

Here are solution hints for practice exam:

Multiple choice questions: A, C, E, A, C, D, D, E, D, D.

Long answer questions (partial hints:)

Q 11 :

$$-x^2 + x + \frac{2}{13} \ln |x + 5| + \frac{11}{13} \ln |x - 8| + C$$

Q 12: Equilibria: -2 unstable, 0 stable, 3 unstable

Q 13: The general solution is $(2, -1, 0) + t(-1, 2/3, 1), t \in \mathbb{R}$.

Q 14: Domain $\{(x, y) : y > 0\} \subset \mathbb{R}^2$, Range \mathbb{R} . Level curve for $k \in \mathbb{R}$: $y = e^{k+x}, x \in \mathbb{R}$.
Tangent plane $z = -x + \frac{1}{e}y$.

Q 15:

$$\frac{2}{85} - \frac{9}{85}i$$

Q 16: Eigenvalues and eigenvectors: $\lambda_1 = -4, v_1 = s(1, -1), s \neq 0, \lambda_2 = -2, v_2 = t(1, 1), t \neq 0$. (The conditions $s, t \neq 0$ are required!). The equilibrium is $(0, 0)$ and it is stable. The x -nullcline is the line $y = 3x$, the y -nullcline is the line $y = 1/3x$.

Q 17: Equilibria: $(4, 0)$ (not stable, eigenvalues of Jacobian are -3 and 6), $(2, 1)$ (stable, eigenvalues of Jacobian are $-3 \pm 3i$) Trajectories that start on the x -axis should approach the equilibrium $(4, 0)$, all other trajectories should approach the the equilibrium $(2, 1)$. See posted review for more details on this type of problem.

$$\boxed{Q1} \quad \int_0^{\frac{\pi}{2}} \frac{\cos x dx}{(\sin^2(x))^{\frac{1}{3}}} = \left[\begin{array}{l} \sin x = u \\ \cos x dx = du \end{array} \quad \begin{array}{c|c|c} x & 0 & \frac{\pi}{2} \\ \hline u & 0 & 1 \end{array} \right]$$

$$= \int_0^1 \frac{du}{u^{\frac{2}{3}}} \quad \text{type 2} = \lim_{\epsilon \rightarrow 0} \int_{\epsilon}^1 u^{-\frac{2}{3}} du = \lim_{\epsilon \rightarrow 0} 3u^{\frac{1}{3}} \Big|_{\epsilon}^1 =$$

$$= \lim_{\epsilon \rightarrow 0} [3(1)^{\frac{1}{3}} - 3\epsilon^{\frac{1}{3}}] = 3$$

(A)

$$\boxed{Q2} \quad \int_1^e x^2 \ln(x^3) dx = \frac{x^3}{3} \ln(x^3) \Big|_1^e -$$

$$- \int_1^e \frac{x^3}{3} \cdot \frac{3x^2}{x^3} dx = \frac{x^3}{3} \cdot 3 \ln x \Big|_1^e - \int_1^e x^2 dx =$$

$$= e^3 \ln e - 1 \cdot \ln 1 - \frac{e^3}{3} + \frac{1}{3} = \frac{2e^3}{3} + \frac{1}{3}$$

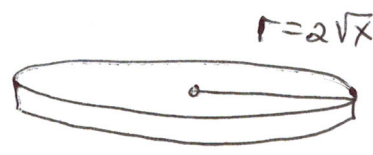
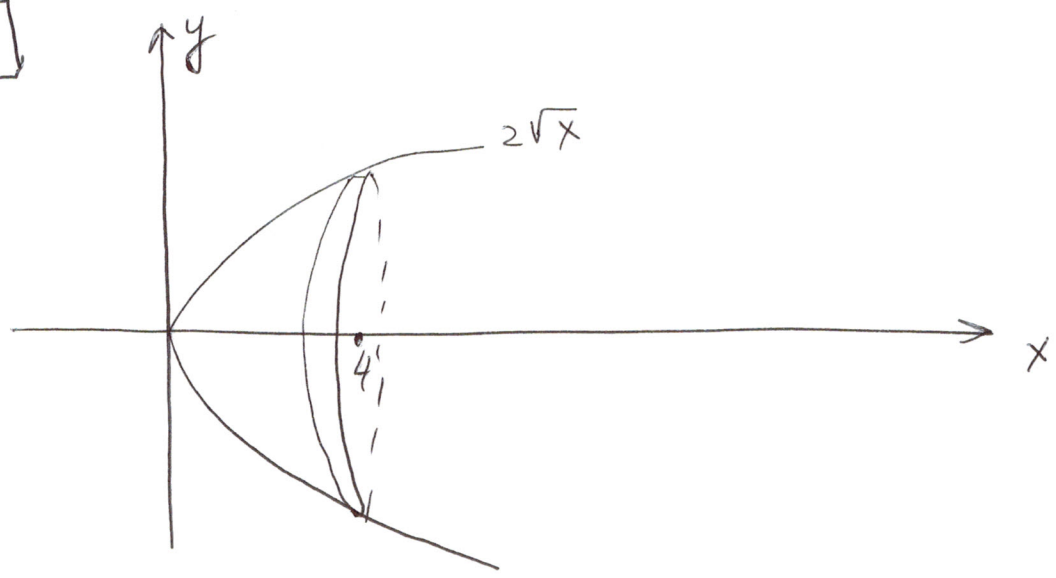
(C)

