 0 & | & 0 \\ 0 & 2 & 1 & | & 0 \end{bmatrix}$ (2)

$\sim \begin{bmatrix} 1 & 0 & 0 & | & 0 \\ 0 & 1 & 0 & | & 0 \\ 0 & 0 & 1 & | & 0 \end{bmatrix}$ $\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ only trivial solution.

Hence, the columns of matrix A are linearly independent. (2)

Q2 Determine whether the vectors are linearly independent. Give the reason. (Hint: No need to solve the linear system.)

(a) (3 Marks) $\begin{bmatrix} -8 \\ 12 \end{bmatrix}$ $\begin{bmatrix} 2 \\ -3 \end{bmatrix}$

$\begin{bmatrix} -8 \\ 12 \end{bmatrix} = 4 \begin{bmatrix} 2 \\ -3 \end{bmatrix}$

Then, dependent.

2 marks for dependent.
1 mark for reason.

(b) (3 Marks) $\begin{bmatrix} 5 \\ -3 \\ -1 \end{bmatrix}$ $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ $\begin{bmatrix} -7 \\ 2 \\ 4 \end{bmatrix}$

Dependent. since there is vector $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$

(c) (3 Marks) $\begin{bmatrix} 5 \\ 1 \end{bmatrix}$ $\begin{bmatrix} 2 \\ 8 \end{bmatrix}$ $\begin{bmatrix} 1 \\ 3 \end{bmatrix}$ $\begin{bmatrix} -1 \\ 7 \end{bmatrix}$

Dependent. since the number of vectors is greater than the entries of each vector.

Q3 Define a transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ by $T(\vec{x}) = A\vec{x}$.

(a) (9 Marks) If T maps $\vec{u} = \begin{bmatrix} 3 \\ 4 \\ 1 \end{bmatrix}$ into $\begin{bmatrix} 4 \\ 1 \end{bmatrix}$ and maps $\vec{v} = \begin{bmatrix} 3 \\ 3 \end{bmatrix}$ into $\begin{bmatrix} -1 \\ 3 \end{bmatrix}$. Find the images under T of $2\vec{u}$, $3\vec{v}$ and $2\vec{u} + 3\vec{v}$. (Hint: Matrix transformation is linear transformation.)

$T(2\vec{u}) = 2T(\vec{u}) = 2 \begin{bmatrix} 4 \\ 1 \end{bmatrix} = \begin{bmatrix} 8 \\ 2 \end{bmatrix}$ (3)

$T(3\vec{v}) = 3T(\vec{v}) = 3 \begin{bmatrix} -1 \\ 3 \end{bmatrix} = \begin{bmatrix} -3 \\ 9 \end{bmatrix}$ (3)

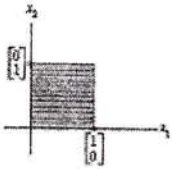
$T(2\vec{u} + 3\vec{v}) = T(2\vec{u}) + T(3\vec{v}) = \begin{bmatrix} 8 \\ 2 \end{bmatrix} + \begin{bmatrix} -3 \\ 9 \end{bmatrix} = \begin{bmatrix} 5 \\ 11 \end{bmatrix}$ (3)

(b) (3 Marks) Let A be a 6×5 matrix. What must n and m be in order to define T?

$$m = 6 \quad n = 5 \quad \text{i.e. } \mathbb{R}^5 \rightarrow \mathbb{R}^6.$$

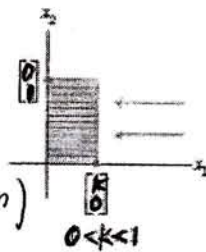
Q4 (4 Marks) Find the standard matrix for the following transformation.

Transformation	Image of the Unit Square	Standard Matrix
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Horizontal contraction and expansion

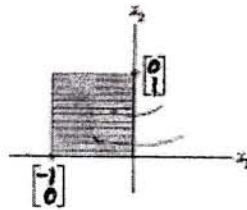
(Horizontal contraction and expansion)



$$\begin{bmatrix} k & 0 \\ 0 & 1 \end{bmatrix} = ? \quad (2)$$

Reflection through the x_2 -axis

(Reflection through the x_2 -axis)



$$\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} = ? \quad (2)$$

Q5 Let $T(x_1, x_2) = (3x_1 + x_2, 5x_1 + 7x_2, x_1 + 3x_2)$.

(a) (4 Marks) What's the standard matrix for the linear transformation T. That is $T(\vec{x}) = A\vec{x}$, find A.

$$A = \begin{bmatrix} 3 & 1 \\ 5 & 7 \\ 1 & 3 \end{bmatrix}$$

(b) (3 Marks) Show that T is a one-to-one linear transformation.

Need to show that $A\vec{x} = \vec{0}$ has only trivial solution.

$$\left. \begin{aligned} \left[\begin{array}{cc|c} 3 & 1 & 0 \\ 5 & 7 & 0 \\ 1 & 3 & 0 \end{array} \right] & \sim \left[\begin{array}{cc|c} 1 & 3 & 0 \\ 5 & 7 & 0 \\ 3 & 1 & 0 \end{array} \right] & \sim \left[\begin{array}{cc|c} 1 & 3 & 0 \\ 0 & -8 & 0 \\ 0 & -8 & 0 \end{array} \right] \\ & \sim \left[\begin{array}{cc|c} 1 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & -8 & 0 \end{array} \right] & \sim \left[\begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right] & \vec{x} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \end{aligned} \right\} (2)$$

(c) (3 Marks) Is T onto transformation?

From part (b), $A \sim \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$

A doesn't have pivot position in each row. (1)

Therefore, T is not onto transformation. (2)

Therefore, T is one-to-one (1)