Here, I used integration by parts method:

$$\int u dv = uv - \int v du$$

$x^2 dx = dv$	$\ln(x^3) = u$
$\frac{x^3}{3} = v$	$\frac{3x^2}{x^3} dx = \frac{3}{x} dx = du$

Q3



$$A_i = \pi r^2 = \pi \cdot 4 \cdot x$$

$$V_x = \pi \cdot 4 \cdot x dx$$

$$V = 4\pi \int_0^4 x dx = 32\pi$$

(E)

Q4

$$\frac{dx}{dt} = \frac{3x}{t^2}$$

$$x(1) = e$$

$$x(3) = ?$$

$$\frac{dx}{x} = \frac{3dt}{t^2}$$

$$\ln|x| = -\frac{3}{t} + C$$

$$|x| = e^{-\frac{3}{t} + C} = C \cdot e^{-\frac{3}{t}}$$

$$x(t) = \pm C e^{-\frac{3}{t}} = \hat{C} \cdot e^{-\frac{3}{t}}$$

$$x(1) = \hat{C} e^{-3} = e \Rightarrow \hat{C} = e^4$$

$$x(t) = e^4 \cdot e^{-\frac{3}{t}}$$

$$x(3) = e^4 \cdot e^{-1} = e^3$$

(A)

Q5 $X = \begin{bmatrix} 2 & -1 & 7 \\ 8 & 6 & -2 \end{bmatrix}$, $Y = \begin{bmatrix} 4 & 2 \\ 8 & 4 \end{bmatrix}$,

$$Z = \begin{bmatrix} 3 & -1 & 0 \\ 5 & 1 & 0 \\ 7 & 7 & 1 \end{bmatrix}$$

(i) XY is defined

$$\begin{bmatrix} 2 & -1 & 7 \\ 8 & 6 & -2 \end{bmatrix} \begin{bmatrix} 4 & 2 \\ 8 & 4 \end{bmatrix} \quad \boxed{\text{No}}$$

$(2 \times 3) \times (2 \times 2)$

(ii) XZ is defined $\boxed{\text{Yes}}$

$$\begin{bmatrix} 2 & -1 & 7 \\ 8 & 6 & -2 \end{bmatrix} \begin{bmatrix} 3 & -1 & 0 \\ 5 & 1 & 0 \\ 7 & 7 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 8 & 0 & 0 \end{bmatrix}$$

$$\underline{(2 \times 3)} \times \underline{(3 \times 3)} = [2 \times 3]$$

(iii) YX^T is defined

$$\begin{bmatrix} 4 & 2 \\ 8 & 4 \end{bmatrix} \begin{bmatrix} 2 & 8 \\ -1 & 6 \\ 7 & -2 \end{bmatrix} \quad \boxed{\text{No}}$$

$(2 \times 2) \times (3 \times 2)$

(iv) ZX^T is defined $\boxed{\text{Yes}}$

$$\begin{bmatrix} 3 & -1 & 0 \\ 5 & 1 & 0 \\ 7 & 7 & 1 \end{bmatrix} \begin{bmatrix} 2 & 8 \\ -1 & 6 \\ 7 & -2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$\underline{[3 \times 3]} \quad \underline{[3 \times 2]} \quad \underline{[3 \times 2]}$

(V) The matrix Y is invertible.

$$\det(Y) = 4 \cdot 4 - 8 \cdot 2 = 0$$

No, it is not.

(VI) $Z + X^T X$ is defined

$$(3 \times 3) + \underbrace{(3 \times 2)}_{\uparrow} \cdot \underbrace{(2 \times 3)}_{\uparrow}$$

Yes, $Z + X^T X$ is defined.

The answer is C

$$\boxed{\text{Q6}} \quad \begin{bmatrix} -\sqrt{3} & 7 & 7 \\ -4 & \sqrt{3} & 0 \\ 0 & 0 & -7 \end{bmatrix}$$

$$A\bar{v} = \lambda\bar{v}$$

$$(A - \lambda I)\bar{v} = 0$$

$(A - \lambda I)$ does not have the inverse,

i.e. $\det(A - \lambda I) = 0$

$$\det(A - \lambda I) = \begin{vmatrix} -\sqrt{3} - \lambda & 7 & 7 \\ -4 & \sqrt{3} - \lambda & 0 \\ 0 & 0 & -7 - \lambda \end{vmatrix} =$$

$$= (-\sqrt{3} - \lambda)(\sqrt{3} - \lambda)(-7 - \lambda) + 0 + 0 - 0 - 0 + 4 \cdot 7(-7 - \lambda) = 0$$

$$= -(\sqrt{3} + \lambda)(\sqrt{3} - \lambda)(-1)(7 + \lambda) - 28(7 + \lambda) = 0$$

$$(\sqrt{3} + \lambda)(\sqrt{3} - \lambda)(7 + \lambda) - 28(7 + \lambda) = 0$$

$$7 + \lambda = 0$$

$$\boxed{\lambda_1 = -7}$$

$$(\sqrt{3} + \lambda)(\sqrt{3} - \lambda) - 28 = 0$$

$$3 - \lambda^2 - 28 = 0$$

$$\lambda^2 = -25$$

$$\boxed{\lambda_2 = 5i, \lambda_3 = -5i}$$

$\lambda = 7$ is not an eigenvalue.

Q7

$$z = -3 + 3i$$

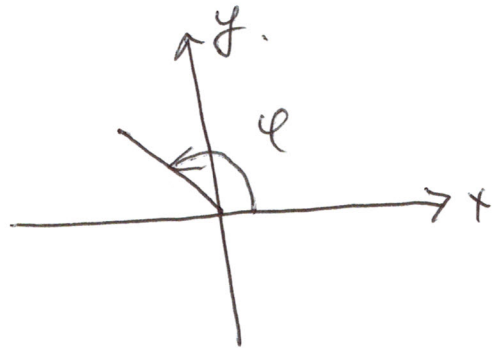
(i) $|z| = r = \sqrt{(-3)^2 + (3)^2} = \sqrt{18} = 3\sqrt{2}$ **Yes**

(ii) $x = -3$ $x = r \cdot \cos \varphi$
 $y = 3$ $y = r \sin \varphi$

$$\frac{y}{x} = -1 = \tan \varphi.$$

$$\varphi = \arctan(-1) + \pi$$

$$\varphi = -\frac{\pi}{4} + \pi = \frac{3\pi}{4}$$



Assume $\varphi \in [-\pi, \pi]$!

or $-3 = 3\sqrt{2} \cos \varphi \Rightarrow \cos \varphi = -\frac{1}{\sqrt{2}}$
 $3 = 3\sqrt{2} \sin \varphi \Rightarrow \sin \varphi = \frac{1}{\sqrt{2}} \Rightarrow \varphi = \frac{3\pi}{4}$

$$z = r \cdot e^{i\varphi} = r (\cos \varphi + i \sin \varphi) = 3\sqrt{2} e^{i\frac{3\pi}{4}}$$

is missing in (ii)

(ii) **No**

(iii) $z = |z| (\cos \frac{3\pi}{4} + i \sin \frac{3\pi}{4})$

(iv) **No**

(v) **Yes**

(vi) $\frac{1}{z} = \frac{\bar{z}}{|z|^2}$ is always true

Yes

D

Q8 $f(x,y) = \begin{pmatrix} x^2 + x + y \\ yx + x^2 \end{pmatrix}$ at $(1,2)$

Jacobian matrix $\begin{pmatrix} f_x & f_y \\ g_x & g_y \end{pmatrix}_{(1,2)} = \begin{pmatrix} 2x+1 & 1 \\ y+2x & x \end{pmatrix}_{(1,2)} =$

$= \begin{bmatrix} 3 & 1 \\ 4 & 1 \end{bmatrix}$

E

Q9 $\frac{dx}{dt} = x^2 - 2xy + y^2 = f(x,y)$

$\frac{dy}{dt} = e^{x^2-1} - 1 - \ln y = g(x,y)$

$f(x,y) = 0$

$x^2 - 2xy + y^2 = 0$ (1)

$g(x,y) = 0$

$e^{x^2-1} - 1 - \ln y = 0$ (2)

A: $(x,y) = (0,2)$ (1) x

B: $(x,y) = (5,2)$ (1) $\Rightarrow 25 - 2 \cdot 5 \cdot 2 + 4 \stackrel{?}{=} 0$
 $g \neq 0$

C: $(x,y) = (3,3)$ $9 - 2 \cdot 9 + 9 \stackrel{?}{=} 0$ Yes. $f(3,3) = 0$
 $g(3,3) \stackrel{?}{=} 0$ $e^8 - 1 - \ln 3 \stackrel{?}{=} 0$

D: $(x,y) = (1,1)$

$f(1,1) = 0$

$g(1,1) = e^0 - 1 - \ln 1 = 1 - 1 - 0 = 0$ ✓

E: $(x,y) = (1,3)$

$f(1,3) = 1 - 6 + 9 \neq 0$

$$\boxed{\text{Q10}} \quad z = f(x, y) = \pi - 2 \cos 3x + 4 \sin 5y$$

$$(x_0, y_0) = (0, \pi)$$

$$z = z_0 + f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

$$z_0 = f(x_0, y_0) = \pi - 2 \cos 0 + 4 \sin 5\pi = \pi - 2$$

$$f_x = -2(\cos 3x)_x + 0 = -2 \cdot (-\sin 3x) \cdot 3 = 6 \sin 3x$$

$$f_x(0, \pi) = 0$$

$$f_y = 0 - 0 + 4(\sin 5y)_y = 4 \cdot 5 \cos 5y = 20 \cos 5y$$

$$f_y(0, \pi) = 20 \cos 5\pi = -20$$

$$z = \pi - 2 + 0 - 20(y - \pi) = \pi - 2 - 20y + 20\pi = -20y + 21\pi - 2$$

D

$$\boxed{\text{Q11}} \quad I = \int \frac{-2x^3 + 7x^2 + 78x - 37}{x^2 - 3x - 40} dx$$

$$\begin{array}{r} \text{---} \\ x^2 - 3x - 40 \overline{) \begin{array}{r} -2x^3 + 7x^2 + 78x - 37 \\ -2x^3 + 6x^2 + 80x \quad \downarrow \\ \hline x^2 - 2x - 37 \\ -x^2 - 3x - 40 \\ \hline x + 3 \end{array}} \end{array}$$

Thus, $(x^2 - 3x - 40) \cdot (-2x + 1) + (x + 3) = -2x^3 + 7x^2 + 78x - 37$

$$I = \underbrace{\int (-2x + 1) dx}_{I_1} + \underbrace{\int \frac{(x+3) dx}{x^2 - 3x - 40}}_{I_2}$$

$$I_1 = -\frac{2x^2}{2} + x + C = -x^2 + x + C$$

$$I_2 = \int \frac{(x+3) dx}{x^2 - 3x - 40}$$

$$x^2 - 3x - 40 = 0$$

$$D = 9 - 4 \cdot (-40) = 169 > 0$$

$$x_1 = 8, \quad x_2 = -5$$

Thus, $\frac{(x+3)}{(x-8)(x+5)} = \frac{A}{x-8} + \frac{B}{x+5}$

$$A(x+5) + B(x-8) = x+3$$

$$\begin{cases} A + B = 1 \\ 5A - 8B = 3 \end{cases} \Rightarrow A = \frac{11}{13}, \quad B = \frac{2}{13}$$

$$I_2 = \frac{11}{13} \int \frac{dx}{x-8} + \frac{2}{13} \int \frac{dx}{x+5} =$$

$$= \frac{11}{13} \ln|x-8| + \frac{2}{13} \ln|x+5| + C.$$

$$I = -x^2 + x + \frac{11}{13} \ln|x-8| + \frac{2}{13} \ln|x+5| + C.$$

Q12 $x' = \frac{dx}{dt} = x^3 - x^2 - 6x = f(x)$

(a) Equilibria: $f(x) = 0$

$$x_1^* = 0$$

$$x_2^* = 3$$

$$x_3^* = -2$$

(b) Use The Stability Criterion for Autonomous dif. eq-ns.

$$f'(x) = 3x^2 - 2x - 6$$

$$f'(0) = -6 < 0 \Rightarrow x_1^* = 0 \text{ is stable.}$$

$$f'(3) \geq 0 \Rightarrow x_2^* \text{ is unstable}$$

$$f'(-2) \geq 0, x_3^* \text{ is unstable.}$$

(c)



Q13

$$\begin{cases} 2x - 3y + 4z = 7 \\ -5x - 12y + 3z = 2 \\ -3x - 15y + 7z = 9 \end{cases}$$

$$\left[\begin{array}{ccc|c} 2 & -3 & 4 & 7 \\ -5 & -12 & 3 & 2 \\ -3 & -15 & 7 & 9 \end{array} \right] \begin{array}{l} R1 \rightarrow R1 \\ R2 \rightarrow R2 + R1 \\ R3 \rightarrow R3 \end{array} \rightarrow \left[\begin{array}{ccc|c} 2 & -3 & 4 & 7 \\ -3 & -15 & 7 & 9 \\ -3 & -15 & 7 & 9 \end{array} \right]$$

$$\begin{array}{l} \rightarrow R1 \rightarrow \frac{R1}{2} \\ R2 \rightarrow \frac{R2}{3} \\ R3 \rightarrow R3 - R2 \end{array} \left[\begin{array}{ccc|c} 1 & -\frac{3}{2} & 2 & \frac{7}{2} \\ 1 & 5 & -\frac{7}{3} & -3 \\ 0 & 0 & 0 & 0 \end{array} \right] \begin{array}{l} \\ R2 \rightarrow R2 - R1 \\ R2 - R1 \end{array} \rightarrow \left[\begin{array}{ccc|c} 1 & -\frac{3}{2} & 2 & \frac{7}{2} \\ 0 & 5 + \frac{3}{2} & -\frac{7}{3} - 2 & -3 - \frac{7}{2} \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\left[\begin{array}{ccc|c} 1 & -\frac{3}{2} & 2 & \frac{7}{2} \\ 0 & \frac{13}{2} & -\frac{13}{3} & -\frac{13}{2} \\ 0 & 0 & 0 & 0 \end{array} \right] \xrightarrow{R2 \rightarrow \frac{R2 \cdot 2}{13}} \left[\begin{array}{ccc|c} 1 & -\frac{3}{2} & 2 & \frac{7}{2} \\ 0 & 1 & -\frac{2}{3} & -1 \\ 0 & 0 & 0 & 0 \end{array} \right] \text{ row echelon form.}$$

$$z = t, \quad t \in \mathbb{R}.$$

$$\begin{aligned} \textcircled{2} \Rightarrow y - \frac{2}{3}z &= -1 \\ y &= \frac{2}{3}z - 1 = \frac{2}{3}t - 1 \end{aligned}$$

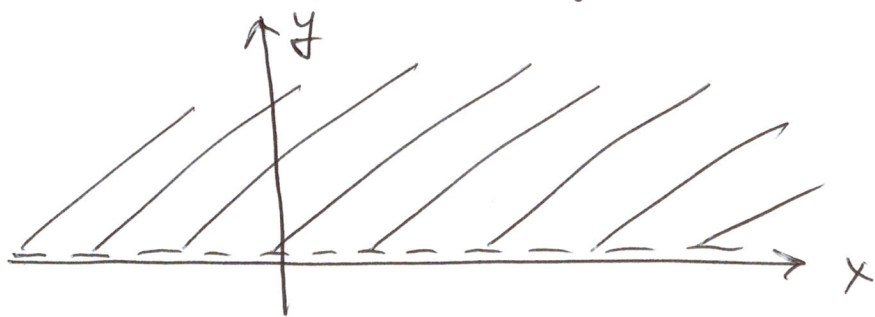
$$\begin{aligned} \textcircled{1} \Rightarrow x - \frac{3}{2}y + 2z &= \frac{7}{2} \\ x &= \frac{3}{2}y + \frac{7}{2} - 2z = \frac{3}{2}\left(\frac{2}{3}t - 1\right) - 2t + \frac{7}{2} = \\ &= 2 - t. \end{aligned}$$

$$\boxed{x = 2 - t, \quad y = \frac{2}{3}t - 1, \quad z = t}$$

Q14

(a) $z = \ln y - x$

The domain: $y > 0, x \in (-\infty, +\infty)$



Range $z \in (-\infty, +\infty)$

(c) $f(x, y) = C$

$\ln y - x = C$

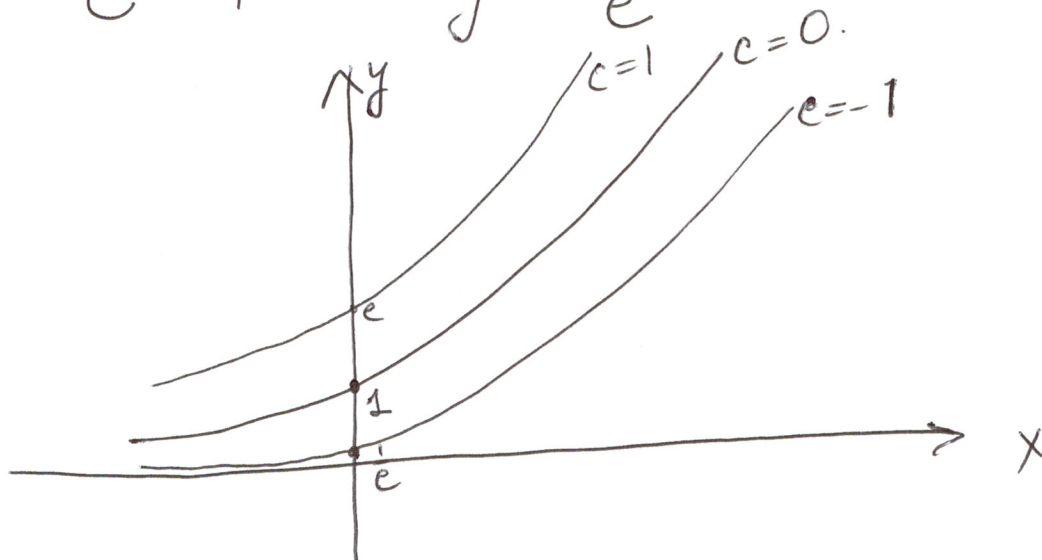
$\ln y = C + x$

$y = e^{C+x} = e^C \cdot e^x$

$C = 0, \quad y = e^x$

$C = 1, \quad y = e \cdot e^x$

$C = -1, \quad y = \frac{e^x}{e}$



$$(d) \quad L(x, y) = f(x_0, y_0) + \frac{\partial f}{\partial x} \Big|_{(x_0, y_0)} (x - x_0) + \frac{\partial f}{\partial y} \Big|_{(x_0, y_0)} (y - y_0) \quad (x_0, y_0) = (2, e)$$

$$Z_0 = f(x_0, y_0) = f(2, e) = \ln e - 2 = -1$$

$$f_x = -1 \quad f_x(x, y) = -1.$$

$$f_x(2, e) = -1.$$

$$f_y = \frac{\partial f}{\partial y} = \frac{1}{y}.$$

$$f_y(x, y) = \frac{1}{y}$$

$$f_y(2, e) = \frac{1}{e}.$$

$$L(x, y) = -1 - 1(x - 2) + \frac{1}{e}(y - e) =$$

$$= -1 - x + 2 + \frac{1}{e}y - 1 = \frac{y}{e} - x$$

$$\boxed{Q_{15}} \quad w = 3 - 4i, \quad z = -6 + 7i$$

$$\frac{|w|}{wz} = \frac{\sqrt{(3)^2 + (-4)^2}}{(3 - 4i)(-6 + 7i)} = \frac{5}{-18 + 24i + 21i - 28i^2} =$$

$$= \frac{5}{-18 + 45i + 28} = \frac{5}{10 + 45i} = \cancel{\$T} \frac{1}{2 + 9i} =$$

$$\frac{1 \cdot (2 - 9i)}{(2 + 9i)(2 - 9i)} = \frac{2 - 9i}{4 + 81} = \frac{2}{85} - \frac{9i}{85}$$

Q16

$$\frac{dx}{dt} = -3x + y$$

$$\frac{dy}{dt} = x - 3y$$

$$A = \begin{bmatrix} -3 & 1 \\ 1 & -3 \end{bmatrix}$$

$$\det(A - \lambda I) = \det \begin{bmatrix} -3-\lambda & 1 \\ 1 & -3-\lambda \end{bmatrix} =$$

$$= (-3-\lambda)(-3-\lambda) - 1 = (3+\lambda)^2 - 1 = \lambda^2 + 6\lambda + 8 = 0$$

$$\lambda_1 = -2; \lambda_2 = -4.$$

$\lambda_1 = -2$

$$A\bar{v}^1 = \lambda_1 \bar{v}^1$$

$$(A - \lambda_1 I)\bar{v}^1 = \bar{0}$$

$$\begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} v_1^1 \\ v_2^1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\left[\begin{array}{cc|c} -1 & 1 & 0 \\ 1 & -1 & 0 \end{array} \right] \rightarrow \left[\begin{array}{cc|c} -1 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

$$v_2^1 = t$$

$$v_1^1 = t, \quad t \in \mathbb{R}, t \neq 0.$$

$$\bar{v}^1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} t.$$

$$\boxed{\lambda_2 = -4} \quad \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} v_1^2 \\ v_2^2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\left[\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right] \quad \vec{v}^2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix} t, \quad t \in \mathbb{R}.$$

The general solution has the following form


$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 e^{-2t} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 e^{-4t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

The Equilibrium.

$$\frac{dx}{dt} = 0 \quad (x^*, y^*) = (0, 0)$$

$$\frac{dy}{dt} = 0.$$

The system is linear, thus the only equilibrium we have is the origin (see lecture notes)

Both eigenvalues are negative, the equilibrium is a stable node .

the x -nullcline.

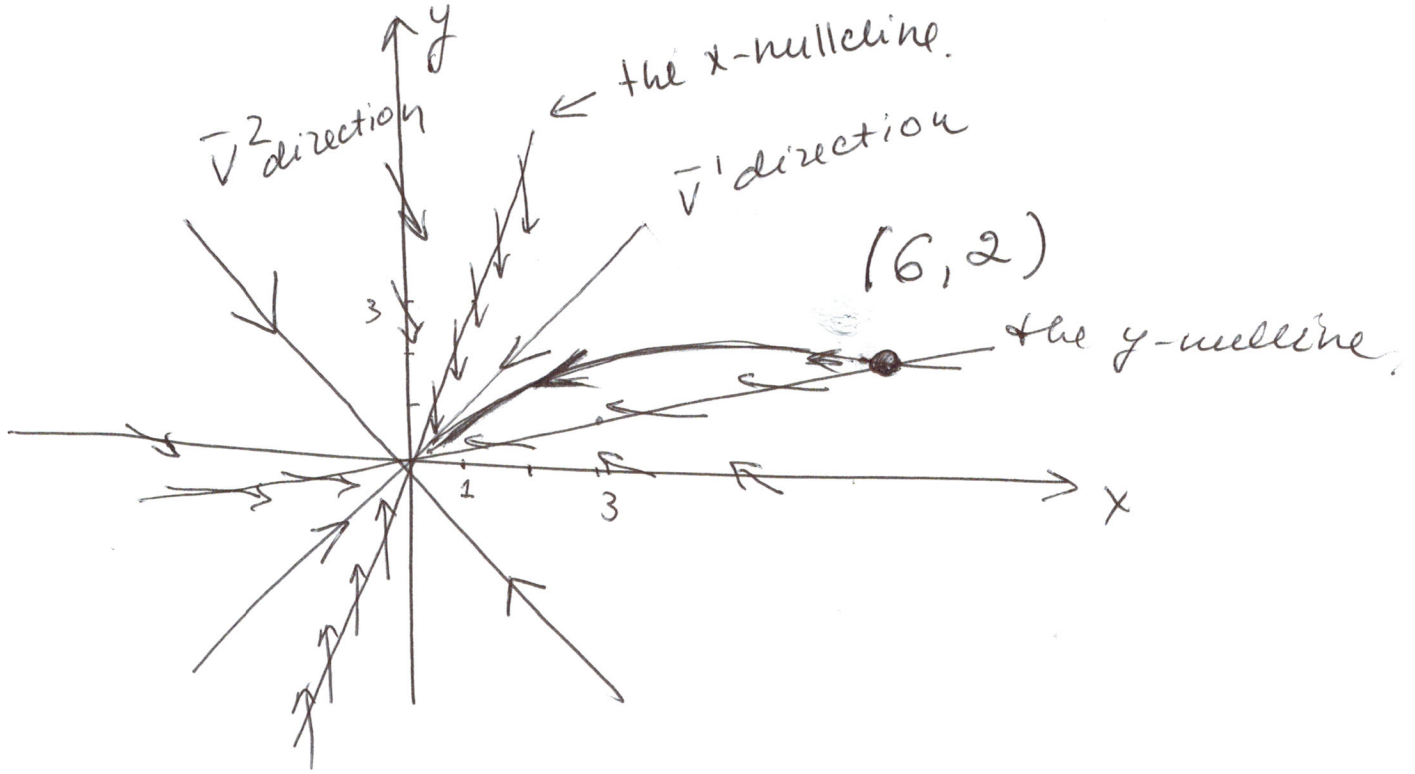
$$-3x + y = 0$$

$$\boxed{y = 3x}$$

the y -nullcline

$$x - 3y = 0$$

$$\boxed{y = \frac{x}{3}}$$



the x-nullcline

$$y = 3x$$

$$\frac{dy}{dt} = x - 3y = x - 9x = -8x.$$

$$\frac{dy}{dt} < 0 \quad x > 0 \quad y \downarrow.$$

$$x < 0 \quad y \uparrow.$$

Q17

$$\frac{dx}{dt} = 12 - 3xy - 3x$$

$$\frac{dy}{dt} = 3xy - 6y$$

(a) Equilibria $\frac{dx}{dt} = 0$ and $\frac{dy}{dt} = 0$.

$$\begin{cases} 12 - 3xy - 3x = 0 & \Leftrightarrow 4 - xy - x = 0 \\ 3xy - 6y = 0 & \Leftrightarrow y(x - 2) = 0 \end{cases}$$

$$y = 0. \quad x = 4.$$

$$x = 2. \quad \begin{aligned} 4 - 2y - 2 &= 0 \\ y &= 1. \end{aligned}$$

$$\begin{aligned} (x_1^*, y_1^*) &= (4, 0) \\ (x_2^*, y_2^*) &= (2, 1) \end{aligned}$$

(b) $J(x, y) = \begin{bmatrix} f_x & f_y \\ g_x & g_y \end{bmatrix} = \begin{bmatrix} -3y - 3 & -3x \\ 3y & 3x - 6 \end{bmatrix}$

(c) $J(4, 0) = \begin{bmatrix} -3 & -12 \\ 0 & 6 \end{bmatrix} \quad \lambda_1 = -3 \quad ; \quad \lambda_2 = 6.$
 $\bar{v}_1 = \begin{bmatrix} 4 \\ 3 \\ 1 \end{bmatrix} \quad \bar{v}_2 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

$(x_1^*, y_1^*) = (4, 0)$ is a saddle point (unstable).

$$J(2, 1) = \begin{bmatrix} -6 & -6 \\ 3 & 0 \end{bmatrix} = B$$

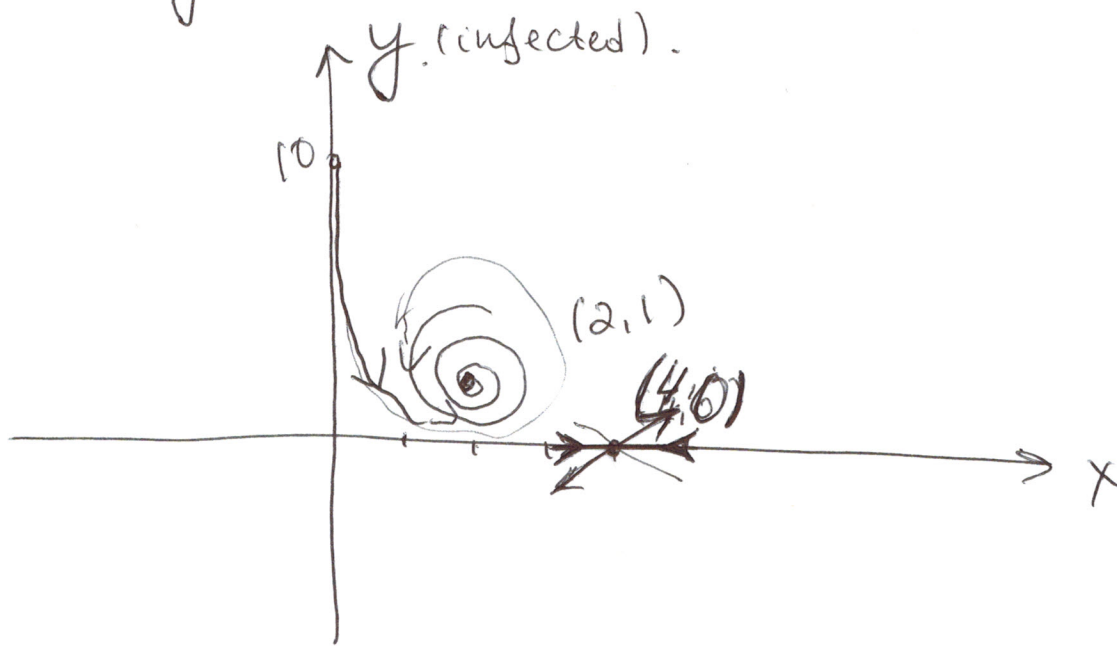
$$\det(B - \lambda I) = (-6 - \lambda)(-\lambda) + 18 = \lambda^2 + 6\lambda + 18 = 0$$

$$\lambda_1 = -3 + 3i$$

$$\lambda_2 = -3 - 3i$$

$$\operatorname{Re}(\lambda_1, \lambda_2) = -3 < 0 \Rightarrow$$

(x_2^*, y_2^*) is a stable spiral.



(f) if 10 people are initially infected, then in the long term the population will stabilize at $(2, 1)$.

We will have 1 infected and 2 susceptible individuals.